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APOLLO SYSTEMS RELIABILITY

STATUS REPORT (U)

VOLUME II

SUBSYSTEMS RELIABILITY STATUS

(NASA-TM-X-62865) APOLLO SYSTEMS
RELIABILITY STATUS REPORT. VOLUME 2:
SUBSYSTEMS RELIABILITY STATUS (NASA) 204 p

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23 SEPTEMBER 1963

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

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APOLLO SYSTEMS RELIABILITY

STATUS REPORT (U)

VOLUME II

SUBSYSTEMS RELIABILITY STATUS

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SECTION 12
INTRODUCTION

BACKGROUND

The reliability of the Apollo system is of paramount importance in attaining the mission assigned. To provide the most useful engineering management tool possible, the factors pertinent to reliability must be evaluated and interpreted to provide direct aid to the organizations responsible for the system. This volume is to become a unified engineering management compilation, combining the available data from NASA and contractor sources. Future editions will expand and complete the presentation of the reliability status as it is possible.

The variation in systems definitions, mission definitions, and program planning will require continued effort to assemble and present a coherent system report. Currently available system and mission definitions and data disagree in significant areas. It is the function of this report to make such a combination and to extract the significant trends and problems for individual attention. The present report is seriously limited in the completeness of the available information. However, established reliability problems are defined, and their significance is interpreted.

Formal center submittals do not now exist, and the material presented here is derived largely from contractor reports. Ultimate reliability apportionments will come from NASA sources, but the ones included are largely those of the contractors. Adequate information from centers and contractors will make possible a system documentation that will be directly useful in all Apollo areas. Major information sources to date have been the Apollo System Description, now seriously out of date, and NAA Quarterly Reliability Reports 62-557.

STANDARD DATA CODE

Table 12-1 illustrates the data code. The first 17 digits are the key to equipment identification; the remaining digits have other uses and are not specifically required for equipment identity.

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MISSION SYSTEM 1st and 2nd Digits	SUBSYSTEMS 3rd and 4th Digits	FUNCTIONAL SYSTEMS 5th and 6th Digits		FUNCTIONAL SUBSYSTEMS 7th, 8th, and 9th Digits		COMPONENTS 10th, 11th, and 12th Digits	
		-----01	02	01	001	Engine	462
01 Apollo/Saturn I 02 Apollo/Saturn IB 03 Apollo/Saturn V 04 Apollo/Saturn - 05 Mercury 06 Gemini 07 Polaris	01 Propulsion 02 Electrical Power 03 Structures 04 Environment Control 05 Guidance 06 Communications 07 Crew System	01 Propulsion 02 Electrical Power 03 Structures 04 Environment Control 05 Guidance 06 Communications 07 Crew System	01 Propulsion 02 Electrical Power 03 Structures 04 Environment Control 05 Guidance 06 Communications 07 Crew System	011 Engine Systems	002 Fuel Feed	UHF System	463
				021 Vector Control	003 Oxidizer Feed	Intercommunications	464
				031 Engine Control System	004 Solid Propellant	S-Band System	465
				041 Pneumatic Control System	005 Fuel Tank	Scientific Instrumentation	466
				051 Ignition	006 Oxidizer Tank	DSIF System	467
				061 Ordnance	007 Fuel Transfer Ground	HF System	468
				071 Propellant Utilization (Oxygen only)	008 Fuel Transfer Flight Components	FM System	469
				081 Reaction Control	009 Oxidizer Transfer Ground	Remote Automatic Calibration	470
				091 D-C Power Source	010 Oxidizer Transfer Flight Components	Emergency Measurement Detection	471
				101 A-C Power Source	011 Fuel Pressurization Ground	DDAS	472
				111 Power Sources (Exc. AC/DC)	012 Oxidizer Pressurization Flight Components	Gyroscopes	473
				121 Distribution Systems	013 Oxidizer Pressurization Flight Components	Amplifier Demodulators	474
				131 Cabling	014 Oxidizer Pressurization Flight Components	Accelerometers	475
				141 Interstaging	015 Fuel Transfer (Ground and Flight Half)	Gyro-Stabilized Platform	476
				151 Lighting	016 Oxidizer Transfer (Ground and Flight Half)	Digital Guidance Computer	477
				201 Primary Structures	017 Fuel Pressurization (Ground and Flight Half)	Guidance Signal Processor	478
09 All Pertinent Functional Systems	09 All Pertinent Functional Systems	09 All Pertinent Functional Systems	09 All Pertinent Functional Systems	211 Basic Structures	018 Oxidizer Pressurization (Ground and Flight Half)	Azimuth Alignment Package	479
				301 Equipment Environment Control	019 Fuel Discharge	Analog Control Computer	480
				311 O ₂ Supply	020 Hydraulic Control	Command Receiver-Decoder	481
				321 Water System	021 Servo Control System and Feedback, Hydraulic	GN ₂ Bearing Supply	482
				326 Pressure Suit	022 Servo Loop	Flight Sequencer	483
				331 Back Pack	023 Missile Preflight Pressure System	Inertial Measurement Unit	484
				336 Radiator (Crew)	024 Engine Purge Components (Flight and Ground)	Optical Measurement Unit	485
				341 Thermal Control System	025 Overspeed Trip	Range Drift Measurement Unit	486
				346 Crew Mobility Systems	026 Engine Shutdown	Guidance Computer	487
				351 Survival Equipment	027 Engine Fuel Purge	Power and Servo Assembly	488
				356 Recovery Aids	028 Engine Oxidizer Purge	Rendezvous Radar	489
				401 Rate Gyro Package	029 Fuel Vent Valve Control	Radar Altimeter	490
				406 Control Accelerometer Package	030 Oxidizer Vent Valve Control	Attitude Reference	491
				411 Guidance and Control	031 Fuel Conditioning	Rate Sensors	492
				451 Navigation and Guidance	032 Oxidizer Conditioning	Control Electronics Assembly	493
				456 Stabilization and Control	033 Fuel Pressurization, Flight	Manual Controls	494
09 All Pertinent Subsystems	09 All Pertinent Subsystems	09 All Pertinent Subsystems	09 All Pertinent Subsystems	501 Power and Servo Assembly	034 Oxidizer Pressurization, Flight	Displays and Controls	495
				511 Command Communications	035 Gas Generator Ignitors	Power Supplies (Stabilization)	496
				521 Tracking	036 Thrust Chamber Ignitors	Coupling Display Unit	497
				521 Audio/Visual	037 Hypergol Start	Scanning Telescope	498
				531 Telemetry	038 Electrical Start	Sextant	499
				541 Instrumentation	039 Primacord	Inertial Reference Package	500
				601 Pilot	040 Initiators	Three-axis Rate Gyro Package	501
				606 Navigator	041 Explosive Bolts or Nuts	Electronic Computer Assembly	502
				611 Engineer	042 Retro Rockets	Electrical Power Converter	503
				621 Personal Protection and Support	043 Jetison Motor	Horizon Scanner	504
				631 Waste Management	044 Kicker Motor System	Longitudinal Accelerometer	505
				641 Food and Water	045 Manual Cable Cutter	Lights - Running and Flashing	506
				651 Personal Hygiene, Health and Comfort	046 Variable Flow Valve	LN ₂ Cooler	507
				701 C/O Equipment S-I, S-IC, N-1	047 Solenoid Controlled Valve	Recompression O ₂ Supply	508
				706 C/O Equipment S-II, N-2	048 Servo Control System and Feedback (Elect.)	Pressure Control, Atmospheric	509
				711 C/O Equipment S-3	049 Batteries	Temperature Control, Atmospheric	510
09 All Pertinent Functional Subsystems	09 All Pertinent Functional Subsystems	09 All Pertinent Functional Subsystems	09 All Pertinent Functional Subsystems	716 C/O Equipment S-IV, S-IVB	050 Inverters	O ₂ System	511
				721 Propellant Transfer and Storage	051 Voltage Measuring (Regulated) Supply	Cabin Pressure Regulation	512
				726 Pressurization and Storage	052 Fuel Cells	Superpressure Regulation	513
				731 Transporter and Launchers	053 D-C Distribution	Gaseous Composition Control System	514
				736 Ordnance Tower	054 A-C Distribution	Radiator	515
				739 Umbilical Drop System	055 Connectors	Water-glycol Heat Transport Fluid Circuit	516
				741 Telemetry C/O Equipment	056 Wire	Cabin Thermal Control System	517
				746 Command C/O Equipment	057 Umbilicals	Suit Thermal Control System	518
				751 Instrumentation C/O Equipment	058 Shape Charge	Equipment Thermal Control System	519
				756 Tracking and Audio/Visual C/O Equipment	059 Destruct Command Equipment	Supplemental and Emergency Water Evaporative	520
				761 S/M C/O Equipment	060 UDOP System	Portable Water Supply System	521
				766 Guidance Console	061 Television	Cooling Water Supply System	522
				771 Mission Control	062 SS/FM System	Pressure Suit	523
				776 Computer Control	063 PAM/FM/FM System	Airlock	524
				781 C/M C/O Equipment (Environment)	064 PDM/FM/FM System	ODOB	525
				786 LEM C/O Equipment (Environment)	065 FM/FM System	Radiation Protection	526
				791 Near Earth Net	066 PCM/FM/FM System	Seating and Restraint	527
				796 Deep Space Net	067 MISTRAM System	Decompression Protection	528
09 All Pertinent Functional Subsystems	09 All Pertinent Functional Subsystems	09 All Pertinent Functional Subsystems	09 All Pertinent Functional Subsystems	999 All Pertinent Functional Subsystems	068 Azusa System	Urine Collection and Storage	529
					069 C-Band Radar	Feces Collection and Storage	530
					070 VHF System	Personal Hygiene	531
						Health	532
							533
							534
							535
							536
							537
							538
							539
							540
							541
							542
							543
							544

TYPICAL CODE EXAMPLE

DIGIT	CODE	EQUIPMENT
1, 2	03	APOLLO/SATURN V
3, 4	06	Lunar Excursion Module
5, 6	06	Communications
7, 8, 9	521	Audio/Visual
10, 11, 12	462	UHF System
13, 14, 15	052	Antenna
16, 17	23	NASA Operating Experience Record

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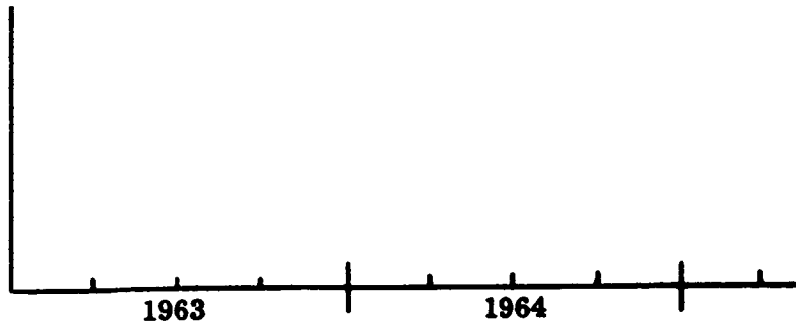
SECTION 13

S-IC STAGE

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S-IC Stage Description

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Propulsion	01				1.6	1
Electrical Power	02				0.3	1
Structures	03				-	
Communications	06				-	

Notes:

1. Engineering estimate for illustration.
- 2.
- 3.
- 4.

SECTION 13

S-IC STAGE
(CODE: 03 13)

DESCRIPTION

The S-IC stage (see Figures 13-1 and 13-2) develops 7,500,000 pounds of thrust supplied by five Rocketdyne engines with a thrust-to-vehicle weight ratio of 1.25. Four engines are gimballed to provide a roll, pitch, and yaw control during powered flight. The maximum gimbal angle is ± 6 degrees, including one degree for snubbing. The center engine is fixed and has no gimbal control.

The S-IC stage initially lifts the vehicle from the pad and raises it to an altitude of approximately 200,000 feet. The S-IC powered flight is approximately 150 seconds.

The S-IC stage will have four fins with an approximate area of 75 square feet. The fins will be attached opposite the outboard engines. Support and holddown for launch will be provided at four points (45 degrees between outboard engines).

CONTRACTORS

Prime Contractor - Boeing
Engine Supplier - Rocketdyne
Airframe supplier - Boeing
Communications Supplier - Collins Radio

MAJOR CONTRIBUTOR TO UNRELIABILITY

The F-1 engine is at present the major functional system contributing to stage unreliability due to engine rough combustion. A "fix" has been to baffle the injector. At present the staked copper sheet type baffle is not proving effective.

RELIABILITY TRENDS

When data is available the reliability curves on the opposite page will be discussed here.

S-IC Stage Description

RELIABILITY DOCUMENTATION

Subsystem: S-IC Module (Code 03 13)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

S-IC Stage Description

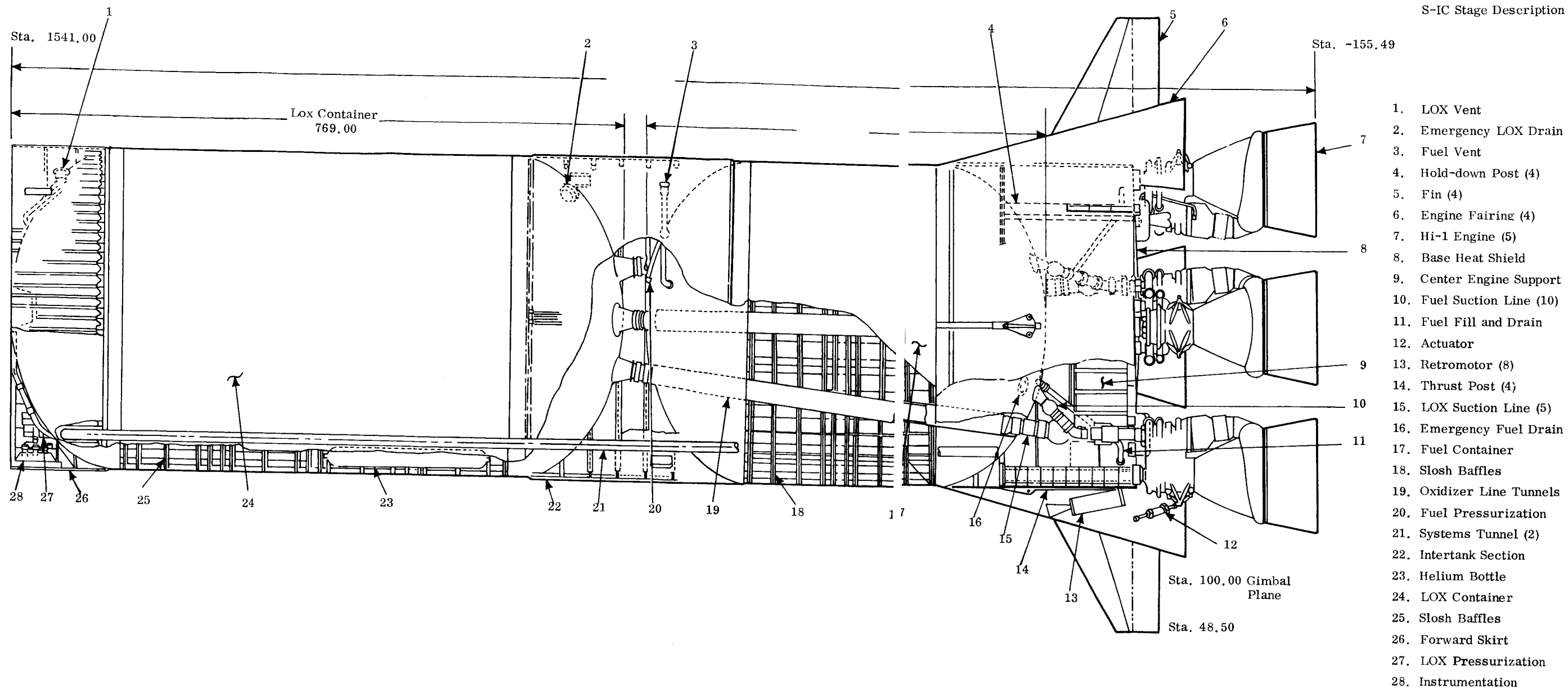


Figure 13-1. S-IC Inboard Profile

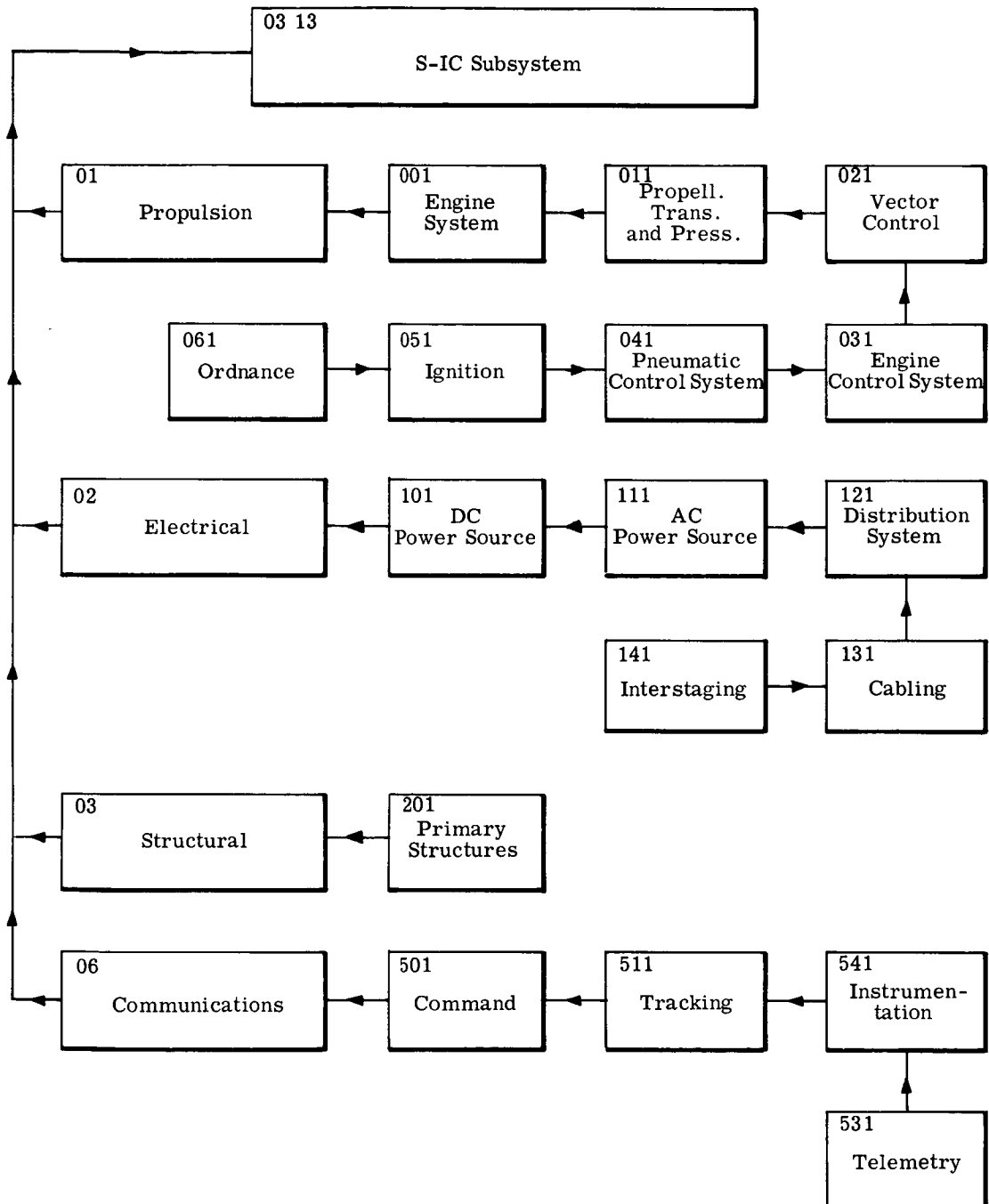


Figure 13-2. S-IC Subsystem Functional Block Diagram

S-IC Propulsion System

RELIABILITY: **Allocated** o **Predicted** o **Achieved** x



RELIABILITY

Functional Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Engine Sys-tem	001						
Propellant Transfer and Press.	011						
Vector Control	021						
Engine Control	031						
Pneumatic Control	041						
Ignition	051						
Ordnance	061						

Notes:

- 1.
- 2.
- 3.
- 4.

S-IC PROPULSION SYSTEM (CODE: 03 13 01) DESCRIPTION

FUNCTION

The propulsion system (see Figures 13-3 through 13-5) is activated after from 1.3 to 1.8 seconds by starting the F-1 gas generator. Ignition of the F-1 engine is accomplished in 0.5 second after gas generator ignition is detected. Transition from engine ignition to mainstage (90 percent thrust) occurs in 1.8 seconds.

Total obtainable thrust is 1,500,000 pounds. The weight mixture ratio is 2.25 ± 2 percent.

The total propellant flow rate is 5700 gallons per second.

Fuel NPSH is 5500.	Pump inlet pressure is 45 psia.
LOX NPSH is 3381.	Pump inlet pressure is 65 psia.
Fuel tank pressure.	Preflight pressure is 28.5 psia.
LOX tank pressure.	Preflight pressure is $35.5 + 0.5$ psia. -1.10 psia.

CONTRACTOR

Prime Contractor - Boeing

F-1 Engines - Rocketdyne

MAJOR CONTRIBUTOR TO UNRELIABILITY

The baffle on the injector of the engine is causing the greatest unreliability. Rocketdyne is employing a staked copper sheet baffle which is proving unreliable. It is expected they will use a stainless steel type baffle with film cooling or internal passages. This type of baffle is more reliable, but experience has shown that a great deal of erosion occurs at the tip of this type of baffle.

RELIABILITY TRENDS

When data is available, the reliability curves on the opposite page will be discussed.

S-IC Propulsion System

RELIABILITY DOCUMENTATION

Functional Subsystem: S-IC Propulsion (03 13 01)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

1. Available information is from industry, contractors, and preliminary specifications. Center submittals have not been received.

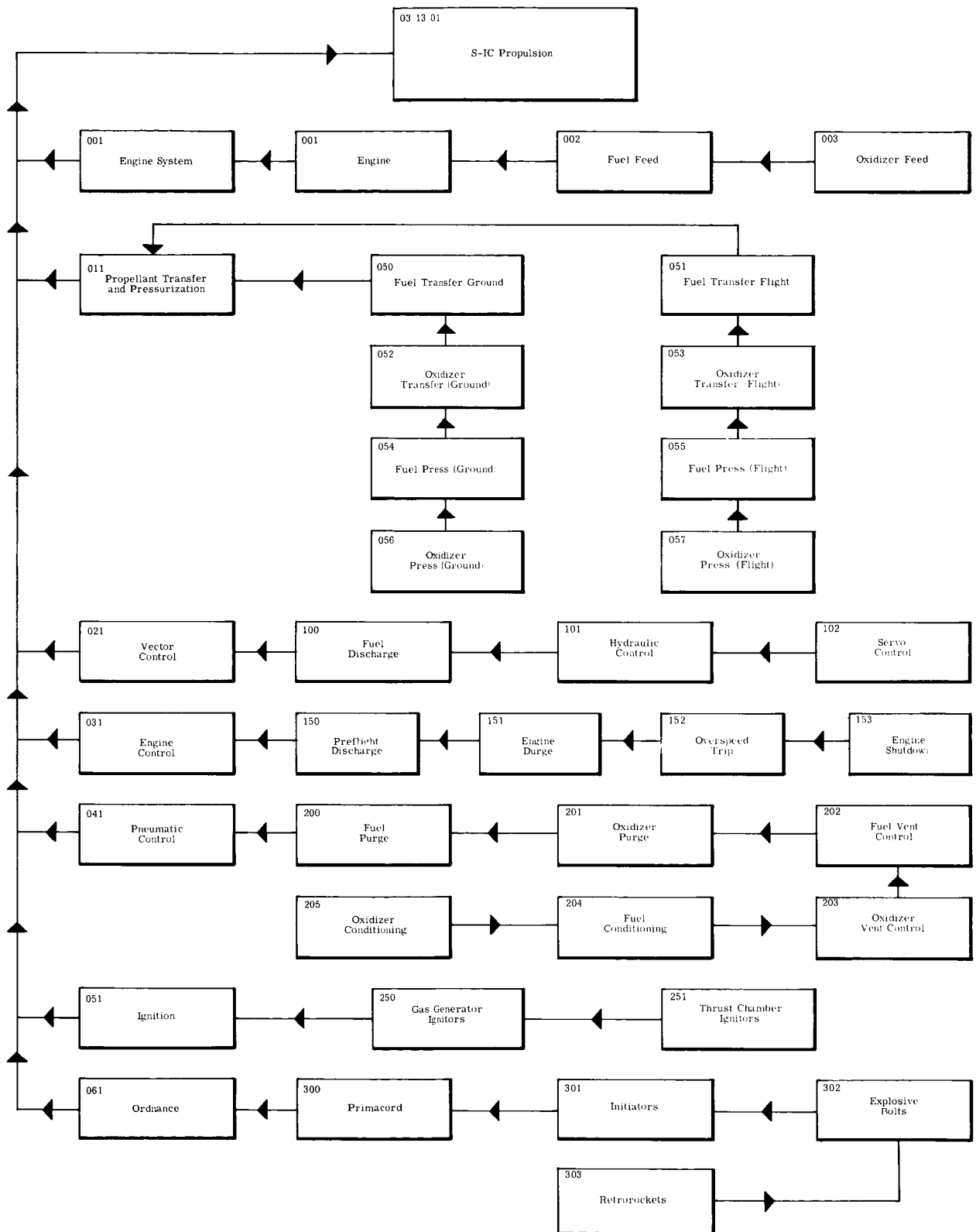


Figure 13-3. S-IC Propulsion System Functional Flow Diagram

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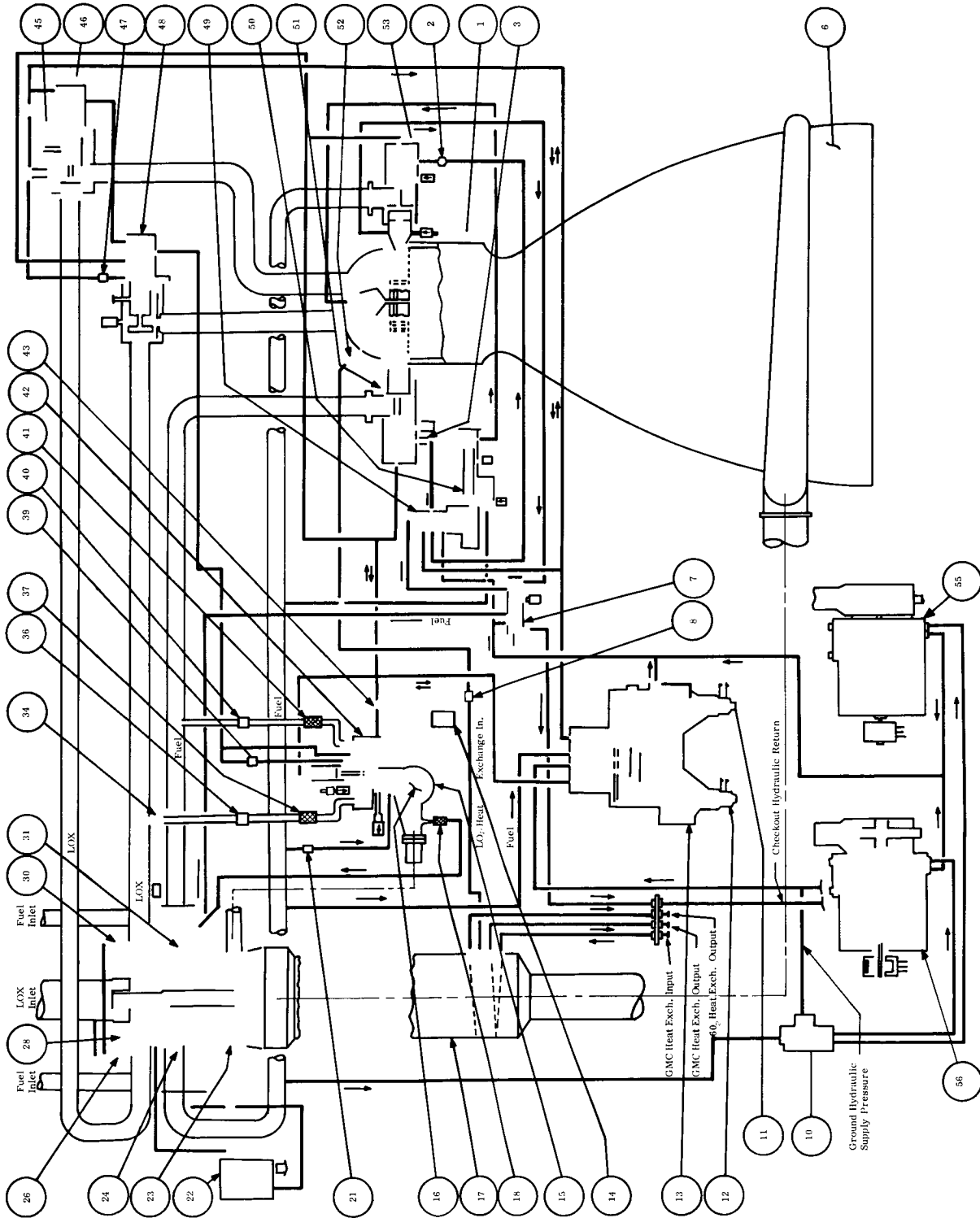
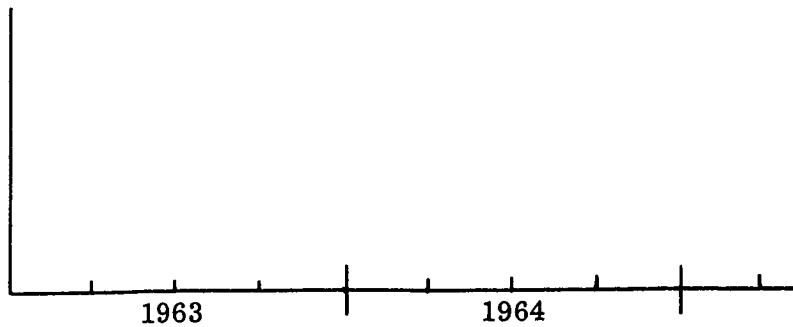


Figure 13-5. F-1 Engine System Outboard Schematic

S-IC Electrical Power System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
DC Power	101						
AC Power	111						
Distribution Systems	121						
Cabling	131						
Interstaging	141						

Notes:

- 1.
- 2.
- 3.
- 4.

S-IC STAGE ELECTRICAL POWER SYSTEM DESCRIPTION (CODE: 03 13 02)

FUNCTION

These power systems are reasonably simple ones in which direct and alternating current needs are supplied by batteries and inverters as appropriate. Certain of the components are items of more or less standard use in the industry. The systems themselves, however, are not well defined in the information presently available, and their analysis has proceeded on the basis of synthesized systems which are assumed to be the most probable configurations. Since relatively subtle changes in the configuration and components used in such a system can have major effects on the reliability achieved, the values thus far derived are of low confidence.

The launch vehicle operations are of relatively short duration; the noise, vibration and possibly moisture environment are extreme and the line transients resulting from certain equipment operations are of considerable magnitude. These situations have an effect upon the reliability of the equipment in use. Accurate evaluation of these factors as applied to the specified Apollo hardware is not presently possible.

CONTRACTORS

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

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RELIABILITY DOCUMENTATION

Functional Subsystem: S-IC Electrical Power (03 13 02)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis	Not Applicable	Not Applicable
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

S-IC Communications

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Command	501						
Tracking	511						
Telemetry	531						
Instrumen- tation	541						

Notes:

- 1.
- 2.
- 3.
- 4.

S-IC COMMUNICATIONS (CODE 03 13 06)

FUNCTION

S-IC communications (see Figure 13-6) is equipped with measuring, signal conditioning, and telemetry systems for realtime transmission of the operating parameters of the vehicle. An emergency detection system is provided to allow a safe abort of the crew. A command destruct system is also provided in the event of mission abort.

CONTRACTORS

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

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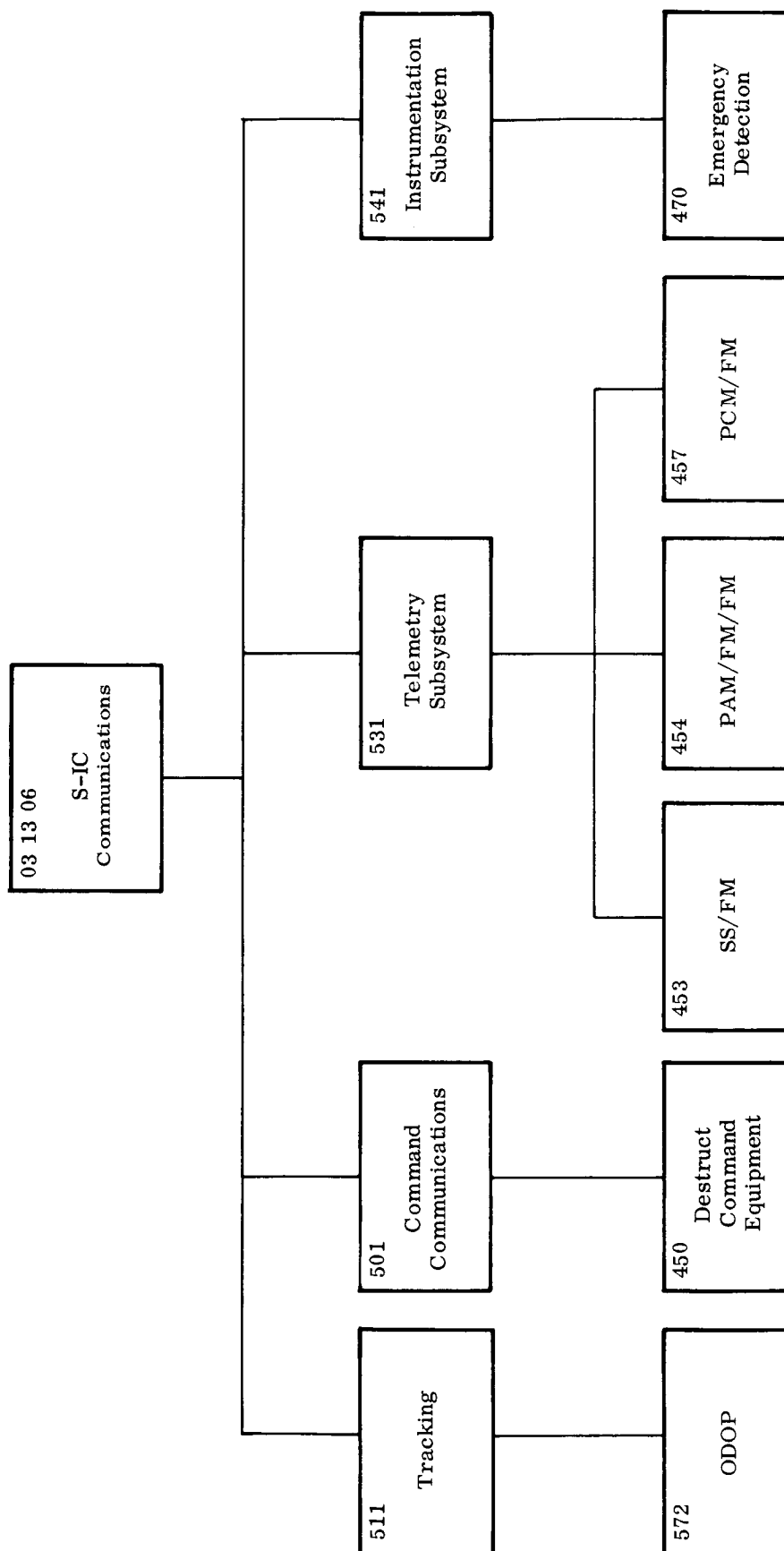


Figure 13-6. S-IC Communications Block Diagram

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RELIABILITY DOCUMENTATION

Functional Subsystem: S-IC Communications (03 13 06)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis	Not Applicable	Not Applicable
7. Maintainability Plan - Flight	Not Applicable	Not Applicable
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

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SECTION 14

S-II STAGE

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S-II Stage Description

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			% of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Propulsion	01				0.4	1
Electrical Power	02				0.3	1
Structures	03				---	
Communications	06				----	

Notes:

1. Engineering estimate for illustration.
- 2.
- 3.
- 4.

SECTION 14

S-II STAGE
(CODE: 03 02)

DESCRIPTION

The S-II stage (see Figures 14-1 and 14-2) is the second stage of the Saturn C-5 launch vehicle and is designed for general earth escape and earth orbit payload applications. Mainstage propulsion is provided by five Rocketdyne J-2 engines.

The basic structure is conventional semimonocoque design with common insulated bulkhead separating the LOX container from the liquid hydrogen container, which is forward. The aft interstage structure will transmit launch loads from the S-IC stage to the aft skirt structure, the aft skirt structure will transmit thrust loads to the S-II stage body, and the forward skirt structure will transmit launch loads from the S-II stage body to the stage above. The conical thrust structure will uniformly transmit loads from the engine mount frame to the aft skirt structure.

Slosh baffles will be provided in each propellant container to control sloshing motion of propellants during flight by transferring absorbed slosh forces uniformly to the container structure.

CONTRACTORS

Prime - MSFC/North American Aviation

Engines - Rocketdyne

MAJOR CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS

S-II data is generally inadequate for an appraisal report.

S-II Stage Description

RELIABILITY DOCUMENTATION

Subsystem: S-II Module (03 02)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

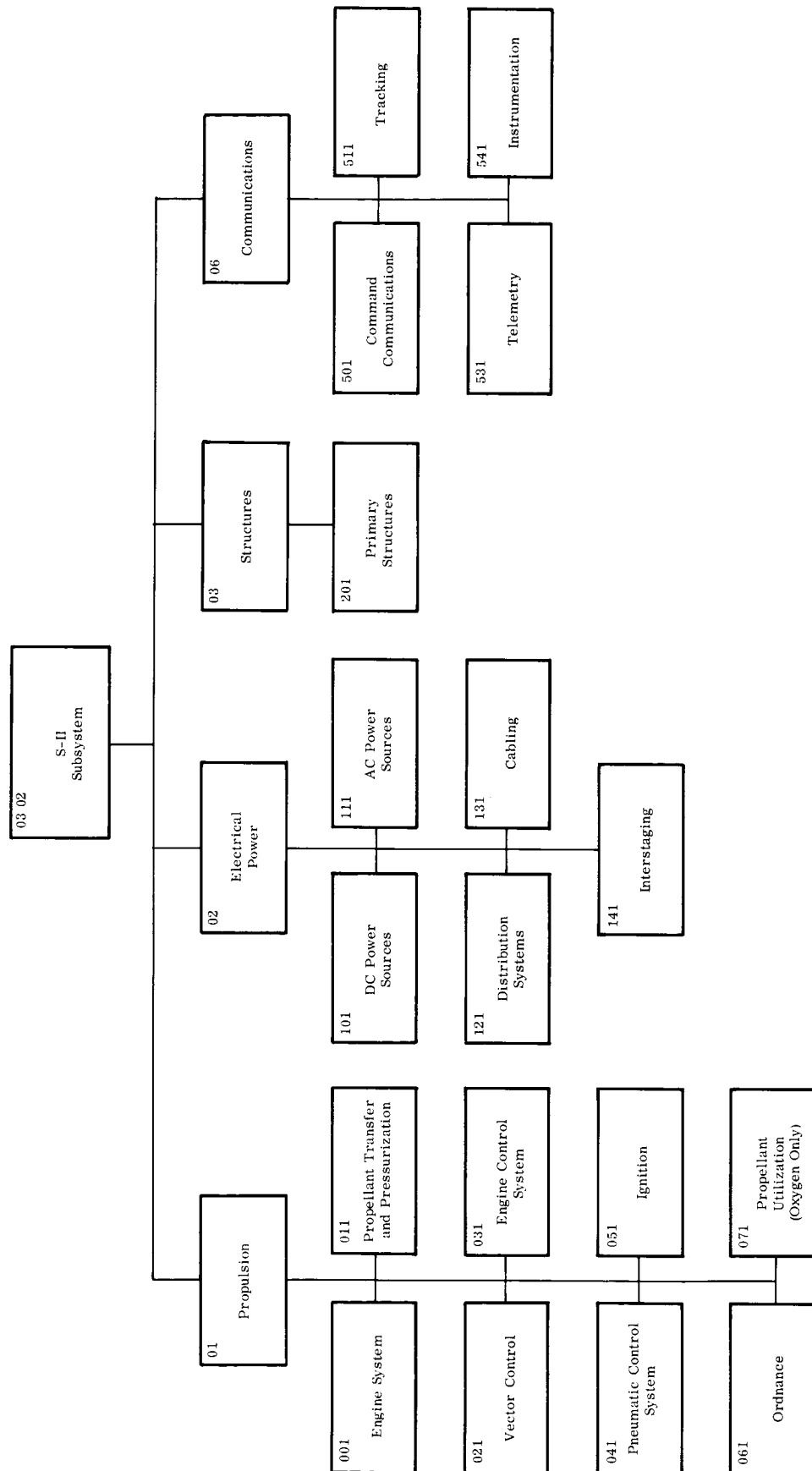


Figure 14-1. Subsystem Block Diagram

S-II Stage Description

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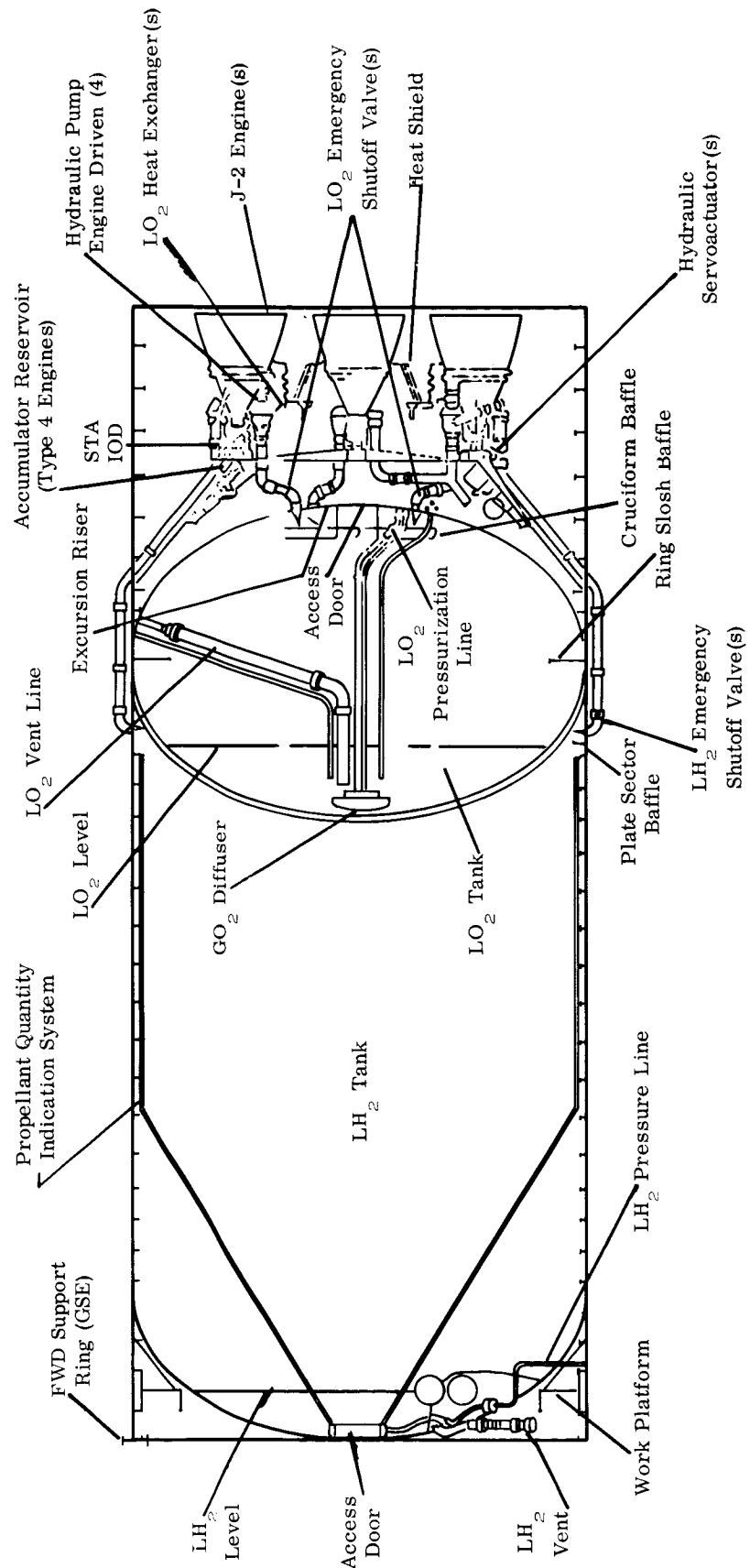
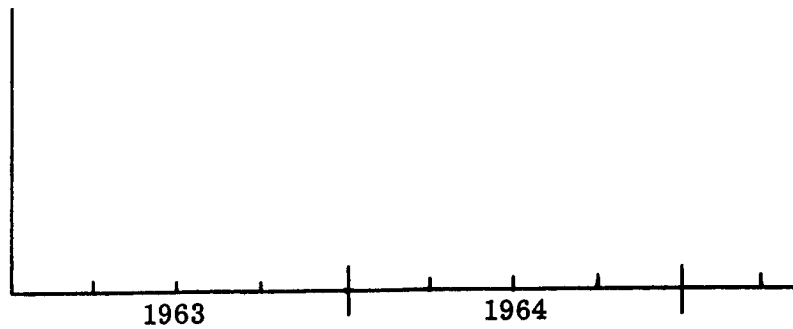


Figure 14-2. S-II Stage

S-II Propulsion System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Engine Sys.	001						
Prop. Trans. and Press.	011						
Vector Cont.	021						
Eng. Cont. Sys.	031						
Pneu. Cont. Sys.	041						
Ignition	051						
Ordnance	061						
Prop. Util.	071						

Notes:

- 1.
- 2.
- 3.
- 4.

S-II STAGE PROPULSION (CODE: 03 02 01)

FUNCTION

The propulsion functional system (see Figure 14-3 and 14-4) is the major portion of the S-II stage. Payload capabilities and nominal trajectories are based on nominal J-2 engine parameters.

The engine system will consist of a cluster of five Rocketdyne J-2 liquid propellant rocket engines. Each engine will be a self-contained operational unit automatically performing individual sequence functions following receipt of a minimum number of input signals from the vehicle programmer.

Pitch, yaw, and roll control is provided by gimbaling the four outboard engines through a movement in a 7-degree square pattern with one-half degree additional for overtravel and snubbing. Each control engine is moved by two hydraulic servo-actuators.

The propellant system provides for purging the propellant tanks, loading of liquid oxygen and liquid hydrogen propellants, draining of propellant tanks, suppression of propellant sloshing motion, and prevention of vortex generation. The propellant pressurization system will provide pressurization of ullage space in the propellant tanks to effect flow to the J-2 rocket engines.

Performance parameters of the J-2 engine are shown in Table 14-1.

MAJOR CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS

CONTRACTORS

Prime -

Engines - Rocketdyne

S-II Propulsion System

RELIABILITY DOCUMENTATION

Functional Subsystem: S-II Propulsion (03 02 01)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

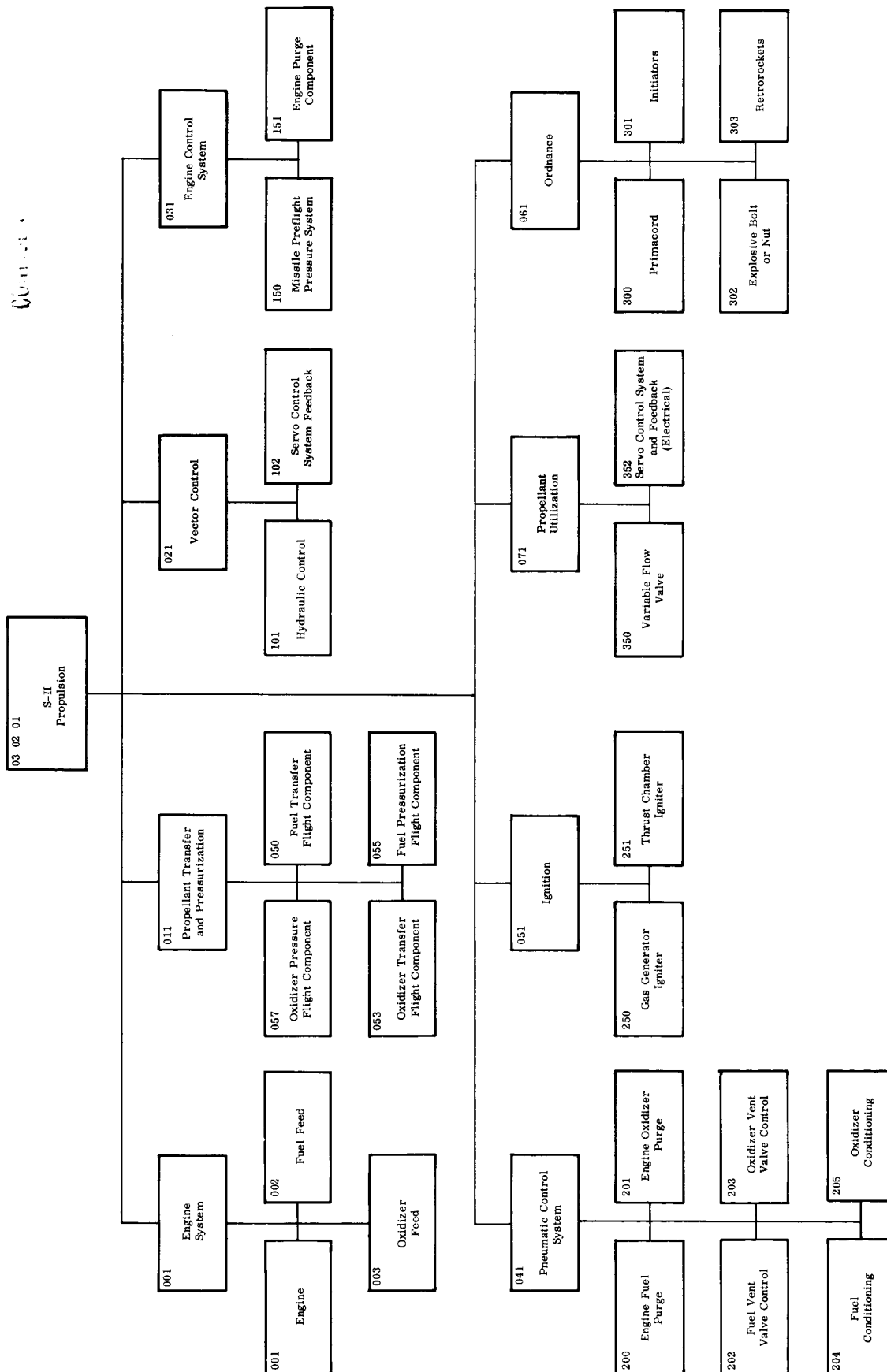


Figure 14-3. S-II Propulsion System Block Diagram

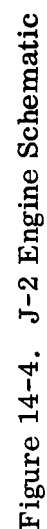


Table 14-1
Performance Parameters and Mechanical Characteristics, J-2 Engine

Item	Characteristic
Oxidizer	Liquid oxygen
Fuel	Liquid hydrogen
Thrust (altitude)	200,000 pounds
Specific impulse	426 seconds
Mixture ratio O/F	5.00
Rated Duration	250 seconds
Oxidizer flow rate	291.30 pounds/seconds
Fuel flow rate	78.26 pounds/seconds
Chamber pressure, PSIA	682.5
Expansion ratio	27.5:1
Diameter	80 inches
Length	116 inches
Weight, dry	3028 pounds
Weight, wet	3188 pounds

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S-II Stage Electrical Power System

S-II STAGE ELECTRICAL POWER SYSTEM (CODE: 03 02 02)

The launch vehicle power systems are reasonably simple ones in which direct and alternating current needs are supplied by batteries and inverters as appropriate. Certain of the components are items of more or less standard use in the industry. The systems, themselves, however, are not well defined in the information presently available, and their analysis has proceeded on the basis of synthesized systems which are assumed to be most probable configurations. Since relatively subtle changes in the configuration and components used in such a system can have major effect on the reliability achieved, the values thus far derived are of low confidence.

The noise, vibration, and possibly moisture environments are extreme and the line transients resulting from certain equipment operations are of considerable magnitude. These situations affect the reliability of the equipment in use. Accurate evaluation of these factors as applied to the specified Apollo hardware is not presently possible.

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S-II Electrical Power Systems

RELIABILITY DOCUMENTATION

Functional Subsystem: S-II Electrical Power (03 02 02)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis	N/A	N/A
7. Maintainability Plan - Flight	N/A	N/A
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		

Notes:

- 1.
- 2.
- 3.
- 4.

S-II STRUCTURES (CODE: 03 02 03)

FUNCTION

MAJOR CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS

CONTRACTORS

Information adequate for analysis not available 15 September 1963.

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S-II Communications

RELIABILITY: Allocated ● Predicted ○ Achieved x

RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Command	501						
Telemetry	531						
Instrumen- tation	541						

Notes:

- 1.
- 2.
- 3.
- 4.

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S-II COMMUNICATIONS (CODE: 03 02 06)

FUNCTION

SIC communications (see Figure 14-5) is equipped with measuring, signal conditioning, and telemetry systems for real-time transmission of the operating parameters of the vehicle. An emergency detection system is provided to allow a safe abort of the crew. A command destruct system is also provided in the event of mission abort.

CONTRACTORS

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

NOTE -Information used in analysis based upon synthesized systems.

S-II Communications

RELIABILITY DOCUMENTATION

Functional Subsystem: S-II Communications (03 02 06)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

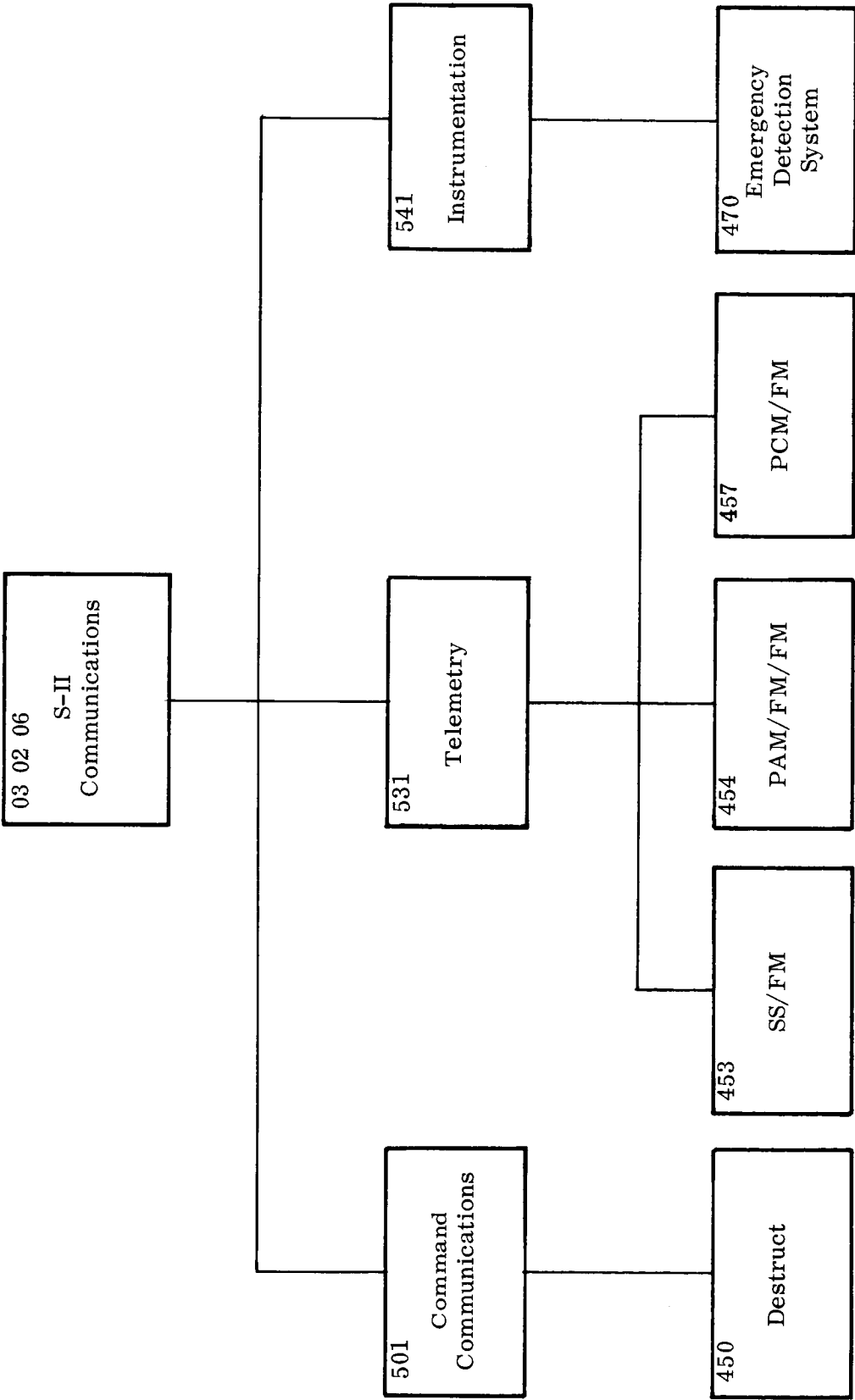


Figure 14-5. S-II Communications Subsystem Block Diagram

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SECTION 15
S-IVB STAGE

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S-IVB Stage Description

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Propulsion	01				7.8	1
Electrical Power	02				0.4	1
Structures	03				-	
Communications	06				-	
React. Control					3.8	1

Notes:

1. Engineering estimate for illustration.
- 2.
- 3.
- 4.

SECTION 15

S-IVB STAGE
(CODE: 03 16)

DESCRIPTION

The over-all S-IVB Stage will be such that it may be applied to early Saturn IB missions or later Saturn V orbital operations, without the necessity of major redesign which may require extensive testing. The S-IVB will be used as the third stage of the advanced Saturn configurations. In the manned lunar landing program this stage is used to provide the escape velocity to the Apollo Spacecraft. The stage configuration is composed of one J-2 engine, a LOX tank and feed system, a hydrogen tank and feed system, and the other associated elements of a boost vehicle.

The engine will be identical to the engines used for the S-II Stage. It will be center mounted and capable of gimballing a maximum of ± 7 degrees in a square pattern, with an additional 1/2-degree allowable for overtravel, snubbing, misalignment, etc.

A 3000-psi cold gas helium system is provided for liquid oxygen tank pressurization, and the hydrogen tank will be pressurized in flight by bleed hydrogen from the engine and prepressurized with cold helium from a ground source.

A closed-loop propellant utilization system will be designed with the capability of limiting total residual propellants over and above unusable propellants to 1000 pounds.

CONTRACTORS

Prime - Douglas Aircraft Company
Engine - Rocketdyne

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

S-IVB Stage Description

RELIABILITY DOCUMENTATION

Subsystems: S-IVB

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis	1	
4. Criticality Analysis	1	
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

1. Some of the available data pertains to the S-IV stage since little information has as yet been provided regarding the S-IVB stage.
- 2.
- 3.
- 4.

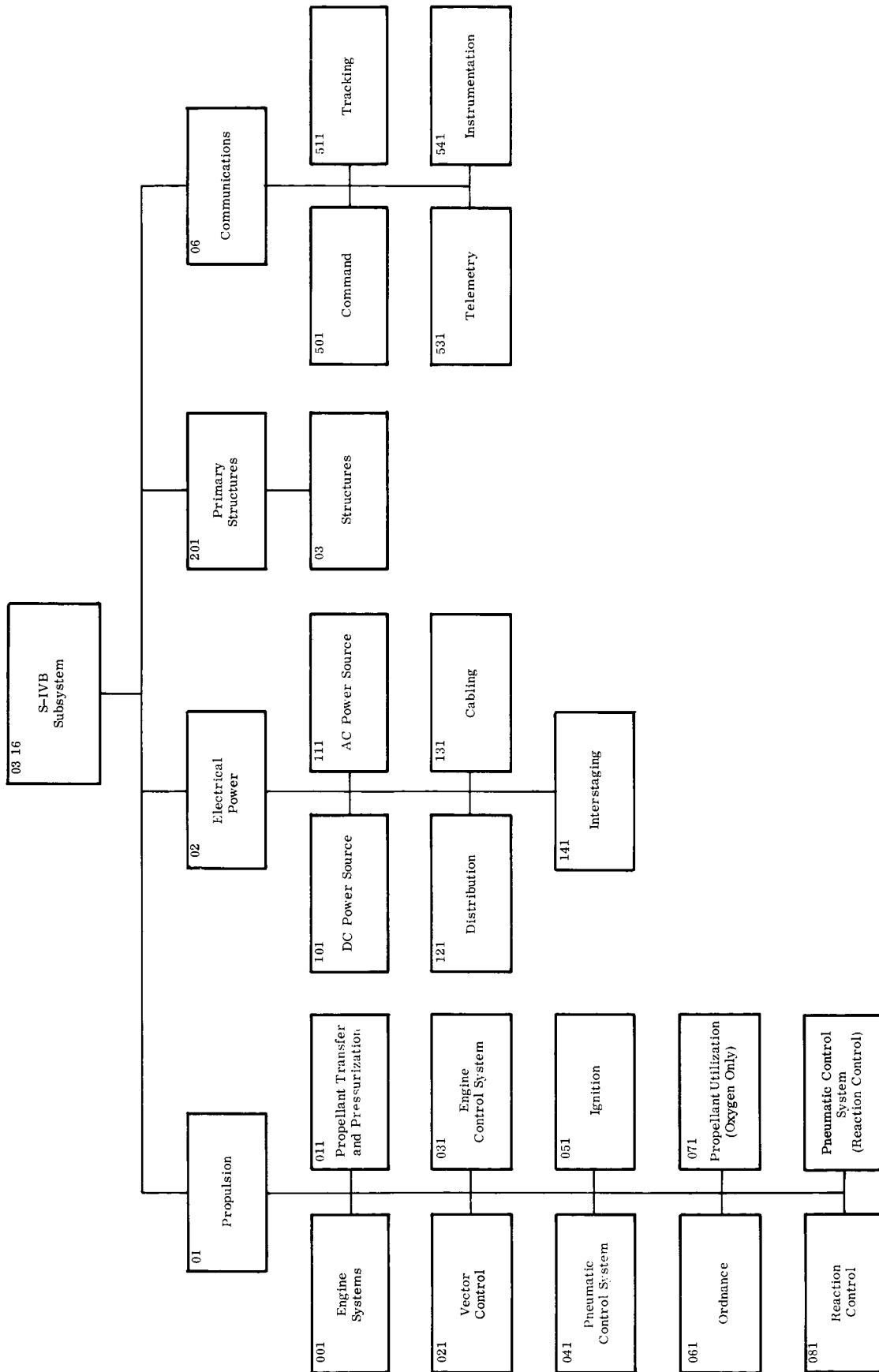


Figure 15-1. S-IVB Stage Block Diagram

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S-IVB Stage Description

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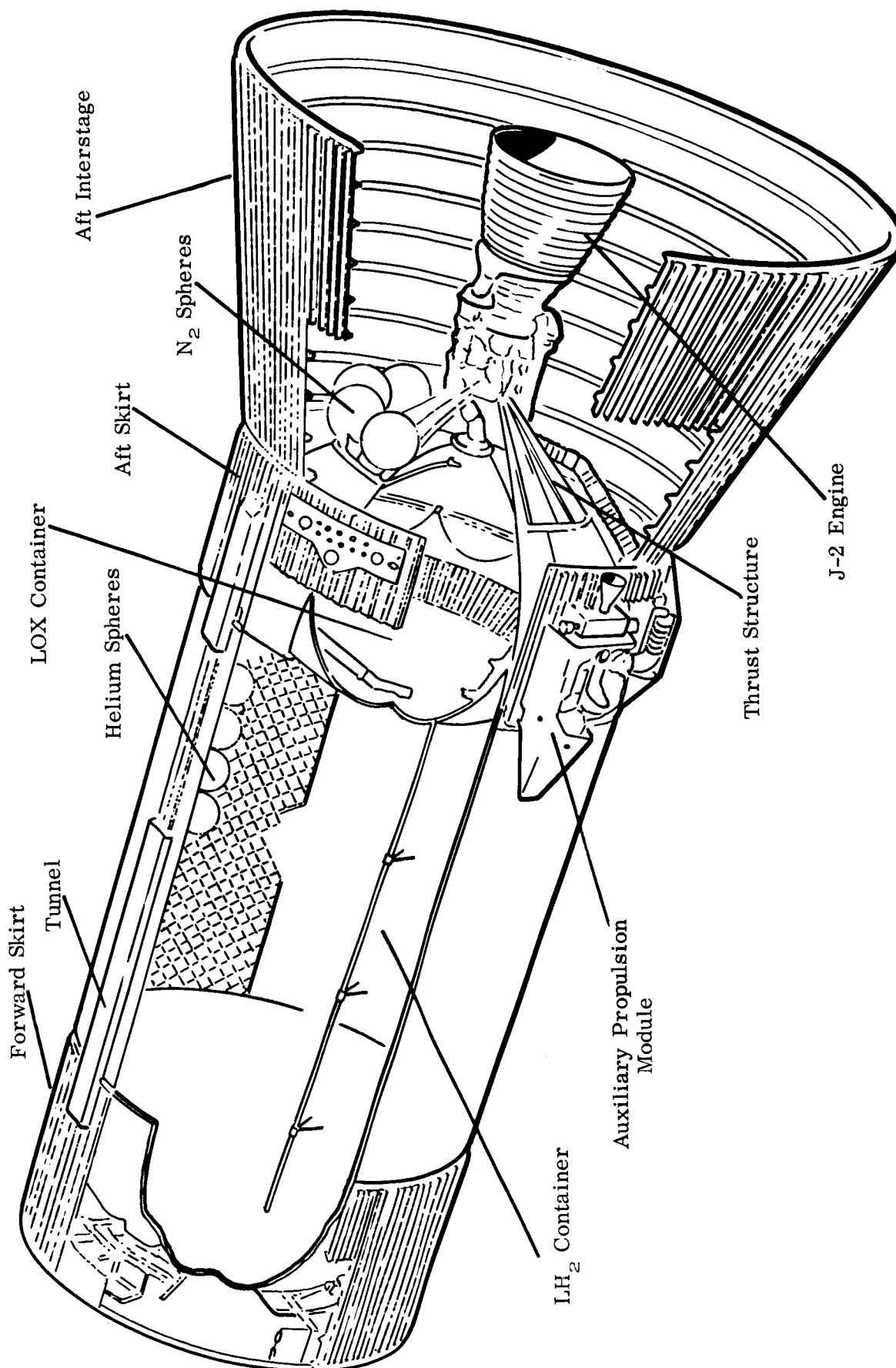
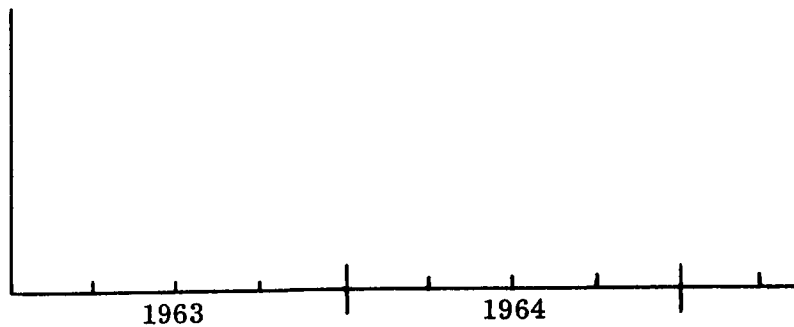


Figure 15-2. S-IVB Stage Profile

S-IVB Propulsion System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Engine Systems	001						
Propellant Transfer and Utilization	011						
Vector Control	021						
Engine Control	031						
Pneumatic Control	041						
Propellant Utilization (oxidizer only)	071						
Ordnance	061						
Ignition	051						
Reaction Control	081						

Notes:

- 1.
- 2.
- 3.
- 4.

S-IVB PROPULSION SYSTEM (CODE: 03 16 01)

FUNCTION

The propulsion system consists of one J-2 engine with a thrust of 200,000 pounds vacuum rating and a hypergolic powered roll and attitude control system. The engine will be capable of gimbaling a maximum of ± 7 degrees in a square pattern, with an additional 1/2-degree allowable for overtravel, snubbing, misalignment, etc.

A propellant pressurization system is provided with a 3000-psi cold gas helium system to pressurize the liquid oxygen tank and a hydrogen bleed from the engine coupled with pressurized helium to pressurize the hydrogen tank.

A closed-loop propellant utilization system will be designed with the capability of limiting total residual propellants over and above unusable propellants to 1000 pounds. In addition, the system will be designed to provide an input to the propellant loading system to control the mass of propellant loading.

Ground purging or conditioning of the S-II/S-IVB interstage compartment will be accomplished with gaseous nitrogen.

Retrorockets will be solid propellant rocket motors.

A closed-loop hydraulic system will be used to provide control power for engine gimbaling.

CONTRACTORS

Prime Contractors

- Propulsion Engine - Rocketdyne
- Retrorockets - Thiokol

MAJOR CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS

S-IVB Propulsion System

RELIABILITY DOCUMENTATION

Functional Subsystem: S-IVB Propulsion

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

S-IVB Propulsion System

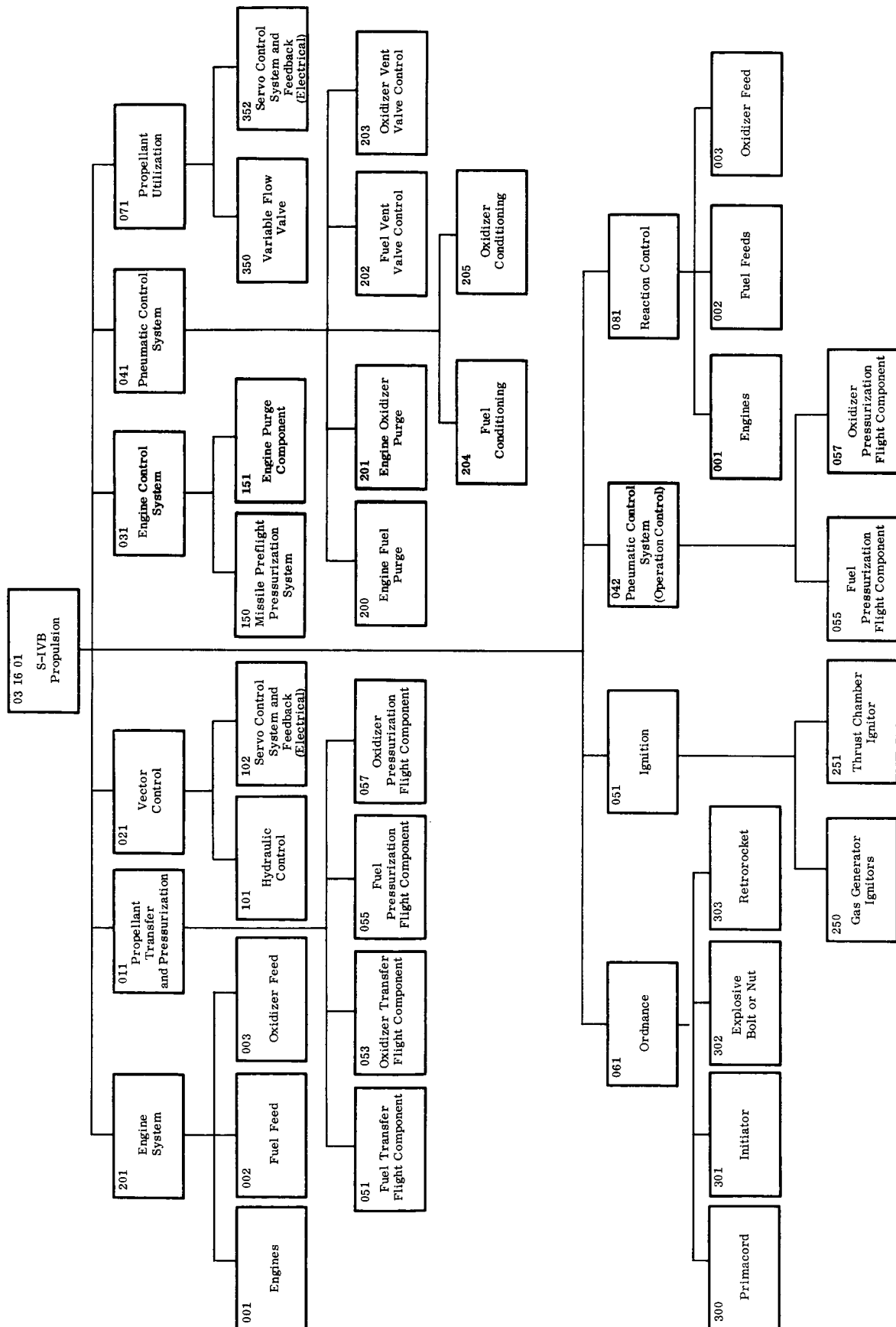


Figure 15-3. S-IVB Propulsion Block Diagram

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S-IVB Propulsion
System

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S-IVB Propulsion System

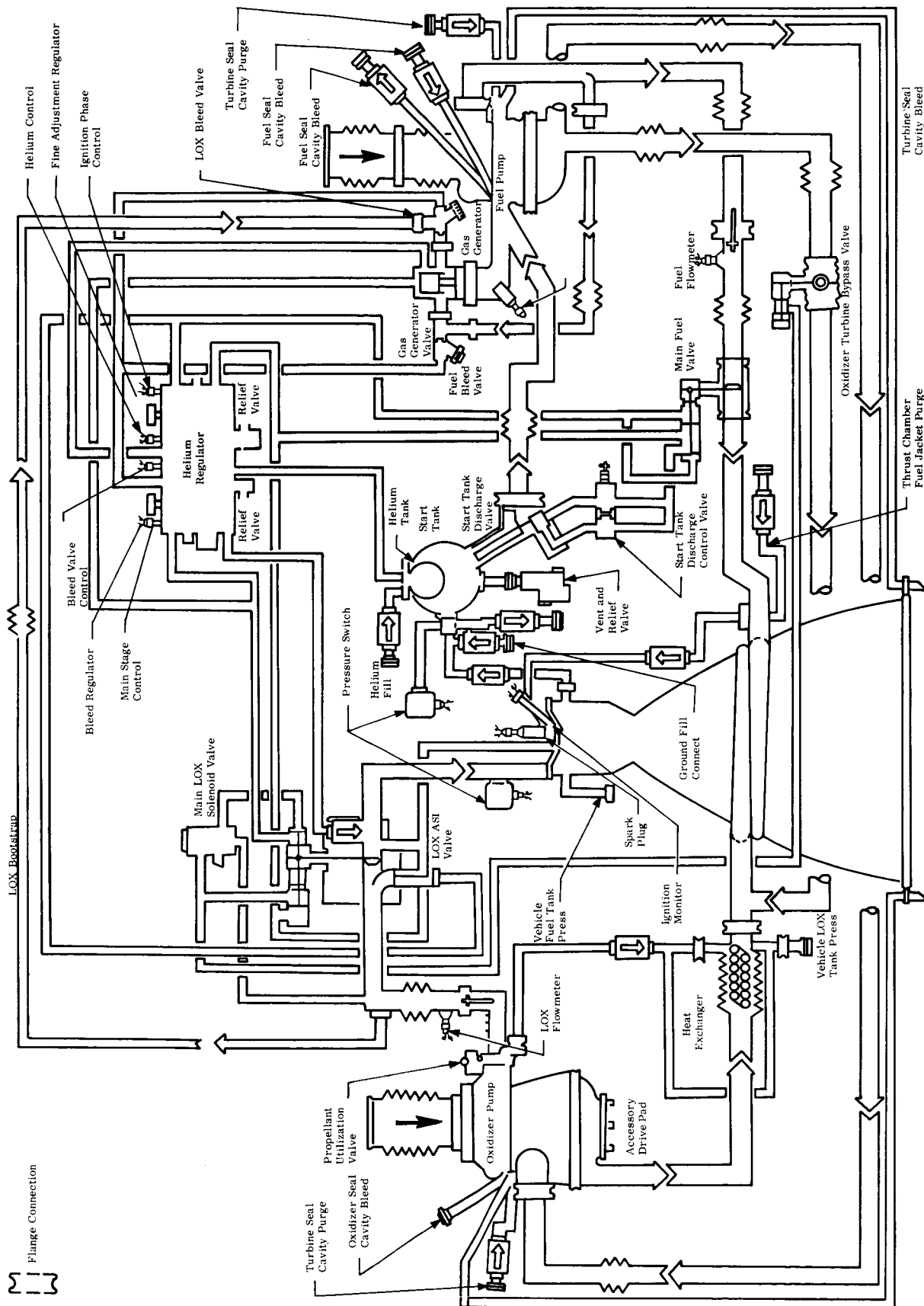


Figure 15-4. J-2 Engine

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S-IVB Electrical Power System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
DC Power	101						
AC Power	111						
Distribution	121						
Cabling	131						
Interstaging	141						

Notes:

- 1.
- 2.
- 3.
- 4.

~~CONFIDENTIAL~~

S-IVB STAGE ELECTRICAL POWER SYSTEMS

The power systems are reasonably simple ones in which direct and alternating current needs are supplied by batteries and inverters as appropriate. Certain of the components are items of more or less standard use in the industry. The systems, themselves, however, are not well defined in the information presently available, and their analysis has proceeded on the basis of synthesized systems which are assumed to be most probable configurations. Since relatively subtle changes in the configuration and components used in such a system can have major effect on the reliability achieved, the values thus far derived are of low confidence.

The launch vehicle operations are of relatively short duration. The noise, vibration, and possibly moisture environment are extreme and the line transients resulting from certain equipment operations are of considerable magnitude. These situations have an effect upon the reliability of the equipment in use. Accurate evaluation of these factors as applied to the specified Apollo hardware is not presently possible.

S-IVB Electrical Power System

RELIABILITY DOCUMENTATION

Functional Subsystem: S-IVB Electrical Power (03 16 02)

	Center Submittals Received	
	Yes	No
1. Design Specifications		1
2. Top Drawings		1
3. Failure Effect Analysis		1
4. Criticality Analysis		1
5. Performance Analysis		1
6. Structural Analysis		1
7. Maintainability Plan		1
8. Reliability Apportionments		1
9. Reliability Model		1
10. Quarterly Reliability Reports		1
11. Test Results		1

Notes:

1. Information not available as of 15 September 1963.
- 2.
- 3.
- 4.

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S-IVB Electrical Power System

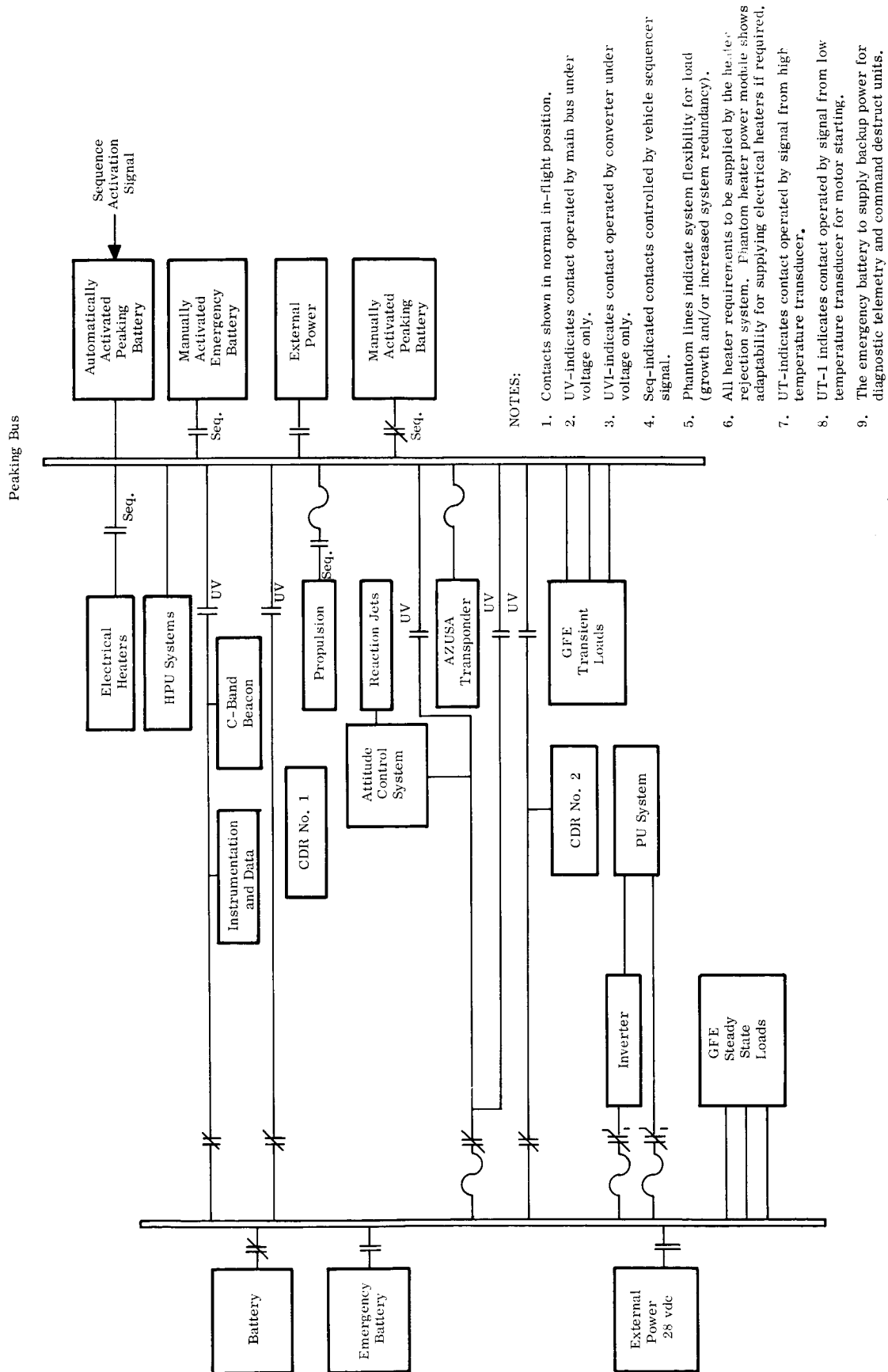


Figure 15-5. Power System Block Diagram

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S-IVB Electrical Power
System

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S-IVB STRUCTURES (CODE: 03 16 03)

FUNCTION

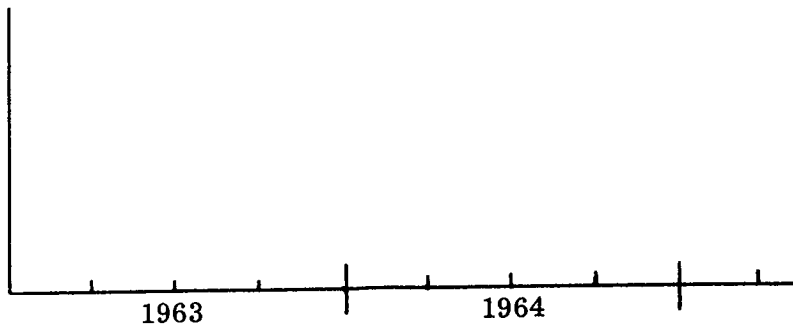
MAJOR CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS

CONTRACTORS

S-IVB Communications

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Command Communications	501						
Tracing	511						
Telemetry	531						
Instrumentation	541						

Notes:

- 1.
- 2.
- 3.
- 4.

S-IVB COMMUNICATIONS (CODE: 03 16 06)

FUNCTION

S-IVB communications is equipped with measuring, signal conditioning, and telemetry systems for real time transmission of the operating parameters of the vehicle. An emergency detection system is provided to allow a safe abort of the crew. A command destruct system is also provided in the event of mission abort.

CONTRACTORS

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

S-IVB Communications

RELIABILITY DOCUMENTATION

Functional Subsystem: S-IVB Communications (03 16 06)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		Not applicable
7. Maintainability Plan - Flight	Not applicable	Not applicable
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

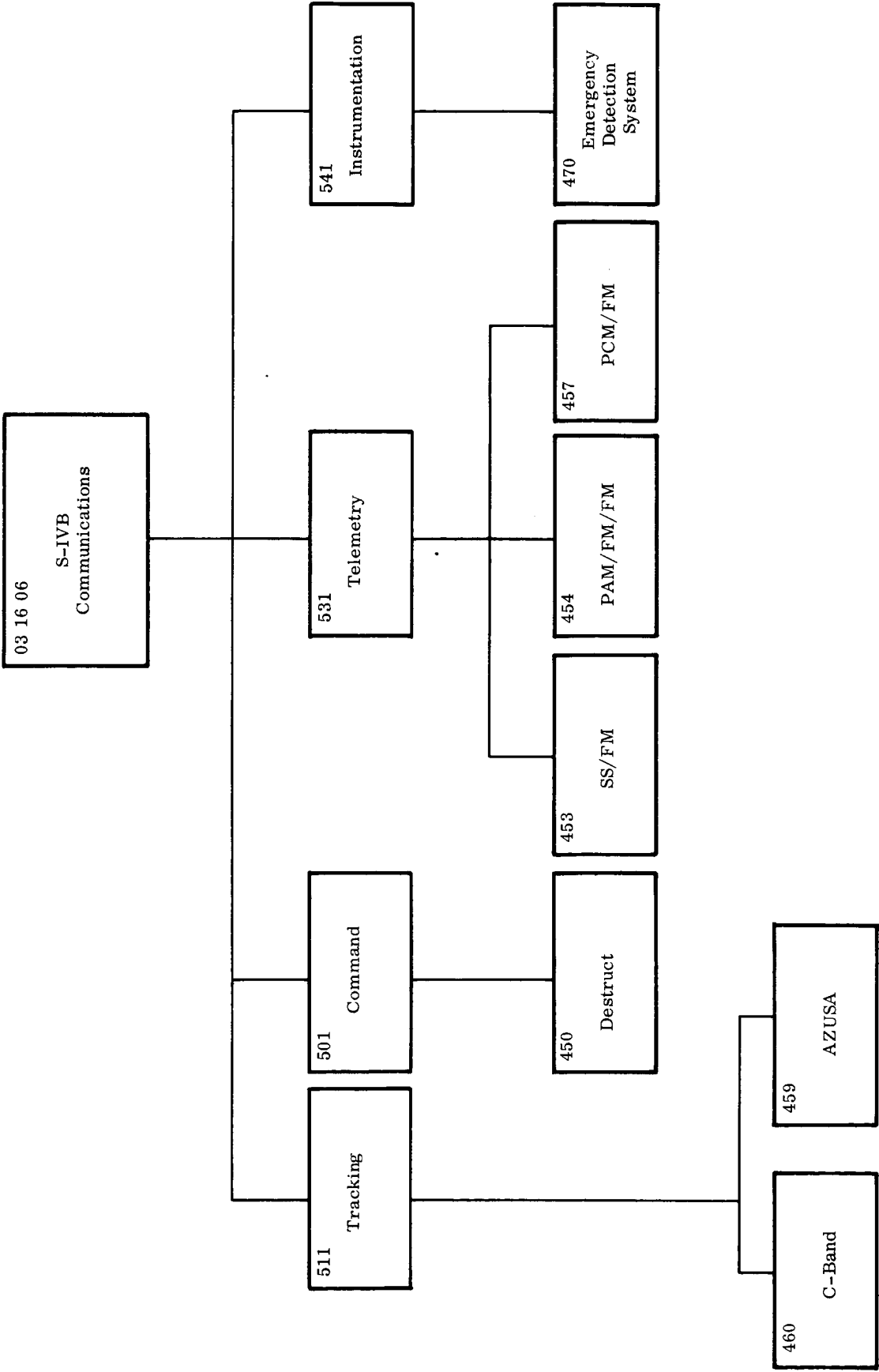


Figure 15-6. S-IVB Communications

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SECTION 16
INSTRUMENT UNIT

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Instrument Unit Description

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Electrical power	02				0	1
Structure	03				-	
Environmental Control	04				1.2	1
Guidance	05				6.8	1
Communications	06				-	

Notes:

1. Engineering estimate for illustration.
- 2.
- 3.
- 4.

SECTION 16

INSTRUMENT UNIT (CODE: 03 05)

INSTRUMENT UNIT DESCRIPTION (CODE: 03 05)

FUNCTION

The instrument unit is an interstage adapter between the launch vehicle and the spacecraft. It houses the launch guidance and control system, an emergency detection system, and various RF components including tracking transponders, telemetry transmitters, and command receivers. The structure is permanently attached to the S-IVB stage, and includes a separation interface at the spacecraft.

CONTRACTORS

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

Instrument Unit Description

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RELIABILITY DOCUMENTATION

Functional Subsystem: Instrument Unit (Code: 03 05)

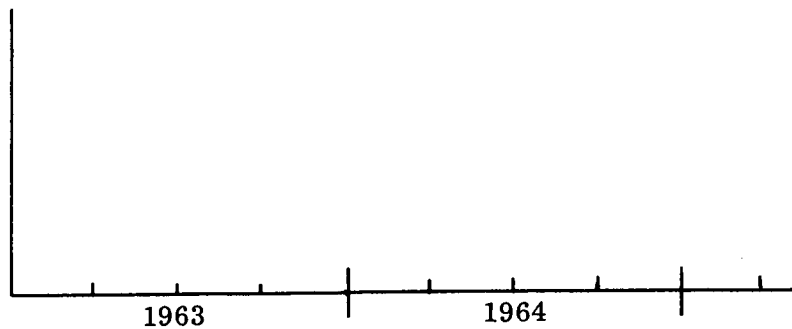
	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

1. Data not available as of 15 September 1963.
- 2.
- 3.
- 4.

Instrument Unit Electrical
Power System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
DC Power source	101						
AC Power source	111						
Distribution	121						
Cabling	131						
Interstaging	141						

Notes:

- 1.
- 2.
- 3.
- 4.

INSTRUMENT UNIT ELECTRICAL POWER SYSTEM

The power systems are reasonably simple ones in which direct and alternating current needs are supplied by batteries and inverters as appropriate. Certain of the components are items of more or less standard use in the industry. The systems, themselves, however, are not well defined in the information presently available, and their analysis has proceeded on the basis of synthesized systems which are assumed to be most probable configurations. Since relatively subtle changes in the configuration and components used in such a system can have a major effect on the reliability achieved, the values thus far derived are of low confidence.

The launch vehicle operations are of relatively short duration. The noise, vibration, and possibly moisture environment are extreme and the line transients resulting from certain equipment operations are of considerable magnitude. These situations have an effect upon the reliability of the equipment in use. Accurate evaluation of these factors as applied to the specified Apollo hardware is not presently possible.

Instrument Unit Electrical
Power System

RELIABILITY DOCUMENTATION

Functional Subsystem: Instrument Unit Electrical Power (Code: 03 05 02)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

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Instrument Unit Structures

INSTRUMENT UNIT STRUCTURES (CODE: 03 05 03)

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Instrument Unit Environmental
Control System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Pressuriza- tion Regula- tor	312						
Liquid Nitro- gen Cooling	313						
Circulation System	314						

Notes:

- 1.
- 2.
- 3.
- 4.

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Instrument Unit Environmental
Control System

INSTRUMENT UNIT ENVIRONMENTAL CONTROL SYSTEM (CODE: 03 05 04)
DESCRIPTION

FUNCTION

The function of the environmental control system in the instrument unit is primarily the maintenance of suitable operating temperature for the electronic equipment aboard. The unit is a gaseous nitrogen system, but its elements are not presently well defined. Earlier Saturn vehicle instrumentation carried equipment which has been assumed to be similar to that intended for the Apollo launch vehicles and preliminary estimates made on this basis. Since many of the critical components of the launch vehicle guidance are dependent upon this system, it has direct effect upon the mission reliability and safety. Further definition will be required for the development of accurate predictions.

CONTRACTORS

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

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Instrument Unit Environmental Control System

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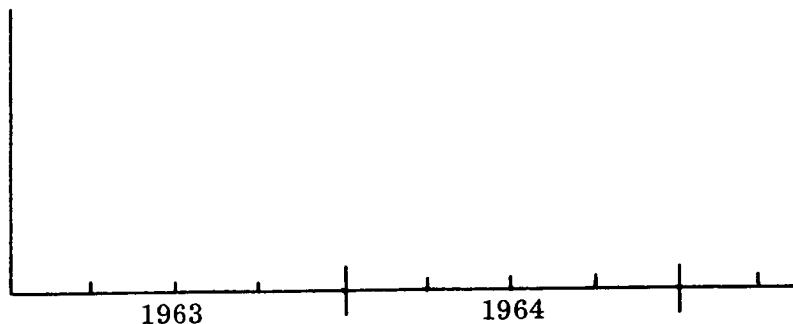
RELIABILITY DOCUMENTATION

Functional Subsystem: Instrument Unit Environmental Control (Code: 03 05 04)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

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RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
ST-124	503				0.96729		2
Digital Guid. Comp.	504				0.99898		1, 2
Guid. Sig. Proc.	505				0.98528		2
Azi. Align. Package	506						
Control Computer	507				0.99953		2
Decoder	508						
GN ₂ Bearing Supply	509						
Flt. Seq.	510						

Notes:

1. Reliability figure was based on ASC-15 computer assuming it to be similar for failure predictions.
2. Reliability predictions based on preliminary study of Saturn V vehicle report by ARINC dated 30 June 1963.
- 3.
- 4.

INSTRUMENT UNIT GUIDANCE AND CONTROL SYSTEM (CODE: 03 05 05 411)

FUNCTION

The adaptive guidance mode concept is used to meet the severe requirements placed on the guidance system. This mode functions by accepting the present vehicle flight variables and engine parameter as initial conditions and defining the optimum path ahead which meets the mission requirements.

The major subsystems are a four gimbal inertial platform, general purpose digital computer, and an analog computer. (See Figure 16-1.)

CONTRACTORS

MAJOR CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS

Instrument Unit Guidance
and Control System

RELIABILITY DOCUMENTATION

Functional Subsystem: Instrument Unit Guidance and Control System

	Center Submittals Received	
	Yes	No
1. Design Specifications	April 1962	X
2. Top Drawings		
3. Failure Effect Analysis		X
4. Criticality Analysis		
5. Performance Analysis		X
6. Structural Analysis	Not Applicable	Not Applicable
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

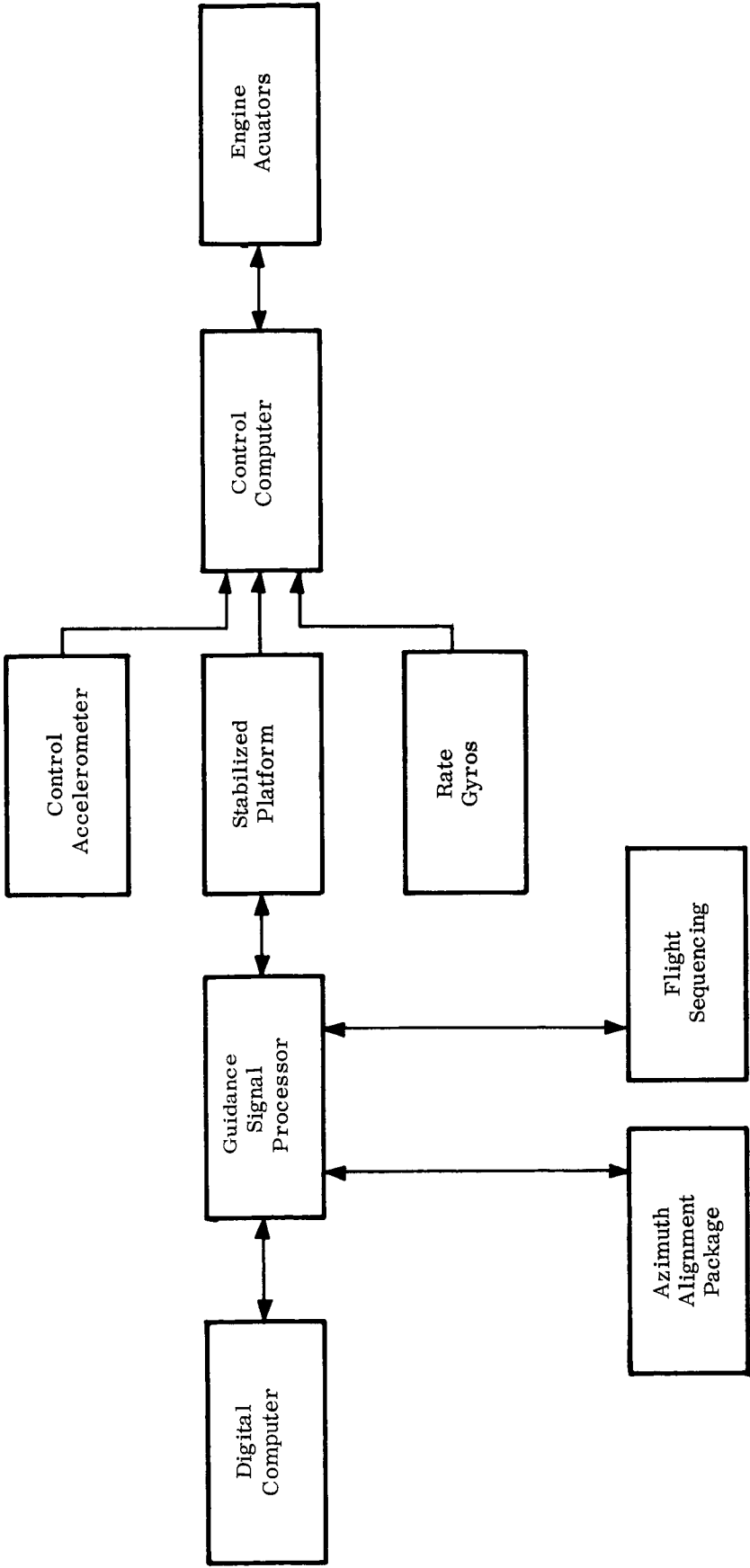
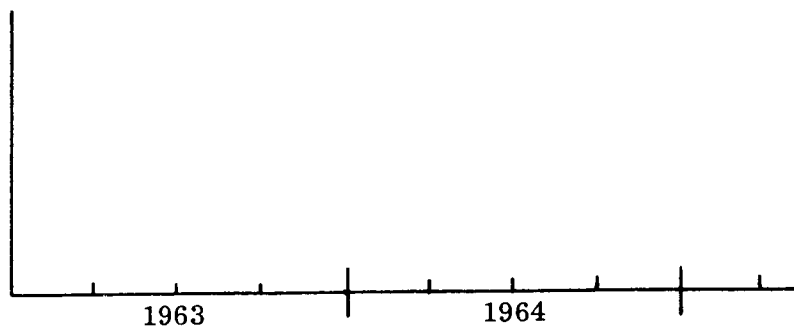


Figure 16-1. Guidance and Control System

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Instrument Unit Communications

RELIABILITY: Allocated ● Predicted ○ Achieved x

RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Telemetry	531						
Tracking	511						

Notes:

- 1.
- 2.
- 3.
- 4.

INSTRUMENT UNIT COMMUNICATIONS (CODE: 03 05 06)

FUNCTION

Instrument unit communications is equipped with measuring, signal conditioning, and telemetry system for realtime transmission of the operating parameters of the vehicles. Tracking subsystems are provided to determine launch trajectory and near earth orbit. (See Figure 16-2.)

CONTRACTORS

MAJOR CONTRIBUTOR TO UNRELIABILITY

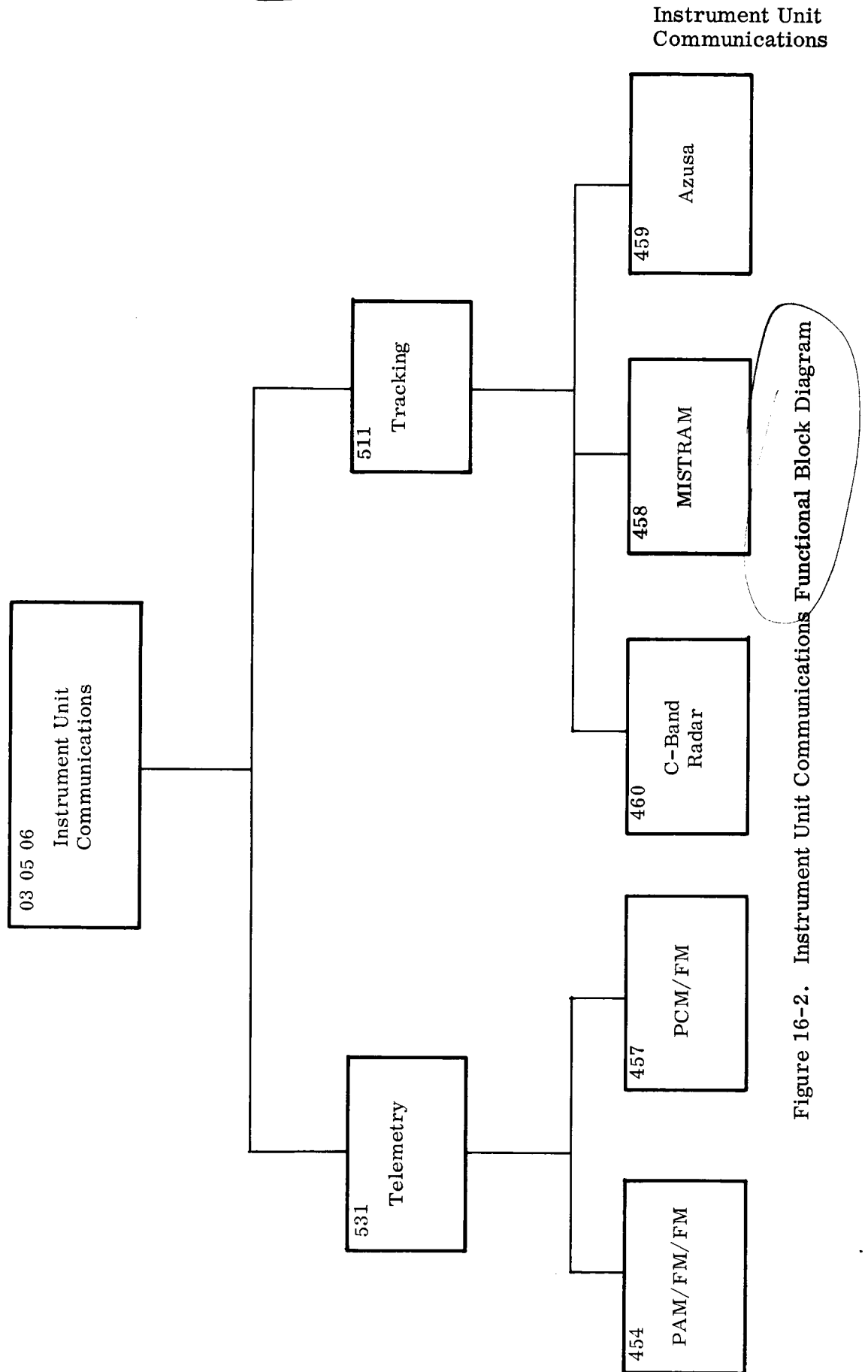
RELIABILITY TRENDS

Instrument Unit Communications

RELIABILITY DOCUMENTATION

Functional Subsystem: Instrument Unit Communications (Code: 03 05 06)

	Center Submittals Received	
	Yes	No
1. Design Specifications	April 1962	X
2. Top Drawings		
3. Failure Effect Analysis		X
4. Criticality Analysis		
5. Performance Analysis		X
6. Structural Analysis	Not Applicable	Not Applicable
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X



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SECTION 17
LUNAR EXCURSION MODULE

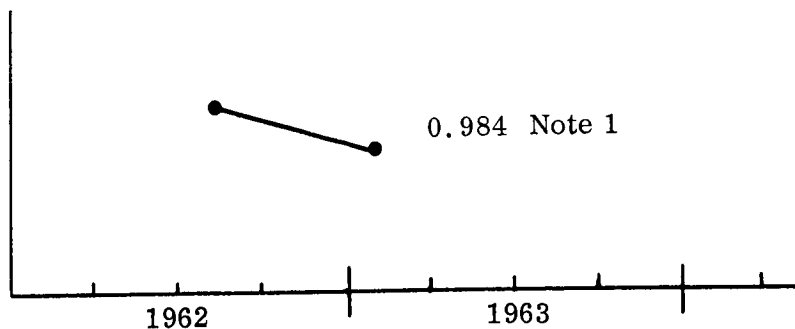
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Lunar Excursion Module Description

RELIABILITY: Allocated ● Predicted ○ Achieved x

Note 6
0.988

Note 5
0.984



RELIABILITY

Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Propulsion	01	0.999968	0.99972		10.8	4
Electrical Power (CM/SM)	02	0.998953	0.9941		7.5	1, 4
Structures	03		0.999994		----	1
Environmental Control	04	0.999154			2.8	2
Guidance	05	0.992183			6.1	3
Stabilization and Control		0.992285				
Communications	06				----	
Crew System	07				----	
Reaction Control					1.2	

Notes:

1. NAA 62-557-4
2. Allocation: Grumman Aiv. Gen. Co. Data
3. Allocation: GAEC LPR 550-1
4. Allocation: NAA 62-557-5
5. NASw: 410 61 14 01
6. NASw: 410 60 14 01

SECTION 17

LUNAR EXCURSION MODULE
(CODE: 03 06)

DESCRIPTION

The lunar excursion module will serve as a vehicle for carrying two of the crew members and payload from the spacecraft in a lunar orbit to the lunar surface and back. This module will have the capability of performing the separation, lunar descent, hovering and translation, landing, ascent, rendezvous, and docking independent of the spacecraft. The lunar excursion module will allow for crew exploration in the vicinity of the lunar touchdown; it is not required to have lunar surface mobility. The lunar excursion module will contain the communication, navigation, guidance, control, computing, display equipment, etc. Equipment arrangements will allow access for maintenance, both before and after earth launch. The module will not be recoverable.

CONTRACTORS

Prime Contractor - MSC/Grumman
Aircraft Engineering
Company

Communications - RCA

Electrical Power - Pratt & Whitney

Reaction Control - Marquardt

Propulsion -

Environmental Control - Hamilton
Standard

Guidance - MIT: ACSP/Raytheon/
Kollsman: RCA

Structure - Grumman

MAJOR CONTRIBUTOR TO UNRELIABILITY

Recent reviews of the planned reliability programs supporting the spacecraft and LEM hardware development have shown fundamental differences in the philosophies guiding the reliability programs. Resolution of the differences to allow meaningful comparisons of values attained will be necessary and is underway. Specifically, the North American testing philosophy is based upon mission simulations in which attributes data are recorded. On the other hand, Grumman uses a qualification test-to-failure technique which provides data of a different sort.

RELIABILITY TRENDS

Estimates made largely by the basis of study and proposal material.

Lunar Excursion Module Description

RELIABILITY DOCUMENTATION

Functional Subsystem: LEM (03 06)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments	1	
9. Reliability Model	1	
10. Quarterly Reliability Reports	1	
11. Test Results		X

Notes:

1. Partial information, GAEC LPR 550-1.
- 2.
- 3.
- 4.

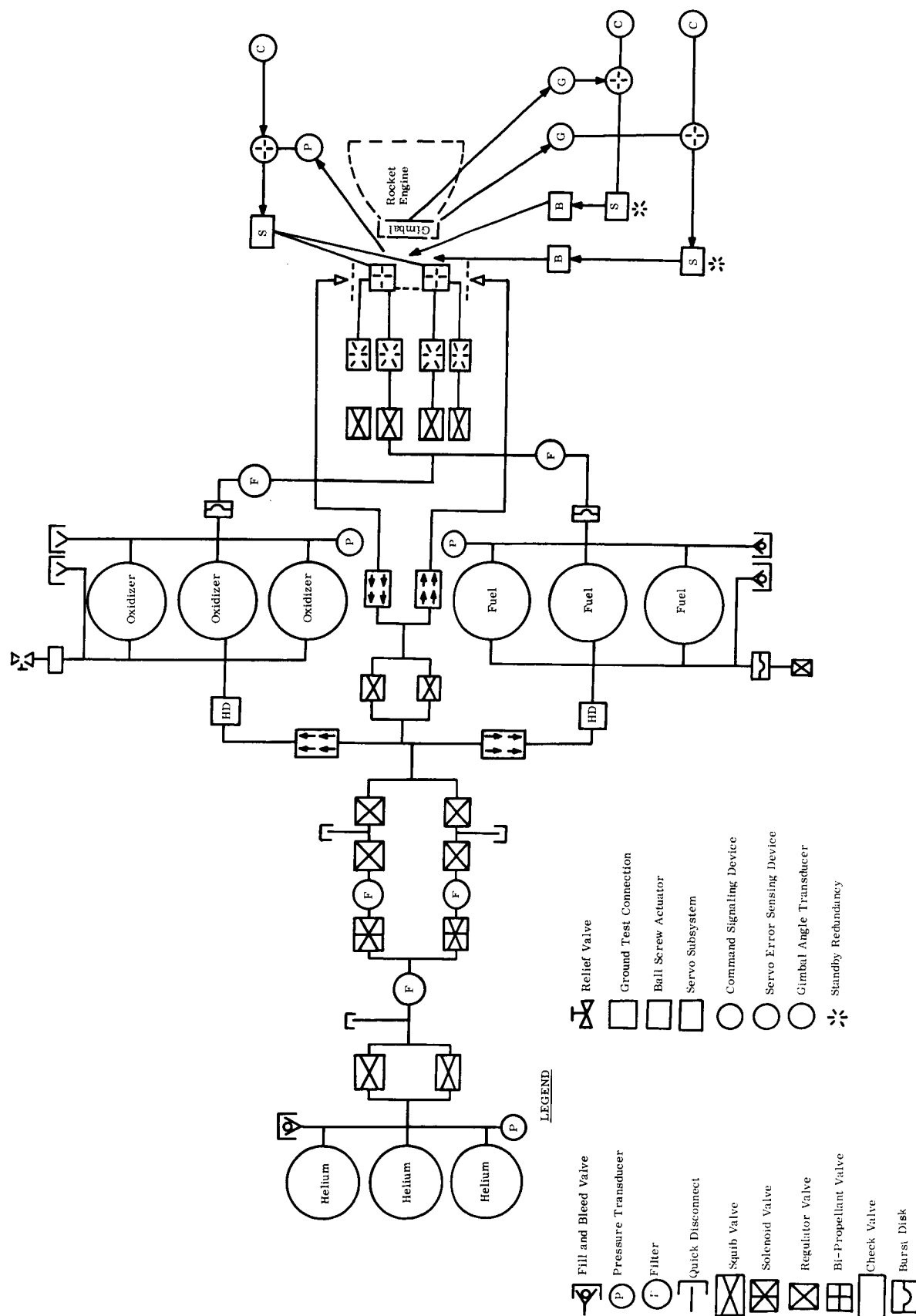


Figure 17-1. Functional Block Diagram Descent Schematic

Lunar Excursion Module Propulsion System

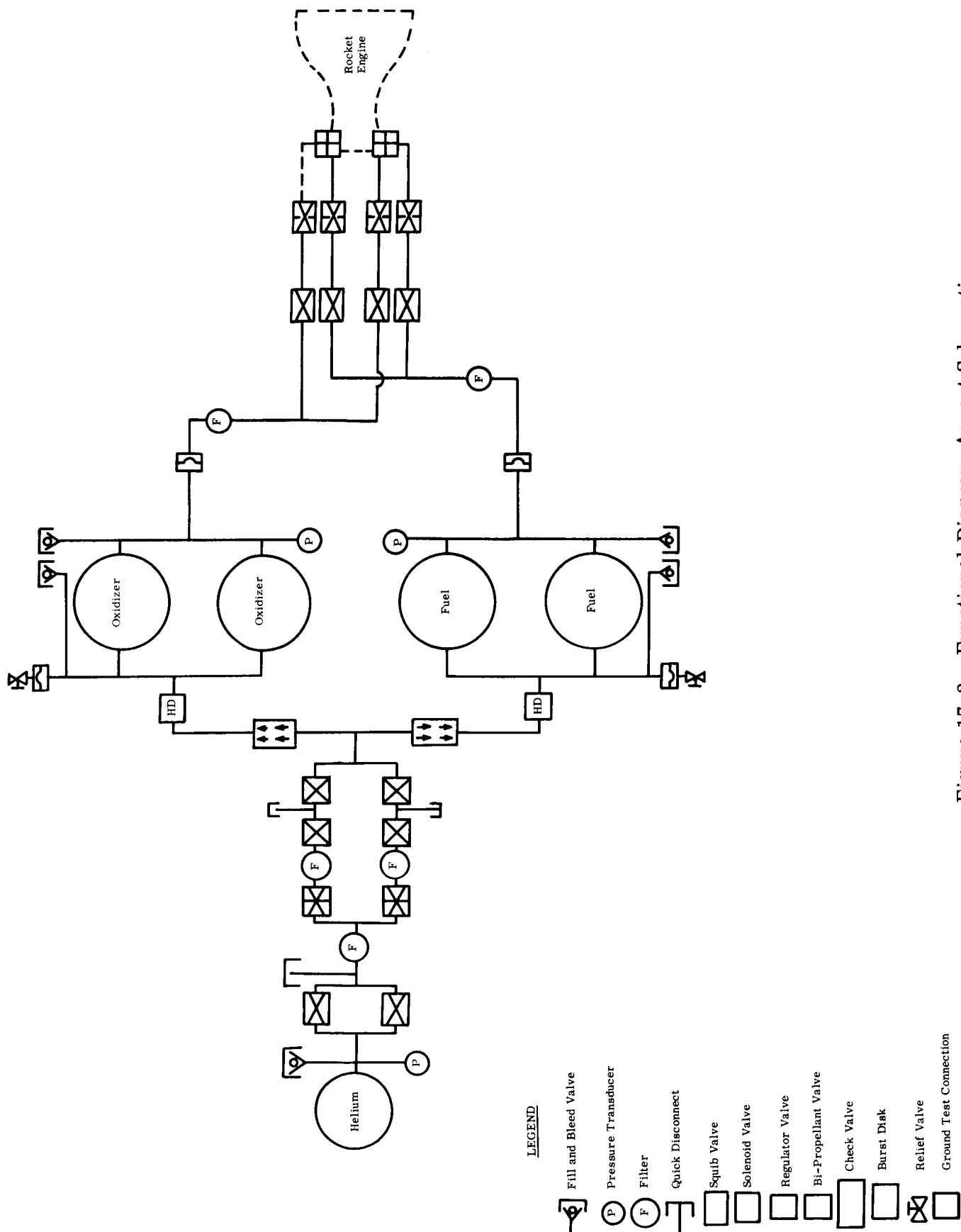


Figure 17-2. Functional Diagram Ascent Schematic

Thruster Valves (Two Per Engine)

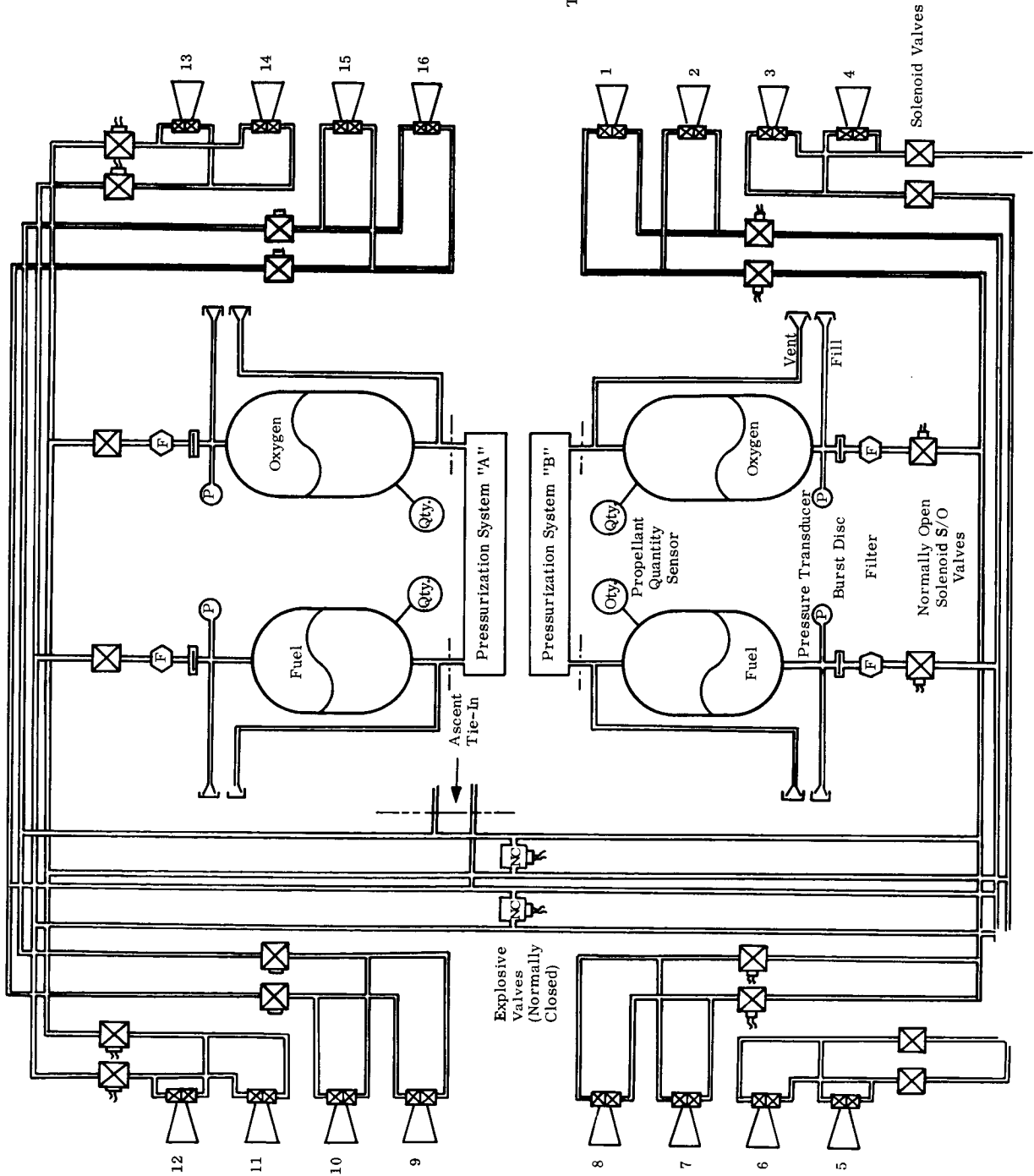


Figure 17-3. Propellant and Thrust Chamber Section Schematic

Lunar Excursion Module Propulsion System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Engine System	001						
Propellant Transfer and Pressurization	011						
Vector Control	021						
Pneumatic Control	041						
Ignition	051						
Propellant Utilization	071						
Reaction Control	081						
Ordnance	061						

Notes:

- 1.
- 2.
- 3.
- 4.

LUNAR EXCURSION MODULE PROPULSION SYSTEM (CODE: 03 06 01)

FUNCTION

The lunar excursion module propulsion is expected to include a descent main engine, an ascent main engine, descent reaction controls, and ascent reaction controls. Both main engines will probably be gimbaled.

Both main engine systems and both reaction control systems will use hypergolic propellants consisting of a 50-50 combination of UDMH and N_2O_4 . The descent main engine must have a throttle capability.

(A Grumman report is in the process of being passed through official channels and should be available for the next report.)

PRIME CONTRACTOR

Grumman Aircraft Engineering Corporation

MAJOR CONTRIBUTORS TO UNRELIABILITY

Because of the frequency with which reaction controls are used and the small value of the impulse required, it is impractical to use ullage rockets to seat propellants prior to expulsion. Instead, a bladder is used to expel the propellants. Because the bladder is in continuous contact with the propellants, it undergoes degradation prior to use and is therefore a major source of unreliability. In addition to this difficulty, the bladder is likely to be sufficiently permeable to permit back diffusion of hypergolic propellants leading to upstream mixing of oxidizer and fuel which could explode and rupture the lines used to pressurize the bladders.

It is to be hoped that the use of bladders in the main propulsion systems can be avoided. However, the continuous burn characteristic of the main engines will cause burnthrough failure hazards to which the intermittently burning reaction control engines will not be as easily susceptible.

Valve seat material in both the main engine systems and reaction controls will be a source of difficulty to the corrosive nature of hypergolic propellants.

Lunar Excursion Module Propulsion System

RELIABILITY TRENDS

Very little improvement can be expected on state-of-the-art equipment since the law of diminishing returns has already been approached. However, a breakthrough in providing improved material for bladders and valve seats would help materially. The predictions themselves can be expected to change considerably as more and better test and flight data become available.

STATE-OF-THE-ART PROPULSION RELIABILITY

The reliability block diagram used in Figure 17-4 is intended to be used for illustrative purposes. The reliability number derived is for a single start-run-shut down sequence. It is based on the observed reliabilities of similar propulsion systems which have been debugged and which use well-developed components and therefore represents "state-of-the-art". The actual configurations will undoubtedly have a different reliability because of different operating modes and improved redundancy. The latter two factors will partially offset each other.

STATE-OF-THE-HARDWARE PROPULSION RELIABILITY

A reliability prediction model based on exact engineering configuration is being prepared as rapidly as possible within the present information limitations.

RELIABILITY DOCUMENTATION

Functional Subsystem: Lunar Excursion Module Propulsion (03 06 01)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

- 1.
- 2.
- 3.
- 4.

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Lunar Excursion Module Propulsion System

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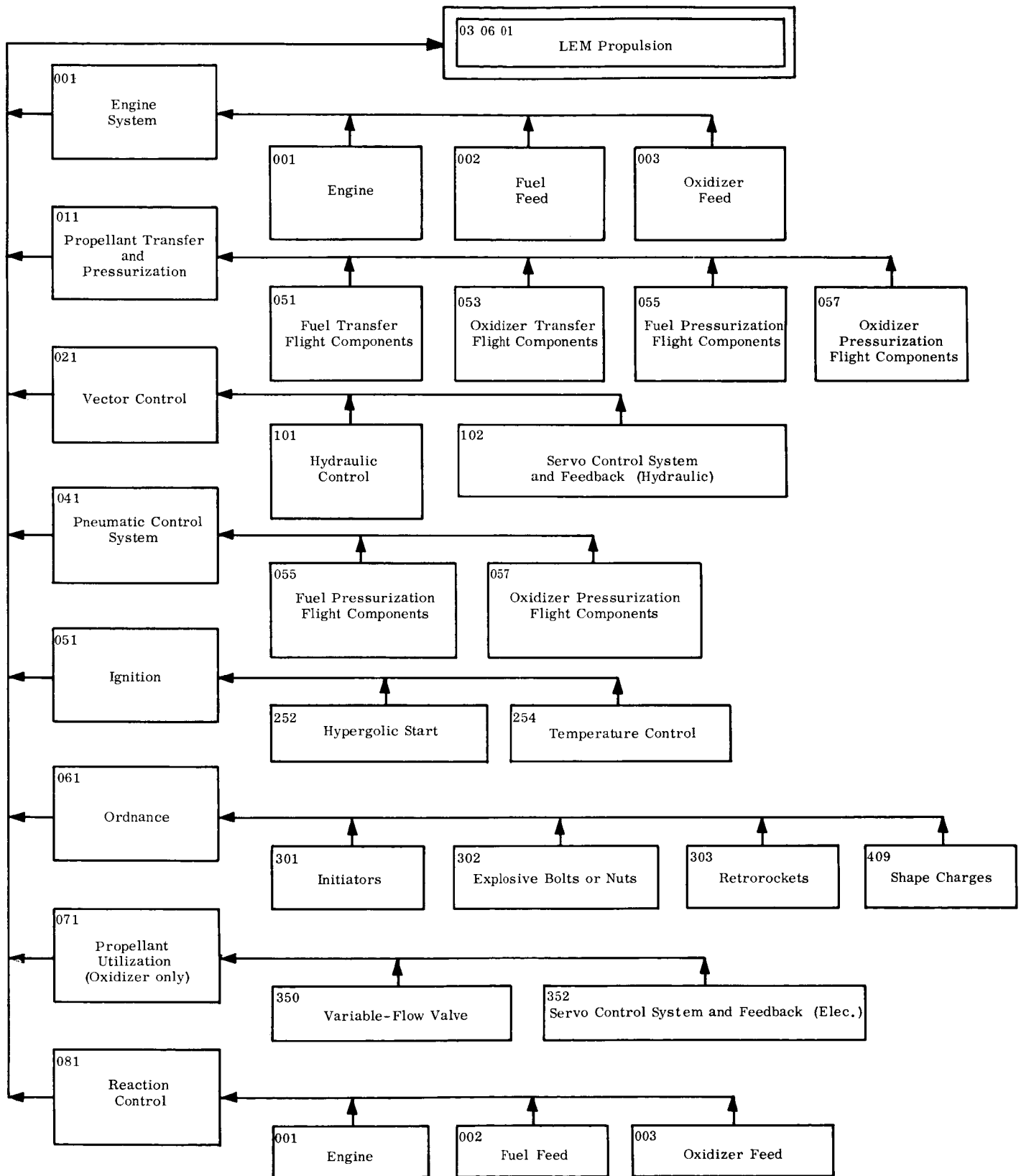


Figure 17-4. State-of-the-Art Model

Lunar Excursion Module Electrical Power System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
DC Power	101						
AC Power	111						
Distribution	121						
Cabling	131						
Interstaging	141						
Lighting	151						

Notes:

- 1.
- 2.
- 3.
- 4.

LUNAR EXCURSION MODULE ELECTRICAL POWER SYSTEM (CODE: 03 06 02)

FUNCTION

The lunar excursion module electrical power system must function for an extended period to provide ac and dc outputs for many critical systems. The lunar excursion module system, like the CM/SM system, consists of both batteries and fuel cells. It provides for the normally predicted loads as well as emergency modes of operation to allow safety in abort situations.

The lunar excursion module electrical power system is not adequately defined in the presently available information. Data from a number of proposals and studies have been used to provide most probable values for reliability studies.

Lunar Excursion Module Electrical Power System

RELIABILITY DOCUMENTATION

Functional Subsystem: Lunar Excursion Module Electrical Power (03 06 02)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

- 1.
- 2.
- 3.
- 4.

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Lunar Excursion Module Structures

LUNAR EXCURSION MODULE STRUCTURES (CODE: 03 06 03)

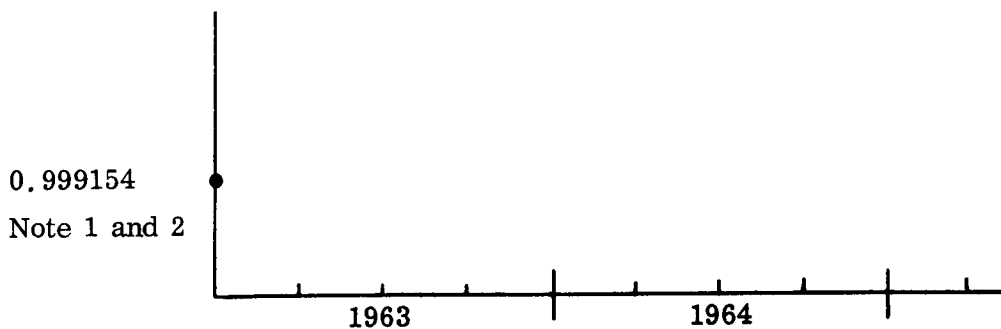
Predicted Reliability: 0.999994.

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Lunar Excursion Module Environmental Control System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
O ₂ Supply	311						
Water System	316						
Pressure Suit	321						
Back Pack	326						
Atmosphere Conditioning	331						

Notes:

1. Success estimate; Crew safety: 0.9999
2. NAA 62-557-4
- 3.
- 4.

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Lunar Excursion Module Environmental Control System

LUNAR EXCURSION MODULE ENVIRONMENTAL CONTROL SYSTEM (CODE: 03 06 04)

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Lunar Excursion Module Environmental Control System

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RELIABILITY DOCUMENTATION

Functional Subsystem: Lunar Excursion Module Environmental Control (03 06 04)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

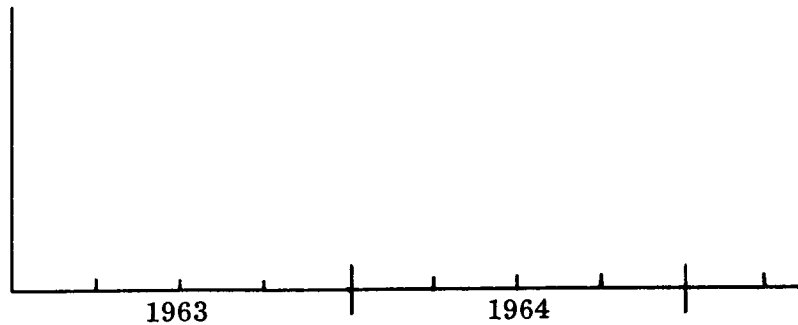
Notes:

- 1.
- 2.
- 3.
- 4.

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Lunar Excursion Module Guidance and Navigation System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Inertial Measurement Unit		Not Available	Not Available				
Power and Servo Assembly		Not Available	Not Available				
Coupling Display Units		Not Available	Not Available				
Telescope		Not Available	Not Available				
Radar Altimeter		(1)	(1)				
Tracking Radar							
Displays and Controls							
Guidance and Navigation		0.992183 (2)	~0.96 (3)				

Notes:

1. A LEM Guidance and Navigation reliability allocation at this hardware level has not been submitted.
2. GAEC LPR-550-1 First Quarterly Reliability Status Report.
3. Independent estimate using GAEC component part failure rates from LPR-550-1.
- 4.

LUNAR EXCURSION MODULE GUIDANCE AND CONTROL (CODE: 03 06 05)

FUNCTION

The guidance and control functions are accomplished by two interconnected systems, the guidance and navigation system, and the stabilization and control system. The integrated system, with crew participation, determines and directs all translational and rotational velocity changes required of the lunar excursion module to accomplish the mission.

The guidance and navigation system determines lunar excursion module position and velocity, calculates velocity changes required to adhere to the flight plan, and issues steering commands to the stabilization and control system to accomplish these velocity changes.

The stabilization and control system accepts translational and rotational commands from the guidance and navigation system or from the manual controls, and directs the primary propulsion thrust vector and/or the reaction jets as required. In the absence of such commands, the system stabilizes the lunar excursion module attitude orientation by reaction jet control.

See Figure 17-5 for a block diagrammatic representation of the LEM guidance and control function.

CONTRACTORS

Guidance and Navigation: MIT Instrumentation Laboratory

Stabilization and Control: to be supplies (RCA, Autonetics, and others)

MAJOR CONTRIBUTORS TO UNRELIABILITY

GUIDANCE AND NAVIGATION

The guidance computer, the tracking radar, and the power and servo assembly are currently considered to be reliability problems, due to their large numbers of component parts and long operating times in the mission (certain radar components have also exhibited high failure rates). These subsystems are designed for inflight maintenance. Studies are in progress to discover whether inflight maintenance is sufficient or whether other alternatives for reliability improvement are indicated.

Lunar Excursion Module Guidance and Control

The same comments on the guidance computer and the power and servo assembly that are made on the command module guidance and navigation system also apply here since the two systems are largely identical and interchangeable. The tracking radar is also being designed for inflight replacement of high-failure-rate components.

STABILIZATION AND CONTROL

The SCS must function throughout the mission, in several modes of operation, and is essential in the interest of crew safety to a successful abort. Accordingly, the entire system is designed for inflight maintenance, and studies are underway to ascertain that this concept will yield the extremely high reliability required.

The SCS also includes a relatively simple guidance subsystem designed to back up the primary guidance and navigation system for abort during descent to the lunar surface, and for ascent guidance from the lunar surface, if required. The need for redundancy and inflight maintainability in this subsystem is currently under study, as is its contribution to over-all guidance and navigation reliability.

Lunar Excursion Module Guidance and Navigation System

RELIABILITY DOCUMENTATION

Functional Subsystem: Lunar Excursion Module Guidance and Navigation

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		Not Applicable
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

1. Current GNS data derived from MIT/IL reports.
- 2.
- 3.
- 4.

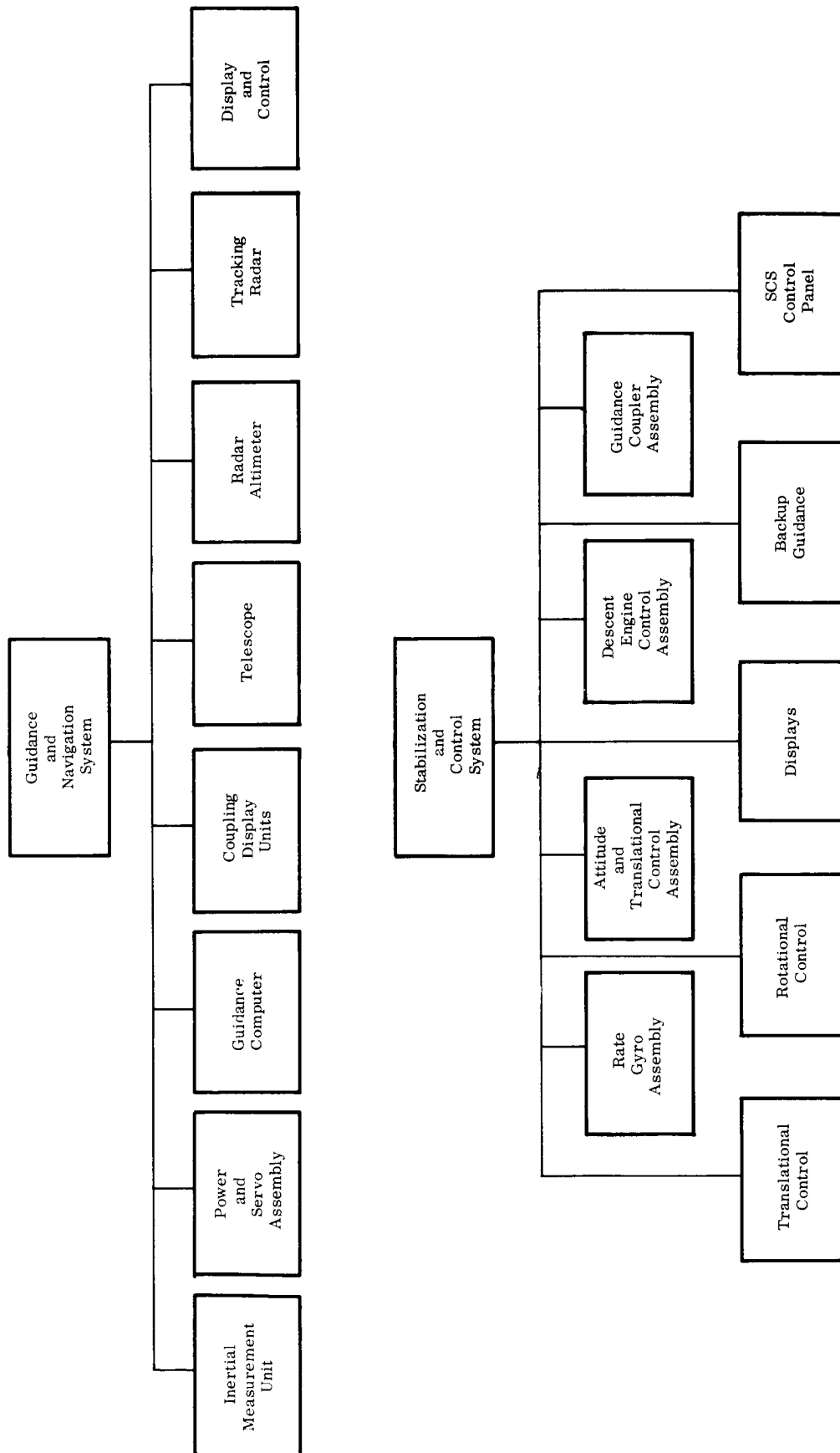


Figure 17-5. LEM Guidance and Control

Lunar Excursion Module Stabilization and Control System

RELIABILITY DOCUMENTATION

Functional Subsystem: Lunar Excursion Module Stabilization and Control

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		Not Applicable
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

1. Current SCS data derived from GAEC LPR-550-1.
- 2.
- 3.
- 4.

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Lunar Excursion Module Stabilization and Control System

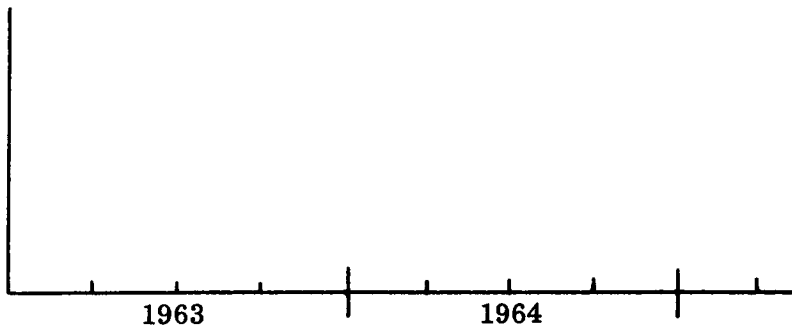
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Lunar Excursion Module Stabilization and Control System

RELIABILITY: Allocated ● Predicted ○ Achieved x

RELIABILITY

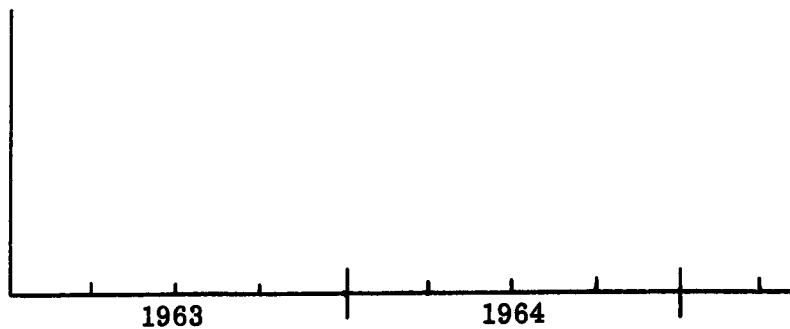
Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Rate Gyro Assy.		0.993896					(1)
Att. & Trans. Cont. Assy.		0.998405					(1)
Guid. Coup. Assy.		0.999984					(1)
Translat. Cont.		0.999946					(1)
Rotat. Cont.		0.999946					(1)
Des. Eng. Cont. Assy.							(2)
Backup Guid.		0.998569					(1)
Displays		0.999982					(1)
SCS Cont. Pn.							(2)
S&C		0.992285					(1)

Notes:

1. GAEC LPR-550-1 First Quarterly Reliability Status Report
2. Omitted in GAEC LPR-550-1
- 3.
- 4.

Lunar Excursion Module Communications

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Audio/Visual	521						
Telemetry	531						
Tracking	511						
Instrumentation	541						

Notes:

- 1.
- 2.
- 3.
- 4.

LUNAR EXCURSION MODULE COMMUNICATIONS (CODE: 03 06 06)

FUNCTION

VOICE

The communication subsystem (see Figure 17-6) is to be capable of providing voice communication between:

- a. The lunar excursion module and the command module during line-of-sight phases of the mission.
- b. The lunar excursion module and the earth.
- c. The lunar excursion module and a crew member at a radial distance of up to three nautical miles from the lunar excursion module.
- d. The crew members within the lunar excursion module.

TELEMETRY

Data transmission shall be provided on either a time shared basis with voice or transmitted simultaneously with voice.

TELEVISION

A closed-circuit television subsystem for use by the crew in monitoring the internal and external scenes in real times is to be provided. A portable near commercial quality television subsystem capable of real time and high resolution picture transmission shall also be provided with consideration given to televising the lunar excursion module launch.

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

CONTRACTORS

System: RCA

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Lunar Excursion Module Communications

RELIABILITY DOCUMENTATION

Functional Subsystem: Lunar Excursion Module Communications (03 06 06)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis	N/A	N/A
7. Maintainability Plan - Flight		X
8. Reliability Apportionments	March 1963	
9. Reliability Model	March 1963	
10. Quarterly Reliability Reports	March 1963	
11. Test Results		X

Notes:

- 1.
- 2.
- 3.
- 4.

Lunar Excursion Module Communications

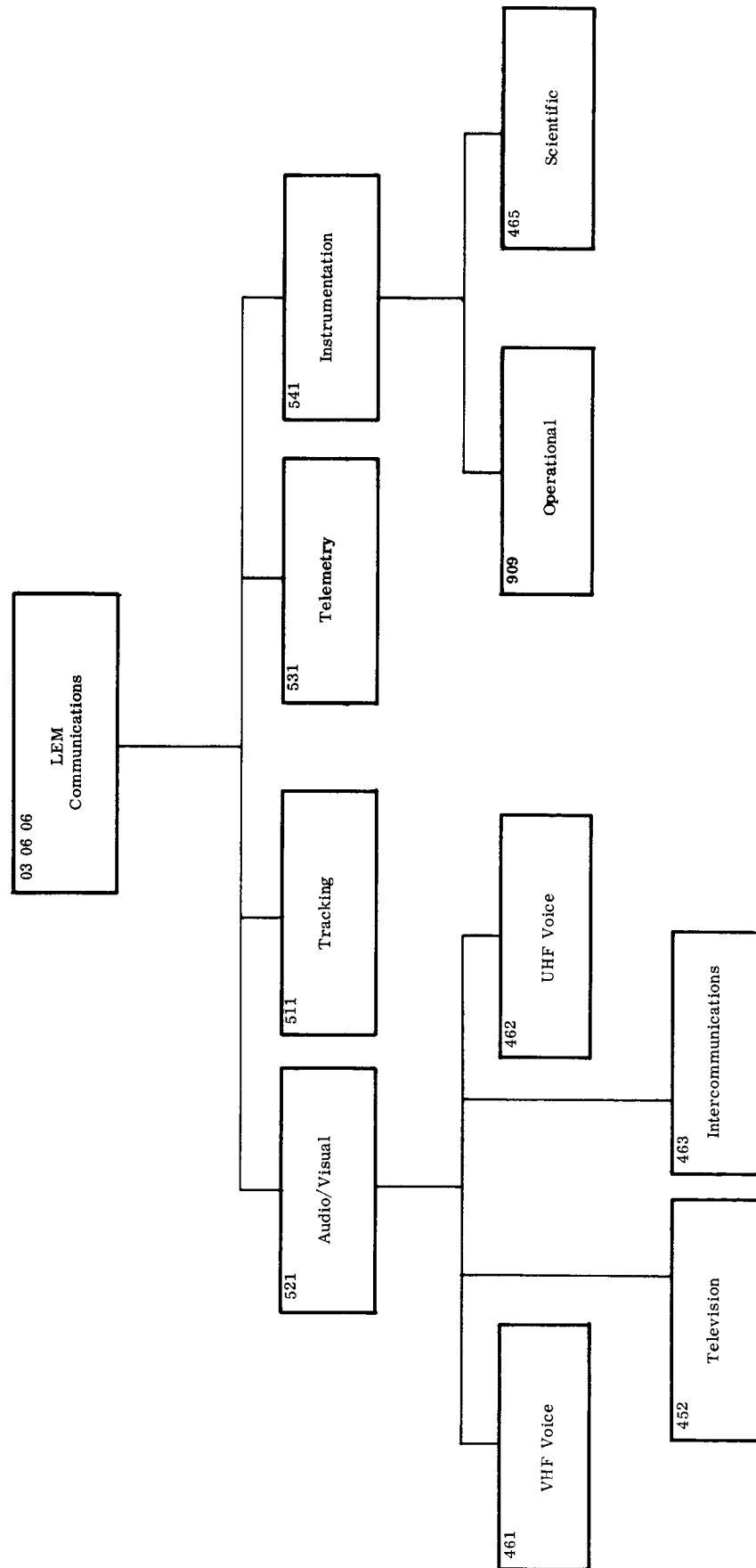


Figure 17-6. Lunar Excursion Module Communications Block Diagram

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Lunar Excursion Module Crew System

LUNAR EXCURSION MODULE CREW SYSTEM (CODE: 03 06 07)

Further definition required.

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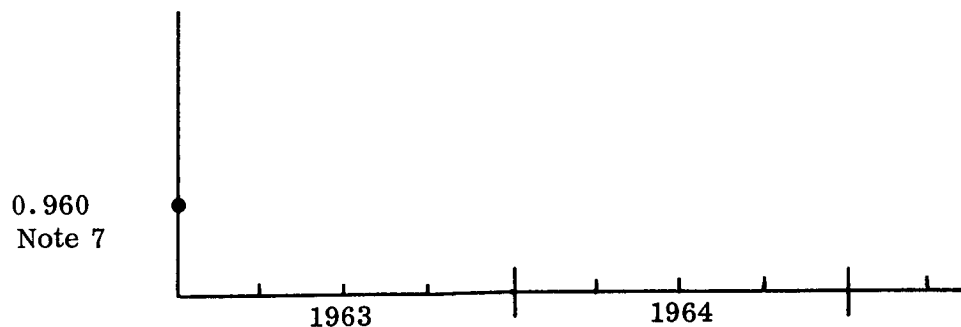
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SECTION 18
SERVICE MODULE

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RELIABILITY: Allocated ● Predicted ○ Achieved x
(CM/SM)



RELIABILITY

Functional Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Propulsion R&C System	01	0.999968	0.997833	}	—	2, 3
Elec. Pwr.	02	0.998953	0.9941		2.0	1, 2, 4, 6
Structures	03	0.999926	0.999947		—	3
ECS	04	0.997675	0.9805		6.7	1, 6
Guidance S&C System	05	0.998901	≅ 0.88		27.0	1, 5, 6
		0.994558	≅ 0.52			
Communications (Instrumentation)	06				—	
Crew Systems	07				—	

Notes:

1. Allocated: NAA 62-557-5
2. Allocated: NAA 62-557-4
3. Predicted: NAA 62-557-4
4. Includes CM Components in Predicted Value
5. MIT R395
6. Engineering Estimate for Illustration
7. NASw-410-61-14-01

SECTION 18

SERVICE MODULE (CODE: 03 07)

DESCRIPTION

FUNCTION

The service module (see Figure 18-1) is a major component of the spacecraft, containing the primary propulsion system and other spacecraft hardware requiring neither direct access by the crew nor use during re-entry. The communication and instrumentation subsystem is considered functionally part of the command module.

CONTRACTORS

Prime Contractor - MSC/North American Aviation

Structure - Grumman

Environmental Control - AiResearch

Electrical Power - Pratt and Whitney

Propulsion - Aerojet General

Reaction Control - Marquardt

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

Systems aboard the service module are functionally part of the command module. Their reliability must therefore be analyzed and presented in this relationship.

Service Module Description

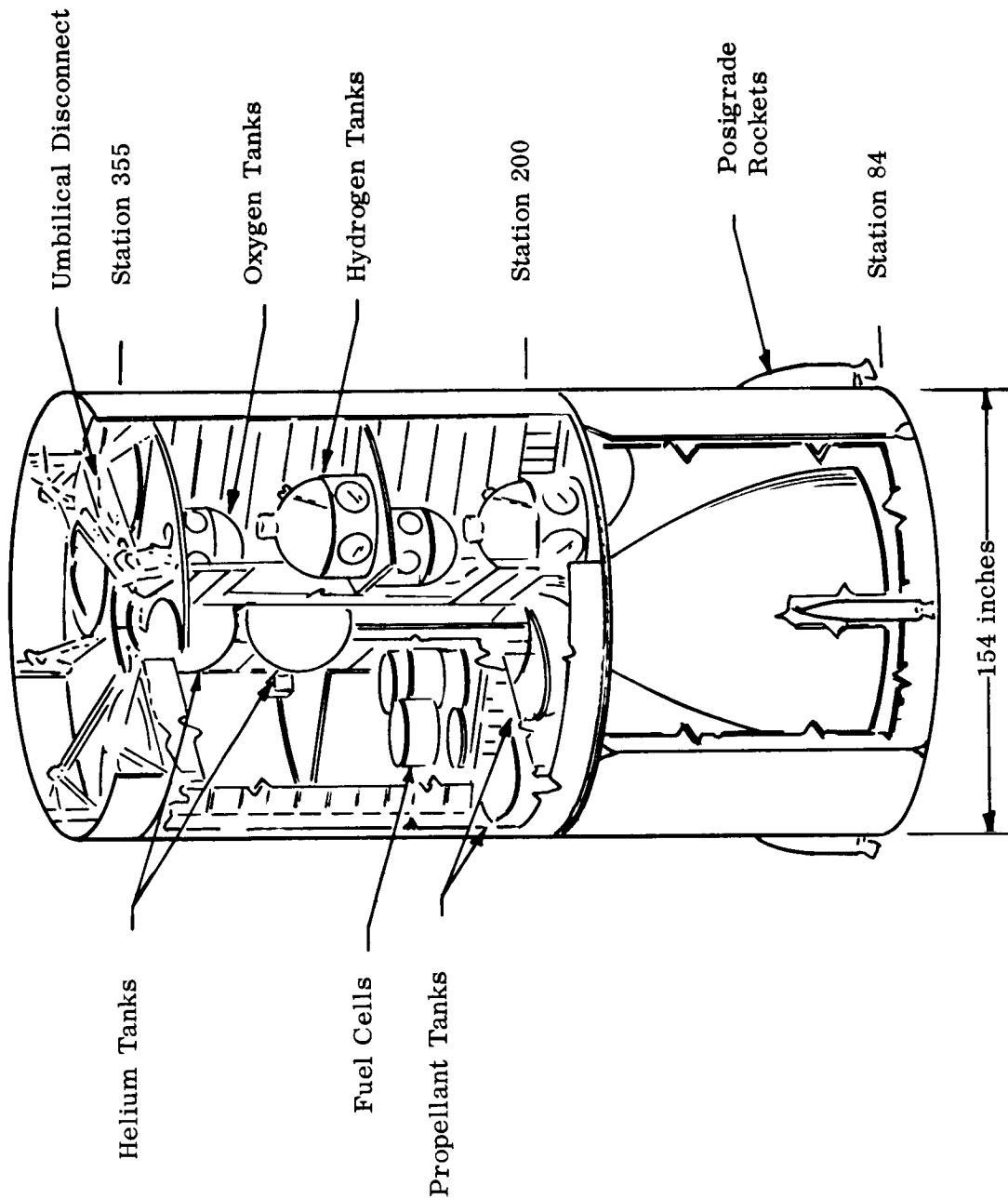


Figure 18-1. Service Module Structural Configuration

RELIABILITY DOCUMENTATION

Subsystem: Service Module

	Center Submittals Received	
	Yes	No
1. Design Specifications	1	
2. Top Drawings		X
3. Failure Effect Analysis	1	
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments	1	
9. Reliability Model	1	
10. Quarterly Reliability Reports	1	
11. Test Results		X

Notes:

1. Partial information is available, largely contained in NAA 62-557 (Quarterly Reliability Reports).
- 2.
- 3.
- 4.

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Service Module Propulsion System

RELIABILITY: Allocated ● Predicted ○ Achieved x

RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Engine System	001						
Propellant Transfer and Pressurization	011						
Vector Control	021						
Pneumatic Control	041						
Ignition	051						
Propellant Utilization	071						
Reaction Control	081	0.99997	0.999989				1
Ordnance	061						

Notes:

1. NAA 5th Report, page 3-74.
- 2.
- 3.
- 4.

PROPULSION SYSTEM (CODE: 03 07 02)

FUNCTION

The service module propulsion system includes a main engine and a reaction control engine. Both systems use the hypergolic propellant combination 50-50 UDMH/ N_2O_4 . The main engine uses pressure-fed propellants and is gimbaled. It has multiple re-start capability and develops a nominal thrust of 21,900 pounds in vacuum. Ullage (propellant seating function) for main engine start is supplied by the reaction control engine system which uses bladder-fed propellants. The reaction control engine system is capable of operating in the continuous as well as the pulsed mode. Each reaction control system engine develops 100 pounds of thrust in vacuum.

The reaction control system is to be designed to have a complete redundant capability which includes the requirement that two of four quad engine arrangements work.

MAJOR CONTRIBUTORS TO UNRELIABILITY

One factor stands out above all others in contributing to service propulsion system unreliability. It is the use of the main engine and reaction control engine system during an extended period of time during which multiple restarts are required. The propellant-expulsion bladders used in the reaction control propulsion system are in contact with damaging propellants during the entire command module use and standby time. Valve seats in both the command module main engine system and reaction control engine system are exposed to propellants as soon as the burst diaphragms, which serve to isolate the propellant tanks from the rest of the system, are ruptured. Furthermore, it is doubtful that specific impulse requirements for the main engine can be met because of combustion instability and subsequent erosion.

RELIABILITY TRENDS

There is little reason to expect large increases in state-of-the-hardware components as compared to state-of-the-art components. However, considerable improvement can be expected as a result of design improvements which have been incorporated in the service module propulsion system. Nonetheless, it is hard to see how a crew-safety-reliability goal of 0.9998 can be achieved within the next few years. The difficulties are well-stated by the excerpts taken from Quarterly Reliability Status Report

Service Module Propulsion System

SID 62-557-5 issued on 31 May 1963 by North American, although the NAA numbers might not stand close scrutiny. This report states:

Two major problem areas within the service module propulsion system that have become apparent are the inability of the present configuration to meet crew safety requirements and the increasing difficulty of expecting engine reliability improvement commensurate with Apollo requirements. The first was caused primarily by the change to the LOR operational concept, and the second is the inability of the subcontractor to achieve performance goals.

NAA specifically means chamber erosion and combustion instability as difficulties. Either specific impulse is low or excessive erosion occurs.

STATE-OF-THE-ART PREDICTION MODEL

A state-of-the-art prediction model is shown in Figure 18-2. It is not based on the exact hardware configuration expected but on observations of the reliability of similar systems for a single start-run-shutdown sequence. However, the requirement that only two of four quads of reaction control engines are required was taken into account.

STATE-OF-THE-HARDWARE PREDICTION MODEL

A state-of-the-hardware prediction model is being prepared as rapidly as engineering information and test stand data are made available from the centers, within the constraints imposed by manpower limitations. This model will undoubtedly predict a higher reliability figure than the state-of-the-art model but it will not meet apportioned reliability requirements. (See Figure 18-3.)

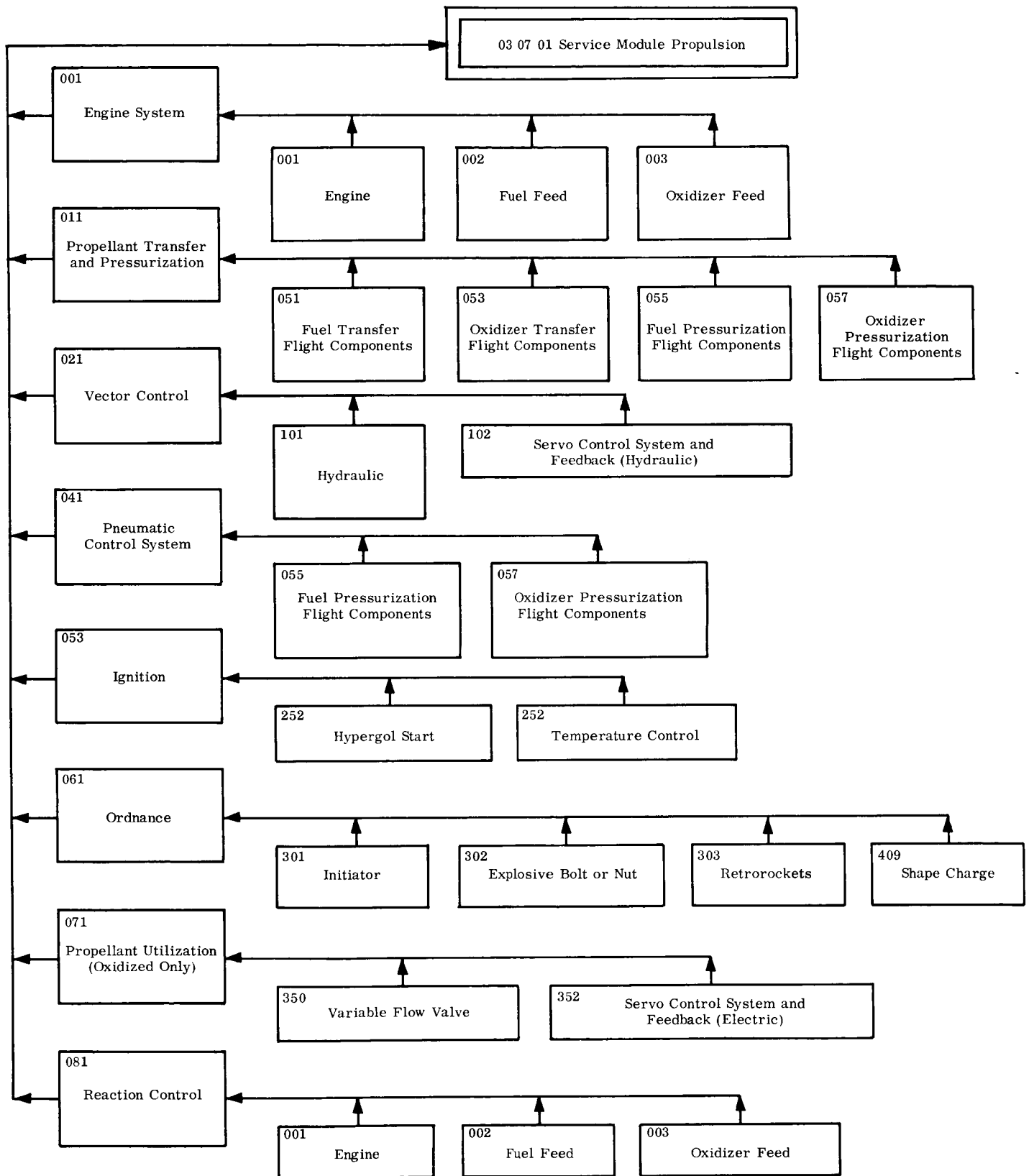


Figure 18-2. State-of-the-Art Model

Service Module Propulsion System

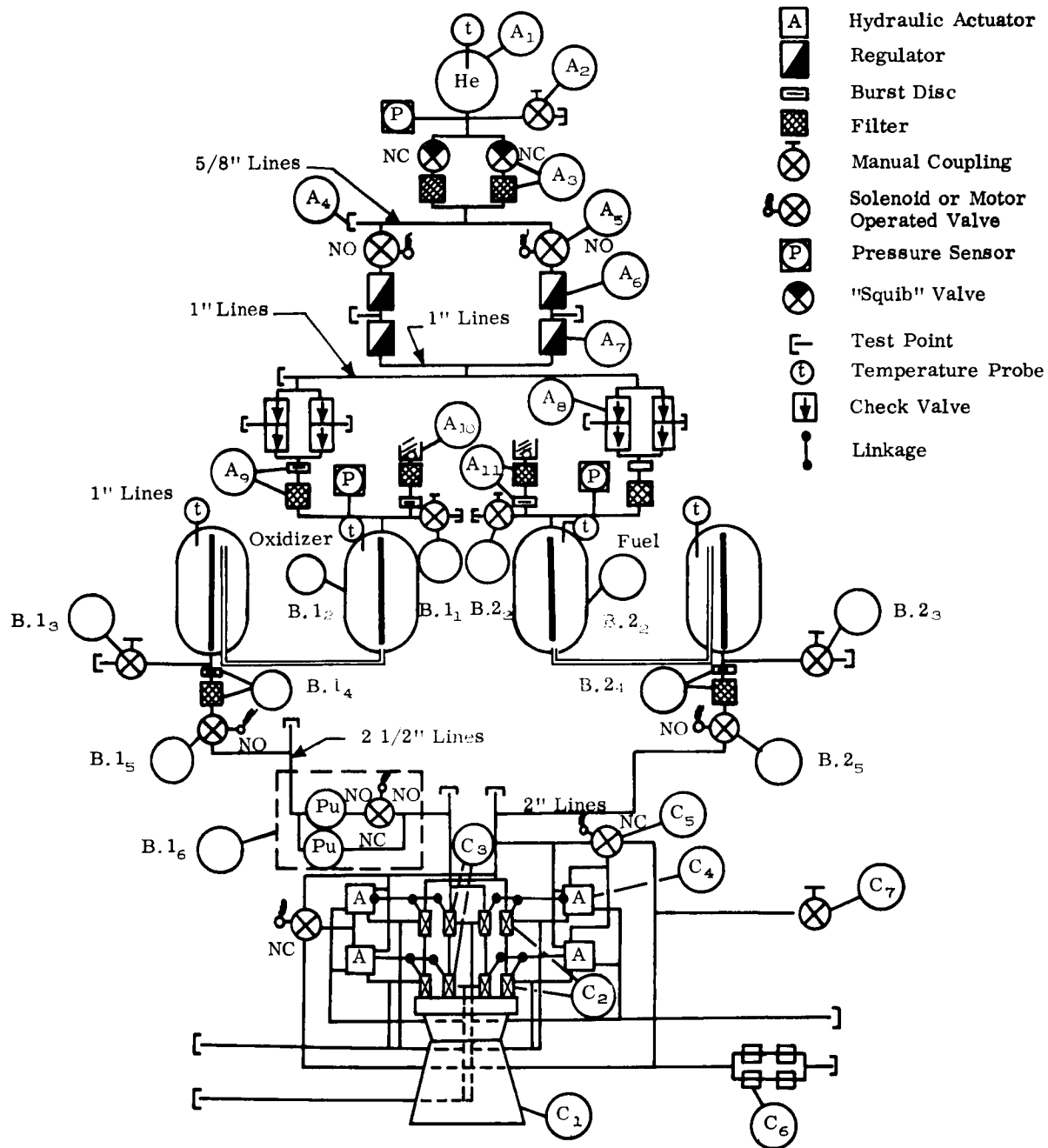


Figure 18-3. Service Module Propulsion System Schematic

RELIABILITY DOCUMENTATION

Functional Subsystem: Service Module Propulsion

	Center Submittals Received	
	Yes	No
1. Design Specifications		
2. Top Drawings		
3. Failure Effect Analysis		
4. Criticality Analysis		
5. Performance Analysis		
6. Structural Analysis		
7. Maintainability Plan		
8. Reliability Apportionments	1	
9. Reliability Model		
10. Quarterly Reliability Reports	1	
11. Test Results		

Notes:

1. These and partial coverage of other items contained in NAA 62-557.
- 2.
- 3.
- 4.

Service Module Electrical Power System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Power Sources	116						
Distribution	121						

Notes:

- 1.
- 2.
- 3.
- 4.

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Service Module Electrical Power System

SERVICE MODULE ELECTRICAL POWER SYSTEM (CODE: 03 07 02)

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Service Module Electrical Power System

RELIABILITY DOCUMENTATION

Functional Subsystem: Service Module Electrical Power

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

1. Information not available as of 15 September 1963.
- 2.
- 3.
- 4.

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Service Module Structures

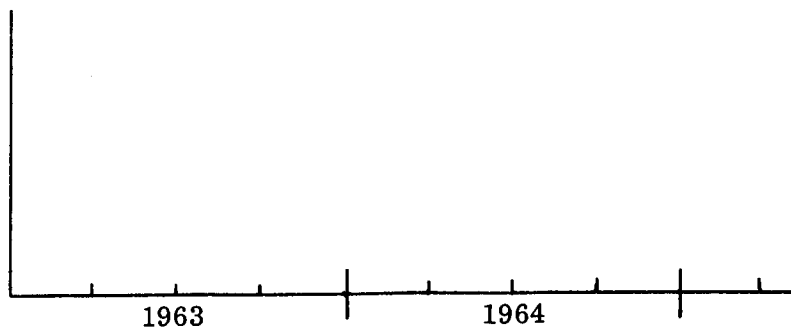
SERVICE MODULE STRUCTURES (CODE: 03 07 03)

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Service Module Environmental Control System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
H ₂ O Glycol circuit	302						
O ₂ Storage	306						
Radiator	307						
Water Supply	316	0.99949					1
O ₂ Supply	311	0.999884					1
Radiator (Crew)	336						
Suit Control	—	0.99949					1
H ₂ O Glycol	—	0.999133					1

Notes:

1. NAA information; systems definition not presently identical.
- 2.
- 3.
- 4.

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Service Module Environmental Control System

SERVICE MODULE ENVIRONMENTAL CONTROL SYSTEM (CODE: 03 07 04)

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Service Module Environmental Control System

RELIABILITY DOCUMENTATION

Functional Subsystem: Service Module Environmental Control

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis	1	
4. Criticality Analysis		X
5. Performance Analysis	1	
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments	1	
9. Reliability Model		X
10. Quarterly Reliability Reports	1	
11. Test Results		X

Notes:

1. The service module system is functionally a part of the command module ECS system; documentation status is therefore similar.
- 2.
- 3.
- 4.

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Service Module Communications

SERVICE MODULE COMMUNICATIONS (CODE: 03 07 06)

Combined with Command Module Communications, Section 19.

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SECTION 19

COMMAND MODULE

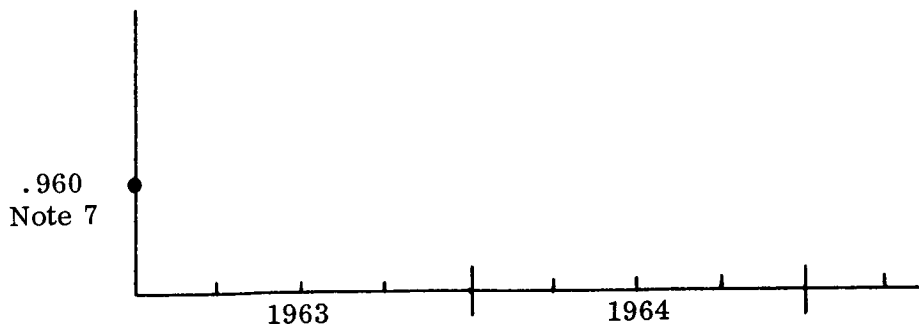
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Command Module Description

RELIABILITY: Allocated ● Predicted ○ Achieved x
(CM/SM)



RELIABILITY

Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Propulsion						
RCS	01	0.000068	0.997833		—	2, 3
EPS	02	0.998853	0.9941		2.0	1, 2, 4, 6
Structures	03	0.999926	0.999947		—	3
ECS	04	0.997675	0.9805		6.7	1, 6
Guidance	05	0.998901	0.88			1, 5, 6
SCS		0.994558	0.52		27.0	
Communica- tions (Instru- mentation)	06				—	
Crew Systems	07				—	
Earth Landing		0.99994	0.99994		0.2	2, 3, 6

Notes:

1. Allocated: NAA 62-557-5
2. Allocated: NAA 62-557-4
3. Predicted: NAA 62-557-4
4. Includes SM components in predicted value.
5. MIT R395
6. Engineering estimate for illustration.
7. NASw-410-61-14-01

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SECTION 19

COMMAND MODULE (CODE: 03 08)

DESCRIPTION

FUNCTION

The command module (see Figure 19-1) provides the control and communications center for the entire mission. It also houses and protects the crew. Its operation depends upon the integrated performance of all the functional subsystems listed in the reliability chart as well as portions of functional subsystems in other modules. Electrical power, communications, guidance, and the environmental control system are all related to equipment in the service module and the LEM.

CONTRACTORS

Prime Contractor - MSC/North American Aviation

Structural System - NAA

Environmental Control and Life Support - NAA/AiResearch

Electrical Power - NAA

Communications and Instrumentation - NAA/Collins

Guidance - MIT/IL; Minneapolis-Honeywell

Propulsion/Reaction Control - NAA/Marquardt

MAJOR CONTRIBUTORS TO UNRELIABILITY

Investigation to date indicates that the communications and guidance systems are the chief command module contributors to the unreliability of the mission. A major reason for the unreliability which occurs is the long period of use and number of components. Both systems have considerable backup equipment aboard the command module and in the associated systems within the service module and the LEM. The guidance and communication equipment is designed in modular form to allow a certain degree of inflight maintenance. The reliability predicted is based not only upon straight equipment functional reliability but must consider the maintainability designed into the equipment. Although the environmental control system is extremely complex and must operate for the entire mission duration, its estimated reliability is reasonably high because of the large number of available alternate modes of operation.

Command Module Description

RELIABILITY DOCUMENTATION

Subsystem: Command Module

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis	1	
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments	1	
9. Reliability Model	1	
10. Quarterly Reliability Reports	1	
11. Test Results		X

1. Data presently available is derived largely from NAA 62-557 (Quarterly Reliability Reports) and from the Apollo System Description.

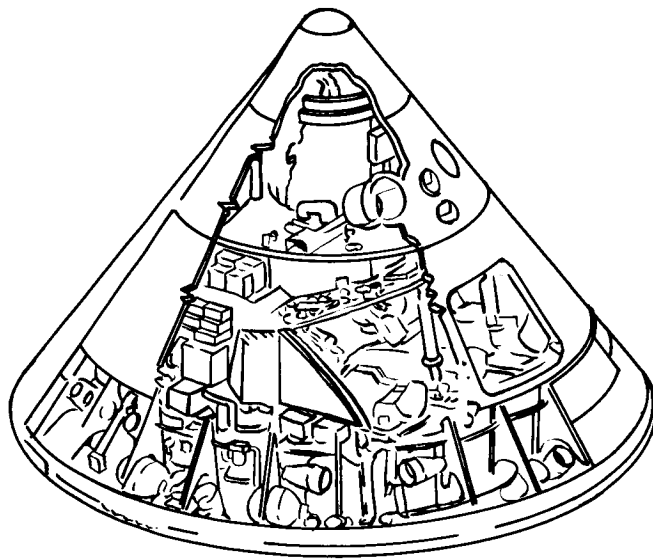


Figure 19-1. Command Module Inboard Profile

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Command Module Propulsion

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Reaction Control	081	0.999960	0.999560				1
Ignition	051		0.9994				2
Pneumatic Control	041						
Ordnance	061						

Notes:

1. NAA 5th Report, page 3-63.
2. Manned No. 3 Propulsion System Reliability Estimate, page 6-2, 15 December 1962.
- 3.
- 4.

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COMMAND MODULE PROPULSION (CODE: 03 08 01)

FUNCTION

The command module (see Figure 19-2) has a reaction control system only. It is to be used after jettison of the service module. It will be used for re-entry or abort to maintain attitude control. The reaction control system has a complete redundant capability.

Engines are capable of either a pulsed or a continuous mode of operation. Each engine can generate 100 pounds of thrust with a specific impulse of 300 seconds.

The propellants are 50-50 UDMH/ N_2O_4 and, of course, are hypergolic and storable. They are pressure fed.

CONTRACTORS

MAJOR CONTRIBUTORS TO UNRELIABILITY

None

RELIABILITY TRENDS

STATE-OF-THE-ART RELIABILITY

Command Module Propulsion

RELIABILITY DOCUMENTATION

Functional Subsystem: Command Module Propulsion

	Center Submittals Received	
	Yes	No
1. Design Specifications	May 1963	x
2. Top Drawings		x
3. Failure Effect Analysis		
4. Criticality Analysis		x
5. Performance Analysis		x
6. Structural Analysis		x
7. Maintainability Plan		x
8. Reliability Apportionments	May 1963	
9. Reliability Model	May 1963	
10. Quarterly Reliability Reports	May 1963	
11. Test Results		x

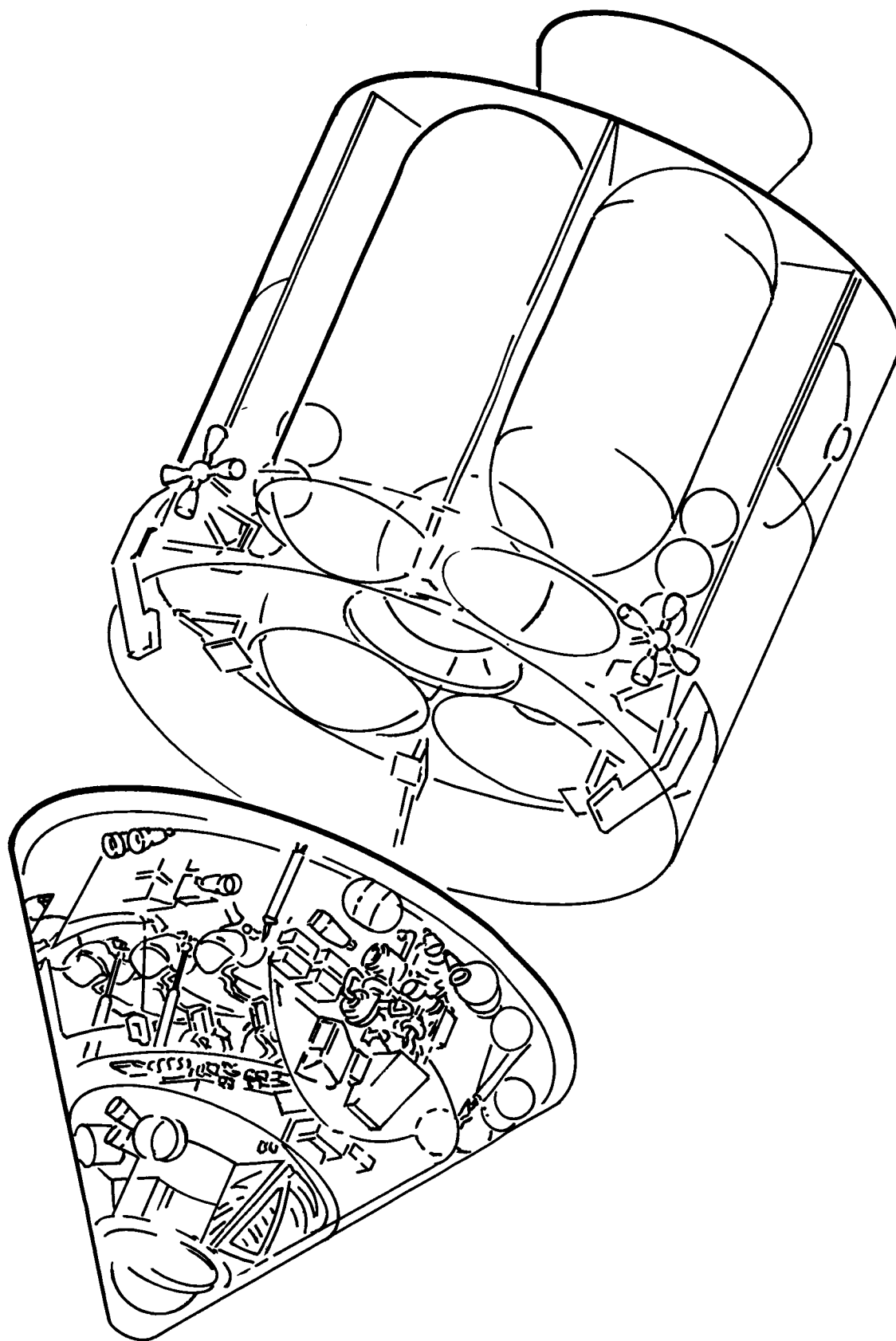


Figure 19-2. Propulsion and Recovery Systems

COMMAND MODULE/SERVICE MODULE ELECTRICAL POWER SYSTEM

FUNCTION

The command module/service module power system (see Figure 19-3) is an integrated but separable system for the supply of the command module electrical power demands during its mission use. Major power requirements are met by the fuel cells carried in the service module, but various batteries for specific uses supplement this power source. The service module portions of the power system function until that unit is jettisoned prior to re-entry. Thereafter, the command module power requirements are met by onboard batteries, which include units for the specific purpose of providing post landing power needs.

Requirements for alternating current power are met by inverters supplied from the dc sources. Separate distribution systems, of course, are required. See Figures 19-3 through 19-7 for additional information.

Analysis of the reliability of this system is relatively complicated for several reasons. First, the systems in the two modules are interdependent. Second, there is a wide variability in the system configurations possible by means of switching to accomplish the varied mission functions or to meet emergency abort requirements. The third and primary difficulty is in the lack of specific information. Recently available reliability analyses have shed considerable light on the system, but actual schematic and specification data still are lacking. Information supplied is, therefore, not substantiated by adequate documentation.

CONTRACTORS

Entry and Post-Landing Battery - Eagle-Picher

Battery Charger - ITT Industrial Products Division

Distribution System - NAA

CM/SM Umbilical -

S/L Sequencer - NAA

Static Inverter - Westinghouse

Interior Illumination and Advisory System - NAA

SM Electrical Distribution System - NAA

SM/GSE Umbilical -

Adapter Interface Connector -

CM/SM Electrical Power System

CM-LET Umbilical -

Forward Pressure Bulkhead Electrical Feedthrough -

Aft Pressure Bulkhead Electrical Feedthrough -

Fuel Cell Power Plants - Pratt and Whitney

Electrical Power System, LET - NAA

MAJOR CONTRIBUTORS TO UNRELIABILITY

In common with experience on previous programs, there is predictable difficulty to be encountered with the inverter systems. In view of the incomplete information now available, specific recommendations are not appropriate.

RELIABILITY TRENDS

Although some reliability predictions are available from NAA 62-557, little current information is available to provide system schematics and specifications.

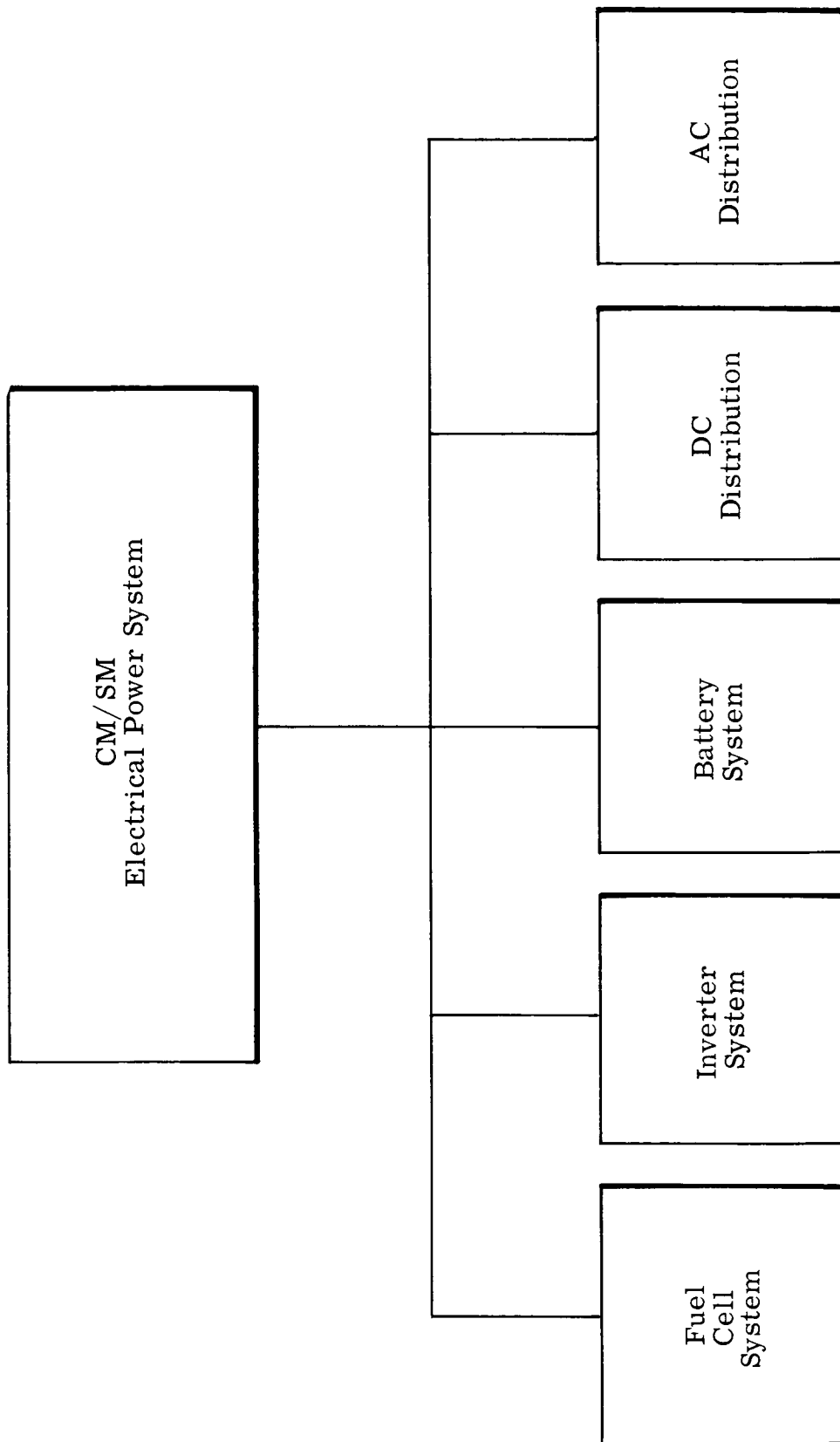


Figure 19-3. Command Module/Service Module Electrical Power System Block Diagram

Command Module Electrical Power System

RELIABILITY DOCUMENTATION

Functional Subsystem: Command Module Electrical Power

	Center Submittals Received	
	Yes	No
1. Design Specifications		2
2. Top Drawings		2
3. Failure Effect Analysis	1	
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		Not Applicable
7. Maintainability Plan		X
8. Reliability Apportionments	1	
9. Reliability Model	1	
10. Quarterly Reliability Reports	1	
11. Test Results		X

1. NAA 62-557.

2. Electrical power system specification information not available as of 15 September 1963.

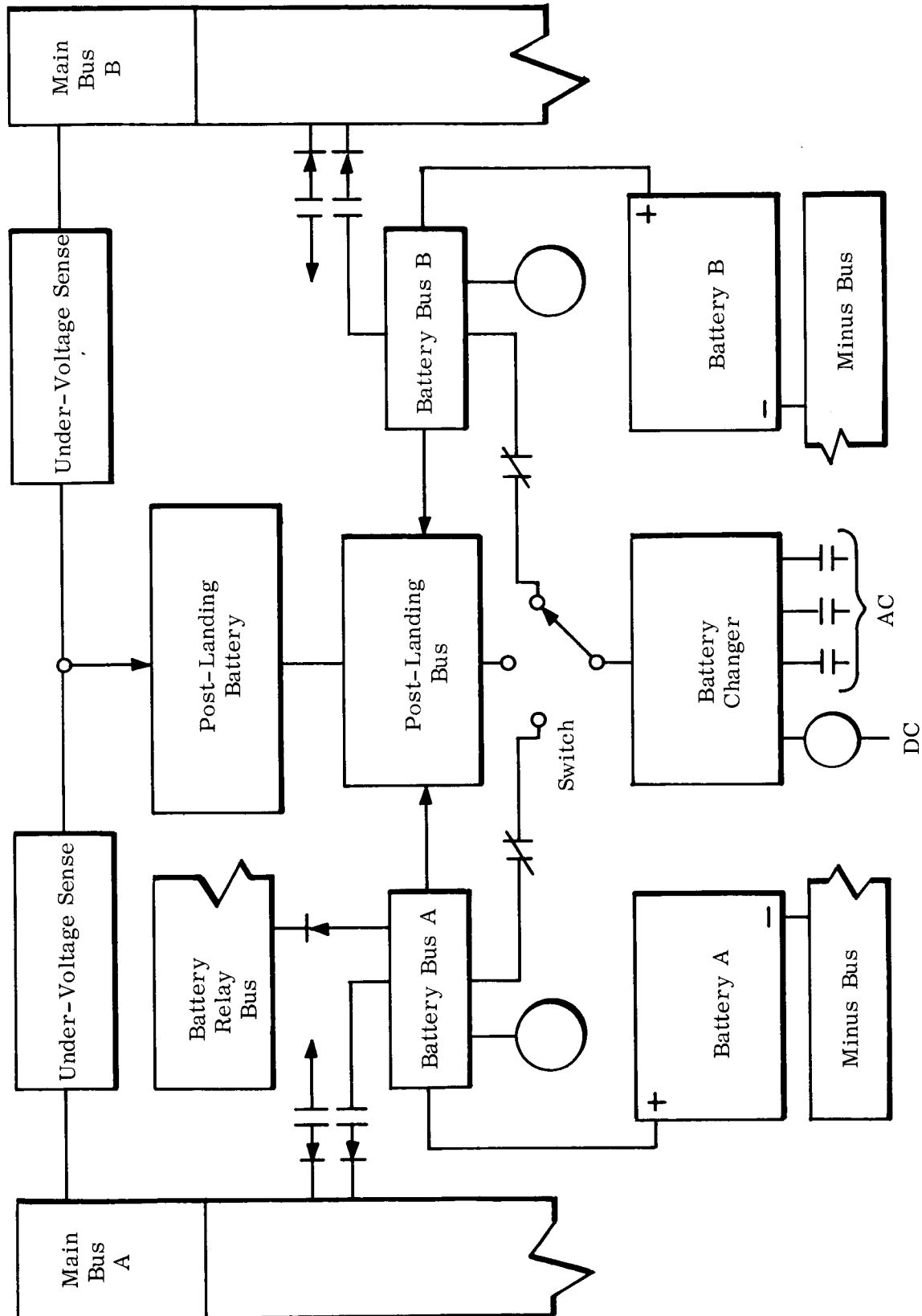


Figure 19-4. Command Module/Service Module Battery System

Command Module Electrical Power System

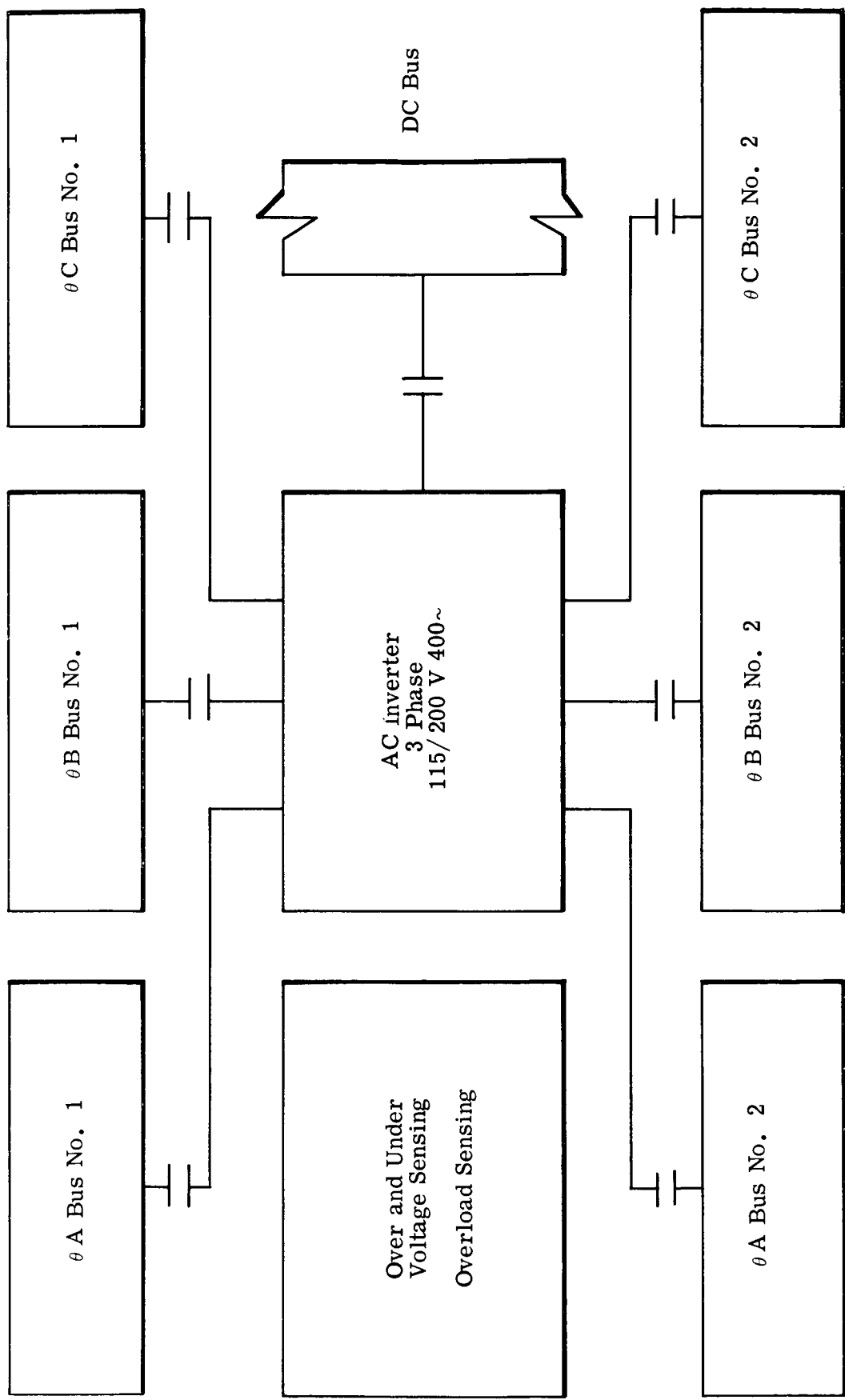


Figure 19-5. Command Module/Service Module AC Power

Command Module Electrical Power System

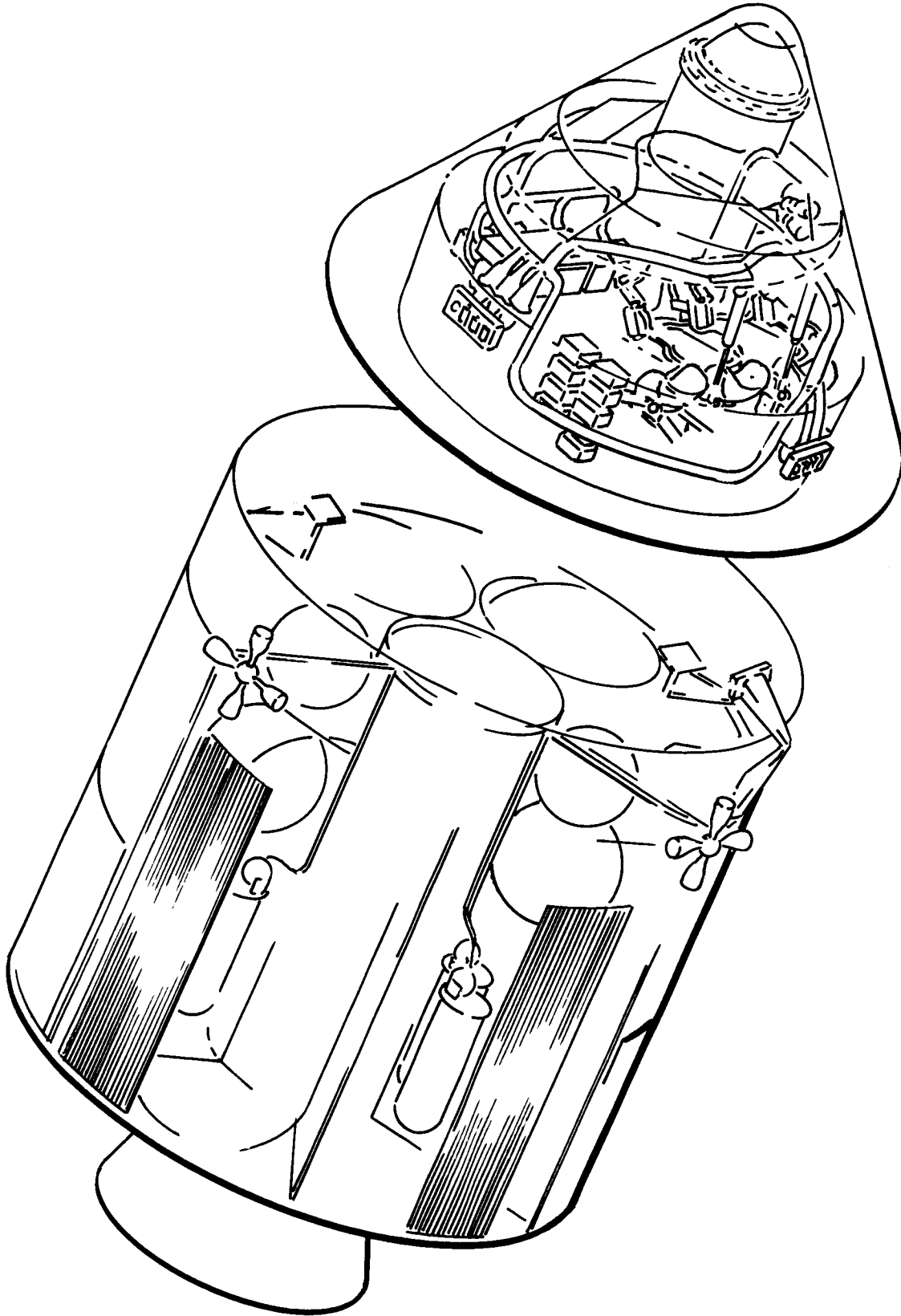


Figure 19-6. Electrical Systems

Command Module Electrical Power System

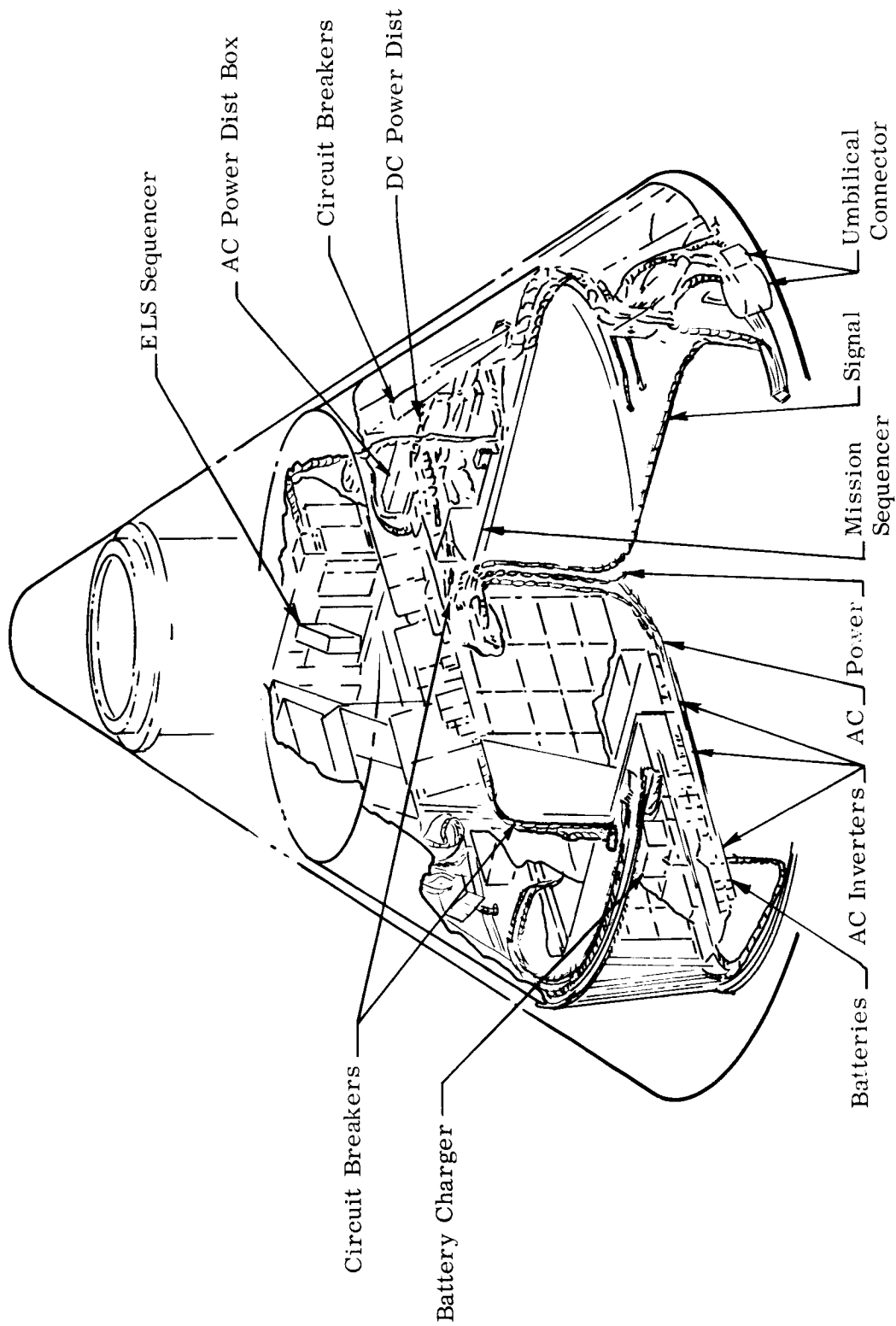


Figure 19-7. Command Module Electrical Components

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Command Module Structures

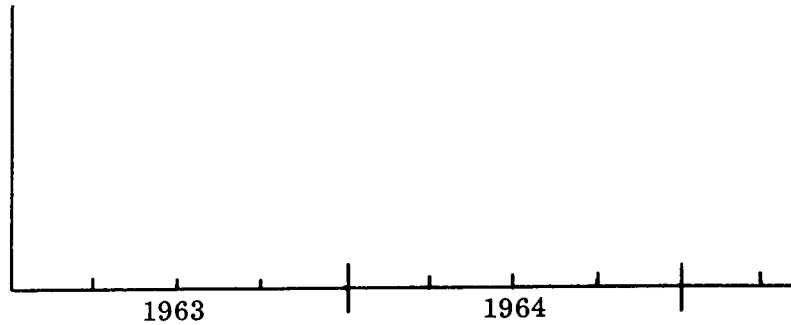
COMMAND MODULE STRUCTURES (CODE: 03 08 03)

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D R A F T

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CM/SM Environmental Control System

RELIABILITY: Allocated ● Predicted ○ Achieved x

RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Suit Control		0.99949					
H ₂ O Glycol		0.999133					
Pressure and Temperature Circuit		0.999812					
O ₂ Supply		0.999854					
H ₂ O Supply		0.99949					

Notes:

1. NAA Document 62-557-5.
- 2.
- 3.
- 4.

CM/SM ENVIRONMENTAL CONTROL SYSTEM (CODE: 03 08 04)

FUNCTION

The environmental control system (see Figure 19-8) will provide conditioned temperature and pressure for crew shirt-sleeve habitation of the command module and oxygen for metabolic use. The subsystem comprises five loops.

- a. Suit Circuit provides oxygen for metabolic use that has been temperature-conditioned, dehumidified, and treated for removal of odors and carbon dioxide.
- b. Water Glycol Circuit acts as a heat transport medium for metabolic heat generated by the crew and heat generated by onboard equipment. (Water glycol flows in a closed path from the command module to the service module where heat is rejected by space radiation, and the cool fluid is then returned to the command module where the cycle is repeated.)
- c. Pressure and Temperature Circuit provides a 5-psia atmosphere to the command module interior, maintained at a temperature of approximately 70°F.
- d. Oxygen Supply System supplies the command module suit circuit and pressure temperature control system with the oxygen necessary to satisfy metabolic requirements of the crew and replaces oxygen lost by command module leakage.
- e. Water Management System receives and stores the potable water generated by the fuel cells as a byproduct and the metabolic waste water generated by the crew. The water stored in two tanks, potable and waste, is then available separately for consumption by the crew or for supplementary cooling during high heat loads in high thermal radiation environment.

CONTRACTORS

AiResearch

MAJOR CONTRIBUTOR TO UNRELIABILITY

RELIABILITY TRENDS

CM/SM Environmental Control System

RELIABILITY DOCUMENTATION

Functional Subsystem: CM/SM Environmental Control System

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis	1	
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments	1	
9. Reliability Model		X
10. Quarterly Reliability Reports	1	
11. Test Results		X

1. Partial NAA information available.

CM/SM Environmental Control System

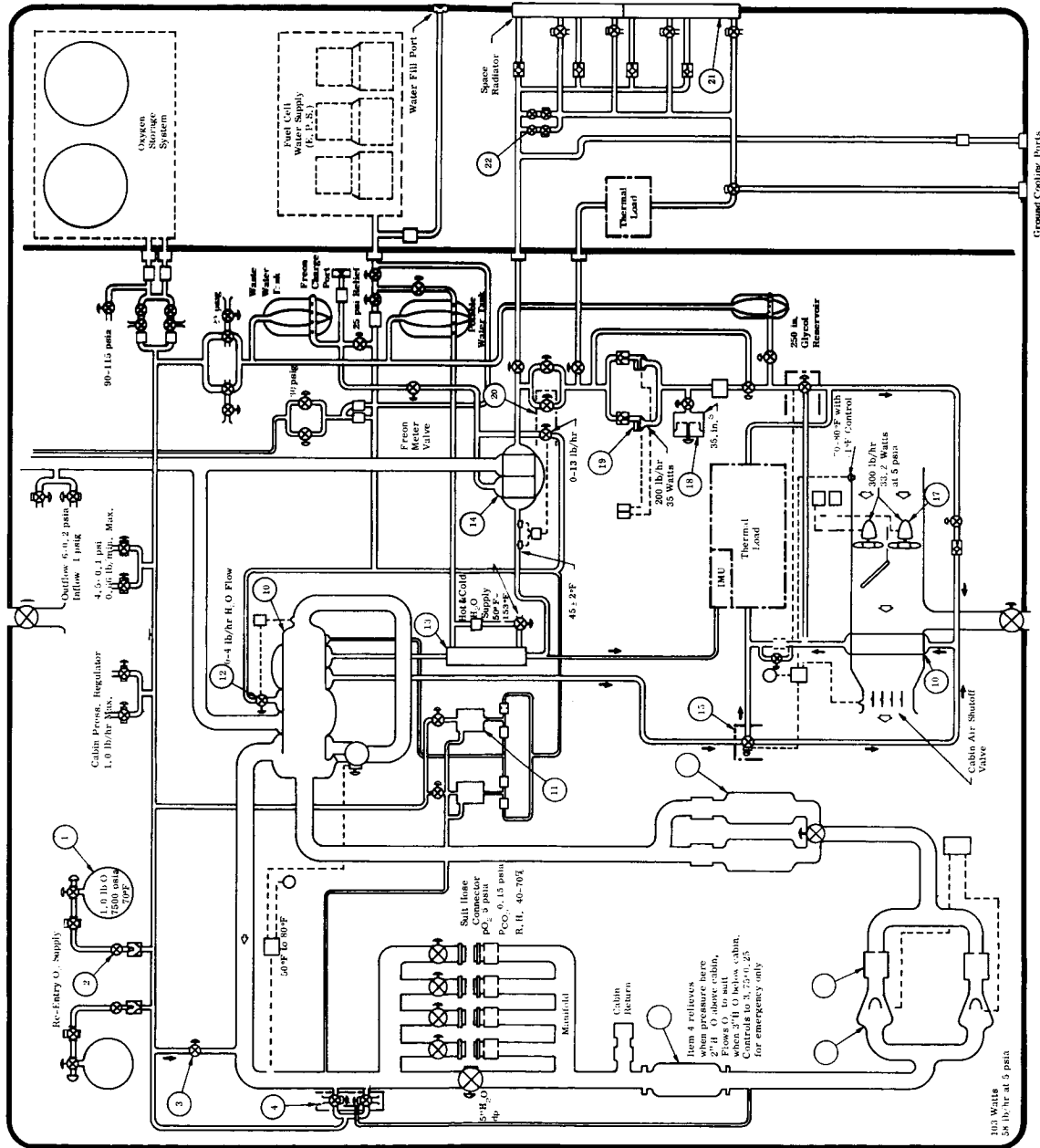
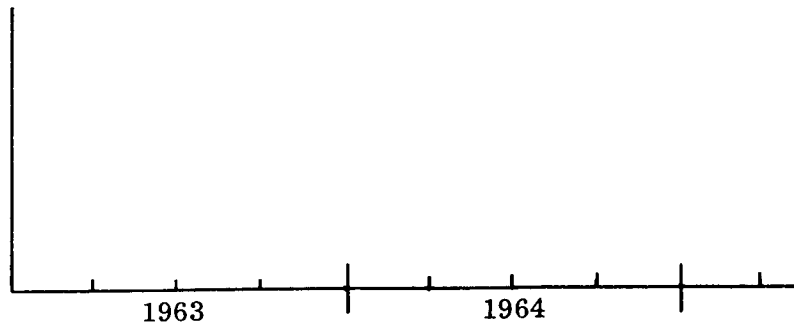


Figure 19-8. CM/SM Environmental Control System

CM/SM Communication

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Audio/Visual	521	0.997	0.937				1
Telemetry	531						
Instrumentation	541						
Command	501						

Notes:

1. NAA 62-557-5.
- 2.
- 3.
- 4.

COMMAND MODULE COMMUNICATIONS (CODE: 03 08 06)

VOICE

Two-way voice communication capability (see Figure 19-9) will be provided between the individual crew members, between the command module and earth based stations, and between each module in a rendezvous maneuver. A personal communication system will provide two-way voice communication between crew members whether internal or external to the command module. An intercommunication (plug-in) system will be supplied. Reliable communication in the near earth phase of flight shall be afforded by a UHF link to that range at which DSIF communications can be acquired and maintained for all potential flight paths. Voice communication using the UHF DSIF transponder will provide reliable voice transmission and reception to lunar distance.

TELEMETRY

A flexible pulse code modulation telemetry subsystem that is compatible with both the VHF and UHF transmission systems will be provided. Initial telemetry and display system design will be flexible enough for the addition of ground spacecraft data link.

TELEVISION

A closed-circuit television subsystem will be provided for use by the crew in monitoring internal and external scenes in real time. Optimum modulation will be used. Frame rate and resolution tradeoffs with transmitter power and antenna size will be optimized.

TRACKING TRANSPONDERS

A C-band transponder subsystem compatible with the NA/FPS-16 and equivalent radar will be provided. This subsystem will be capable of providing reliable tracking signals in the near earth phase of flight as far as the range at which DSIF tracking can be acquired and maintained for all potential flight paths. A UHF transponder that provides reliable velocity and range tracking to lunar distance when used with the DSIF will be supplied.

RADIO RECOVERY AIDS

The radio recovery aids subsystem will consist of an HF transceiver system which may be either voice or tone modulated, and a VHF beacon.

CM/SM Communications

ANTENNAS

The near-earth antenna system will consist of multiple flush-mouthed antennas which essentially provide omnidirectional patterns in a plane that is perpendicular to the booster longitudinal axis of the booster. A similar antenna compatible with DSIF will be used at minor deep space distances. This antenna will offer sufficient gain to permit the reliable transfer of priority information at a reduced bandwidth in an emergency condition up to lunar distances. The directional antenna system will be designed to withstand the stresses to which it will be subjected throughout the mission or it will be retractable for periods of high stress. Both manual and automatic antenna steering will be provided for the directional antenna.

OPERATIONAL INSTRUMENTATION

The system operational instrumentation systems will detect, measure, and display all parameter required by the crew for monitoring and evaluating the integrity and environment of the spacecraft, and the performance of the spacecraft systems. It will provide data for transmission to earth to facilitate the ground assessment of spacecraft performance and failure analysis. It will provide the crew with the information required for abort decision. This system will also document the mission through photography and tape recording.

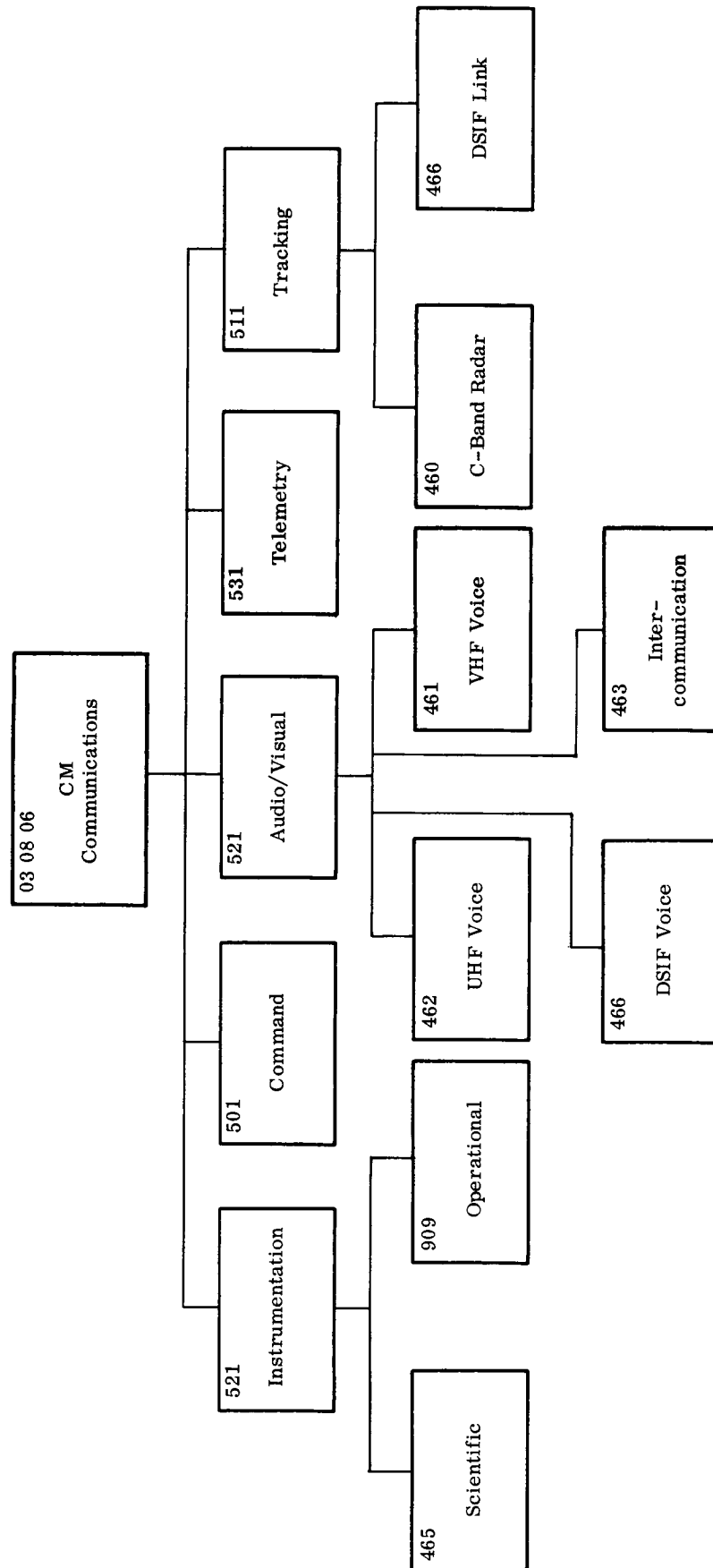


Figure 19-9. Command Module/Service Module Communication

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CM/SM Communication

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RELIABILITY DOCUMENTATION

Functional Subsystem: CM/SM Communications

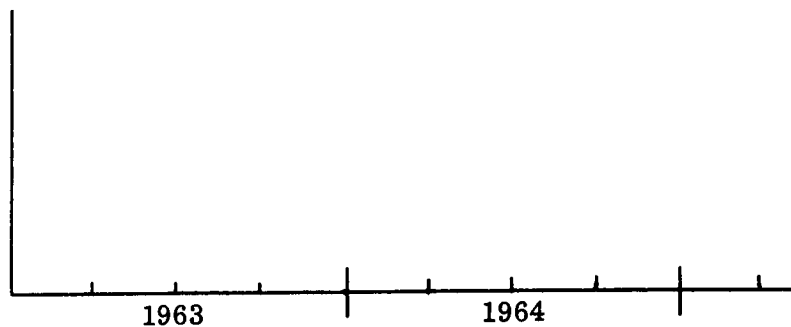
	Center Submittals Received	
	Yes	No
1. Design Specifications	Sept. 1962	
2. Top Drawings		x
3. Failure Effect Analysis	May 1963	x
4. Criticality Analysis	Sept. 1962	
5. Performance Analysis	N/A	N/A
6. Structural Analysis		x
7. Maintainability Plan		x
8. Reliability Apportionments	May 1963	
9. Reliability Model	May 1963	
10. Quarterly Reliability Reports	May 1963	
11. Test Results		x

Notes:

1. NAA 62-557 is the major source of numerical values; configuration and specification data are from the Apollo System Description.
- 2.
- 3.
- 4.

Command Module Crew Systems

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Personnel Protection and Support	621						
Waste Management	631						
Food and Water	641						
Personnel Hygiene, Health, and Comfort	651						
Lighting	151						
Survival Equipment	351						

Notes:

- 1.
- 2.
- 3.
- 4.

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Command Module Crew Systems

COMMAND MODULE CREW SYSTEMS (CODE: 03 08 07)

The equipment in these systems (see Figure 19-10) is as defined by NAA 62-557-5. Reliability data is not presently available. Some of the equipment is essentially identical with that contained in the LEM, and exists as a backup for these units in this arrangement.

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Command Module Crew Systems

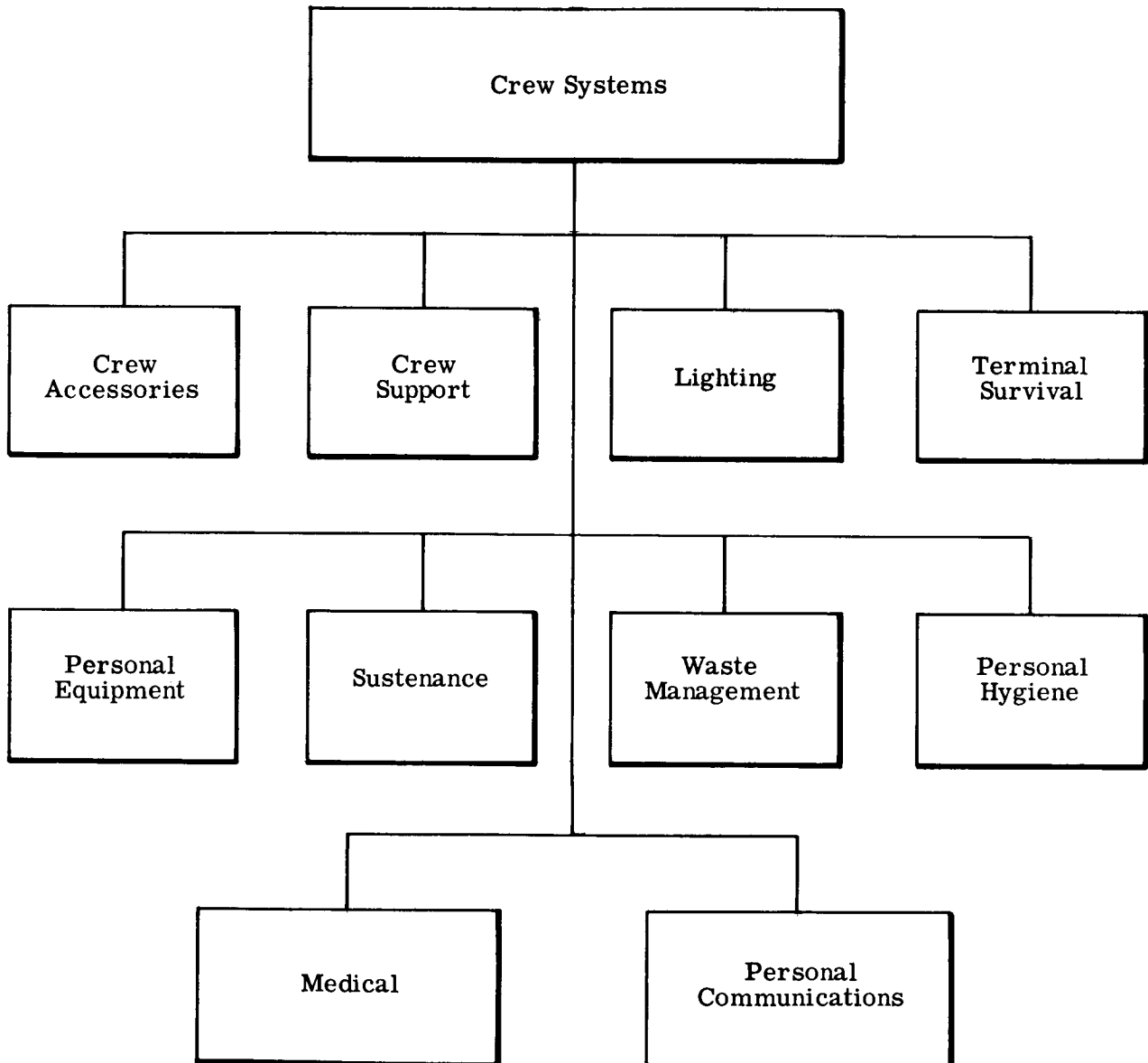


Figure 19-10. Command Module Crew Systems Block Diagram

RELIABILITY DOCUMENTATION

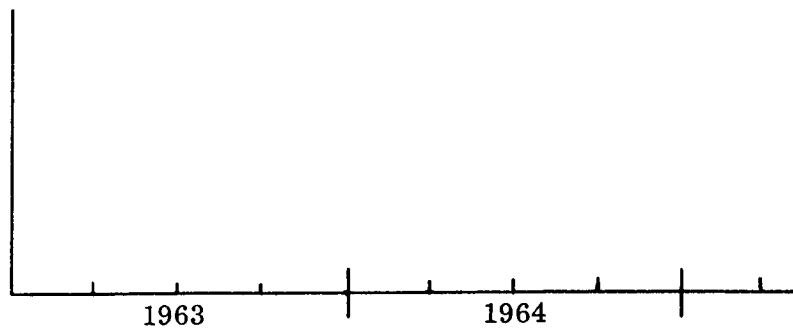
Functional Subsystem: Crew Systems

	Center Submittals Received	
	Yes	No
1. Design Specifications		1
2. Top Drawings		1
3. Failure Effect Analysis		1
4. Criticality Analysis		1
5. Performance Analysis		1
6. Structural Analysis		1
7. Maintainability Plan		1
8. Reliability Apportionments		1
9. Reliability Model		1
10. Quarterly Reliability Reports		1
11. Test Results		1

1. Partial information only.

Command Module Guidance and Navigation System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Inertial Measurement Unit	Not Applicable	Not Applicable					
Power and Servo Assy.							
Guidance Computer							
Coupling Display Units							
Sextant							
Scanning Telescope							
Map and Data Viewer							
Displays and Controls							
G&N		(1) 0.998901 ⁽²⁾	(1) ~ 0.88 ⁽³⁾				

Notes:

1. MIL/IL Report R-395 does not allocate or predict reliability to these major subsystems, nor to the LOR mission G&N allocation.
2. NAA Report SID 62-557-5.
3. MIL/IL Report R-395.
- 4.

COMMAND MODULE GUIDANCE AND CONTROL

FUNCTIONS

The guidance and control functions (see Figure 19-11) are accomplished by two interconnected systems, the guidance and navigation system, and the stabilization and control system. The integrated system, with crew participation, determines and directs all translational and rotational velocity changes required of the spacecraft to accomplish the mission.

The guidance and navigation system determines spacecraft position and velocity, calculates velocity changes required to adhere to the flight plan, and issues steering commands to the stabilization and control system to accomplish these velocity changes.

The stabilization and control system accepts translational and rotational commands from the guidance and navigation system or from the manual controls, and directs the primary propulsion thrust vector and/or the reaction jets as required. In the absence of such commands, the system stabilizes the spacecraft attitude orientation by reaction jet control.

CONTRACTORS

Guidance and Navigation - MIT Instrumentation Laboratory

Stabilization and Control - Minneapolis-Honeywell

MAJOR CONTRIBUTORS TO UNRELIABILITY

GUIDANCE AND NAVIGATION

The guidance computer and the power and servo assembly are currently considered to be reliability problems, because of their large numbers of component parts and long operating times in the mission. These subsystems are designed for inflight maintenance; studies are in progress to discover whether inflight maintenance is sufficient or whether other alternatives for reliability improvement are indicated.

Based on estimates derived from part counts and current component part failure rates, the computer has a very high over-all failure rate. Since it is activated and in use throughout most of the mission, its reliability estimate is low. However, MIL/IL Report R-410 (May 1963) points out that: (1) part count failure rate estimates on

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Command Module Guidance and Control

similar computers have proved to be at least four times too high; (2) the Apollo computer is in an idle, low-power mode much of the time; (3) the failure rate assumed for the most critical computer components (micrologic gates) is perhaps too high; and (4) the sources of most computer failures to date, the welded-wire junctions, have not been considered. The report concludes that the computer failure rate will probably be much lower than currently estimated by part count analysis.

Certain portions of the power and servo assembly, such as the IMU temperature control electronics and the sextant and telescope electronics, are also required to operate through most or all of the mission. It is not known at this time whether anything less than the entire PSA can be activated. The large number of electronic components and welded wire junctions in the PSA result in a high estimated failure rate. The long operating time results in an inadequate level of reliability, and emphasis is being placed on inflight maintenance (replacement of faulty modules) to maintain performance throughout the mission.

Current estimates of inertial measurement unit failure rates are sufficiently low that, in view of the short duty cycle of this equipment, no reliability problems are presently anticipated.

STABILIZATION AND CONTROL

The SCS must function throughout the mission, in several modes of operation, and is essential to any successful abort in the interest of crew safety. Accordingly, the entire system is designed for inflight maintenance, and studies are underway to ascertain that this concept will yield the extremely high reliability required.

Currently, the flight director attitude indicator, the attitude gyro coupling unit in the auxiliary electronic control assembly, and the various inertial sensors are estimated to have relatively high failure rates. These components are among those being considered for inflight replacement.

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Command Module Guidance and Control

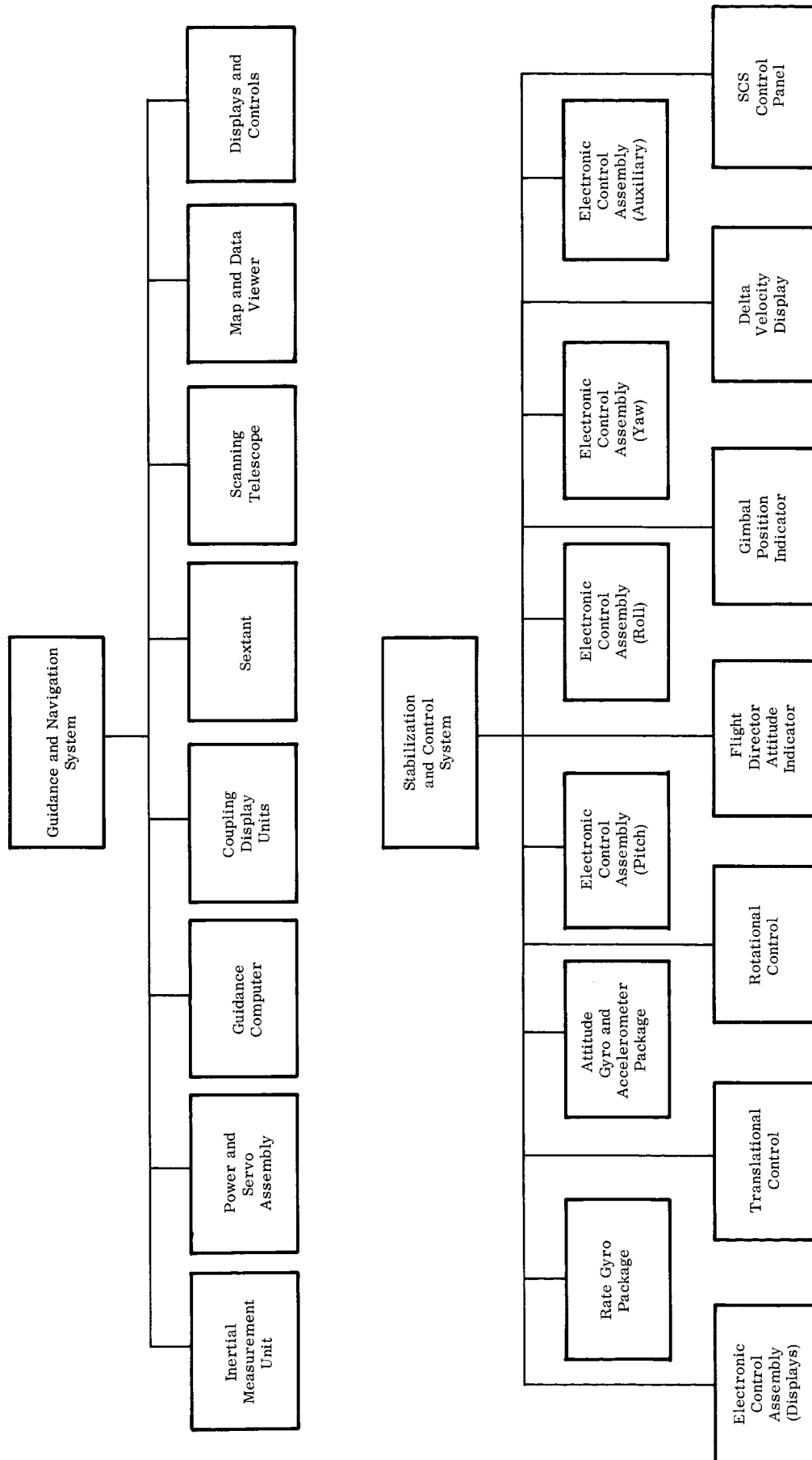


Figure 19-11. Command Module Guidance and Control

Command Module Guidance and Navigation System

RELIABILITY DOCUMENTATION

Functional Subsystem: Guidance and Navigation (CM)

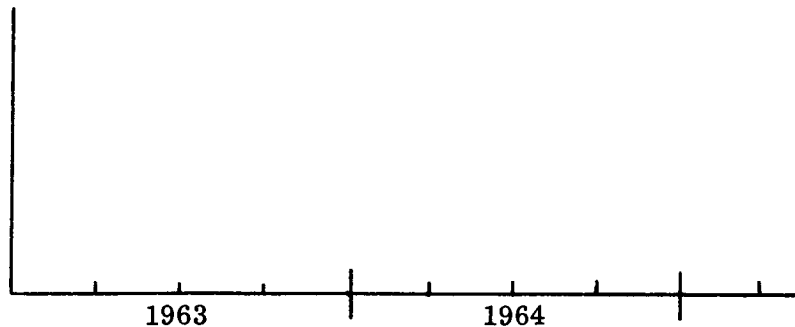
	Center Submittals Received	
	Yes	No
1. Design Specifications	x	
2. Top Drawings	x	
3. Failure Effect Analysis		x
4. Criticality Analysis		x
5. Performance Analysis		x
6. Structural Analysis		Not Applicable
7. Maintainability Plan		x
8. Reliability Apportionments		x
9. Reliability Model		x
10. Quarterly Reliability Reports		x
11. Test Results		x

Notes:

1. Current GNS data derived from several MIL/IL, ACSP, and Raytheon reports acquired from OMSF library. No MIT/IL or industrial subcontractor documentation submitted by centers.
- 2.
- 3.
- 4.

Command Module Guidance and Navigation

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

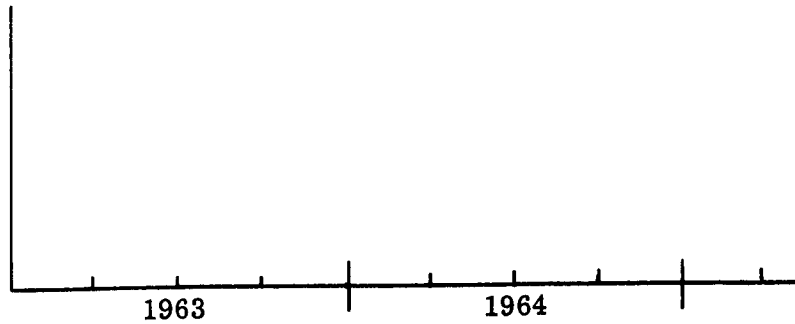
Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Rate Gyro Package		Not Available (1)	0.949804				2
Attitude Gyro and Accelerometer Package			0.917961				3
ECA (Pitch)			0.985210				2
ECA (Roll)			0.985210				2
ECA (Yaw)			0.985210				2
ECA (Aux.)			0.913838				3
ECA (Display)			0.994381				3
Translational Control			0.999999				2
Rotational Control			0.999999				2

Notes:

1. M-H had not allocated reliability to this equipment level as of 20 July 1963.
2. NAA SID 62-557-5.
3. Synthesized from component assembly reliabilities found in SID 62-557-5.
- 4.

Command Module Stabilization and Control System

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY (CONT.)

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Flight Director Attitude Indicator		Not Available	0.701594				2
Gimbal Position Indicator			0.999884				2
Delta Velocity Display			0.999056				2
SCS Control Panel			0.980885				2
Stabilization and Control		0.994558	~ 0.52				

Notes:

1. M-H had not allocated reliability to this equipment level as of 20 July 1963.
2. NAA SID 62-557-5.
3. Synthesized from component assembly reliabilities found in SID 62-557-5.
- 4.

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Command Module Stabilization and Control System

RELIABILITY DOCUMENTATION

Functional Subsystem: Stabilization and Control

	Center Submittals Received	
	Yes	No
1. Design Specifications		x
2. Top Drawings		x
3. Failure Effect Analysis		x
4. Criticality Analysis		x
5. Performance Analysis		x
6. Structural Analysis		Not Applicable
7. Maintainability Plan		x
8. Reliability Apportionments		x
9. Reliability Model		x
10. Quarterly Reliability Reports		x
11. Test Results		x

1. Current SCS data derived from NAA SID 62-557-5 acquired from OMSF library.
No Honeywell or NAA-SCS documentation was submitted by the centers.

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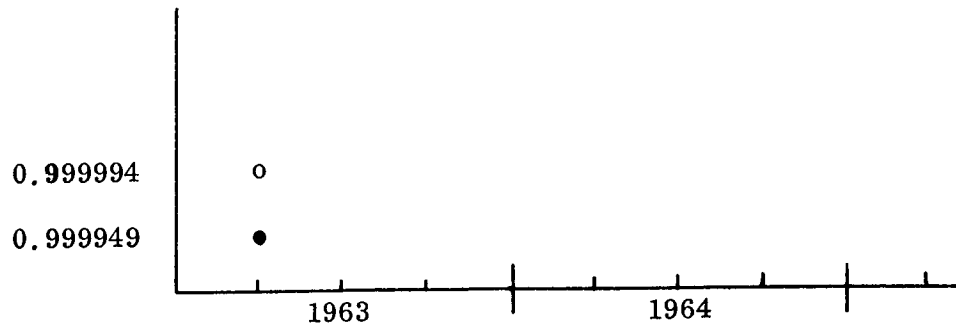
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SECTION 20
LAUNCH ESCAPE SYSTEM

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Launch Escape System Description

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted (1)	Achieved		
Initiator (hot wire squib)		0.999	0.999		3.5	4
Launch escape motor		0.998	0.993			
Pitch control motor		0.999	0.9992			
Tower jettison motor		0.99995	0.9998			
Tower structure		0.99999	0.999999			
Tower separation mechanics (explosive bolts)		0.99999	0.999999			
Total System		0.999949	0.999994			

Notes:

1. Based on state-of-the-art failure rates.
2. Not required for mission success.
3. All data from NAA Document SID 62-557-5.
4. Contributed unreliability is for entire launch escape system; value shown is estimate for illustration only.

SECTION 20

LAUNCH ESCAPE SYSTEM
(CODE: 03 09)DESCRIPTION

The launch escape system is used to provide a means for crew escape during the initial boost phase of the launch vehicle when required by launch vehicle failure. It is attached to the command module and is jettisoned immediately after the second boost phase is entered (the second phase is entered by passing through the region of maximum dynamic pressure of gravity). Successful jettison of the launch escape system is a prerequisite for mission success and its probability is therefore included in the success model. (See Figures 20-1 and 20-2.)

CONTRACTORS

PRINCIPAL CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS

It seems unlikely that reliability apportionments for the solid propellant rockets can be met. All other problems are expected to be solved during debugging operations.

The notable criticality of the problems encountered is not to be underestimated. The problems are, however, ones whose solutions are expected.

Launch Escape System Description

RELIABILITY DOCUMENTATION

Functional Subsystem: Launch Escape System (Code: 03 09)

	Center Submittals Received	
	Yes	No
1. Design Specifications		
2. Top Drawings		
3. Failure Effect Analysis	1	
4. Criticality Analysis		
5. Performance Analysis		
6. Structural Analysis		
7. Maintainability Plan		
8. Reliability Apportionments	1	
9. Reliability Model	1	
10. Quarterly Reliability Reports	1	
11. Test Results		

Notes:

1. Partial information available from NAA 62-557.
- 2.
- 3.
- 4.

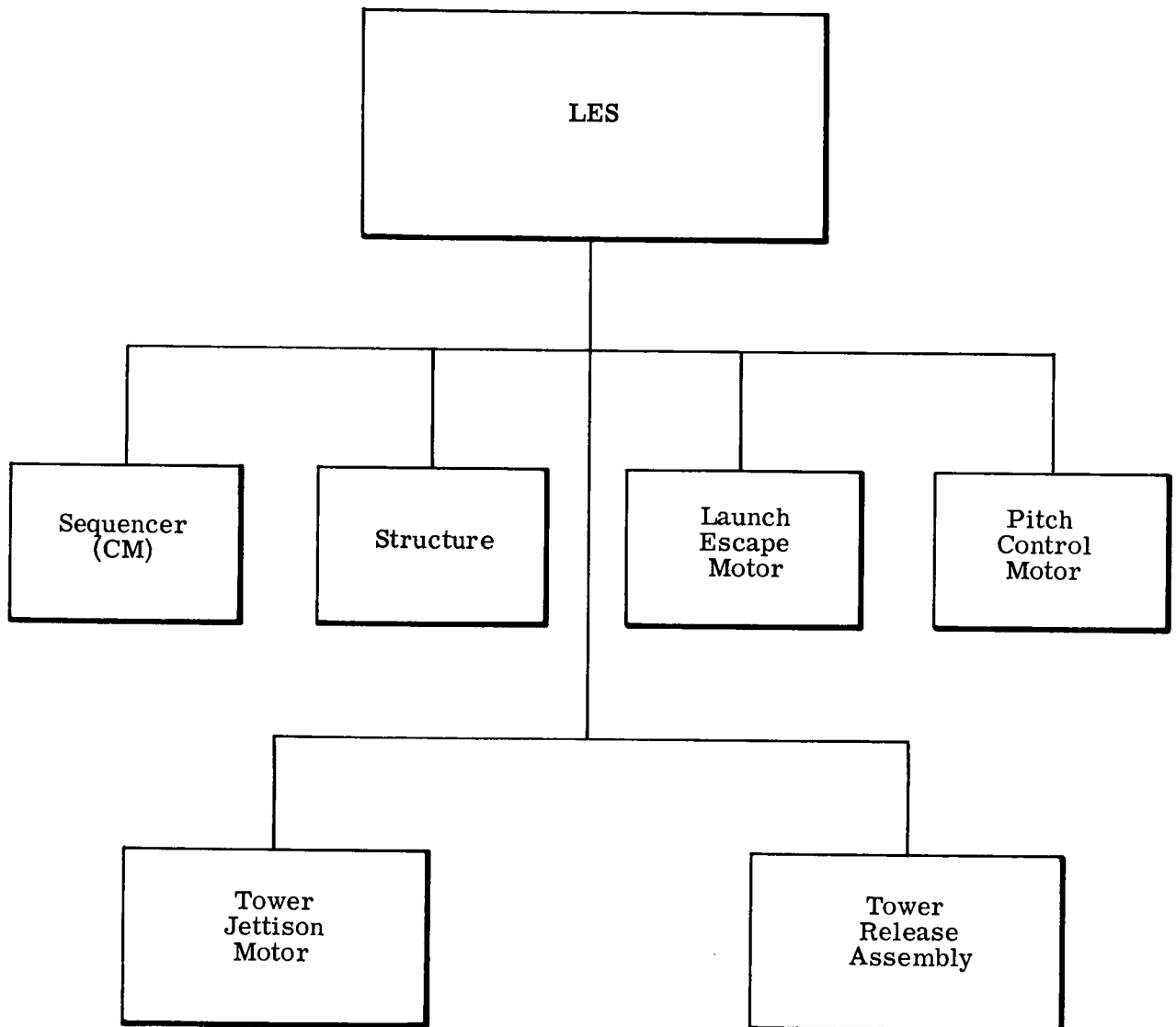


Figure 20-1. Launch Escape System Functional Flow Diagram

Launch Escape System
Description

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Launch Escape System
Description

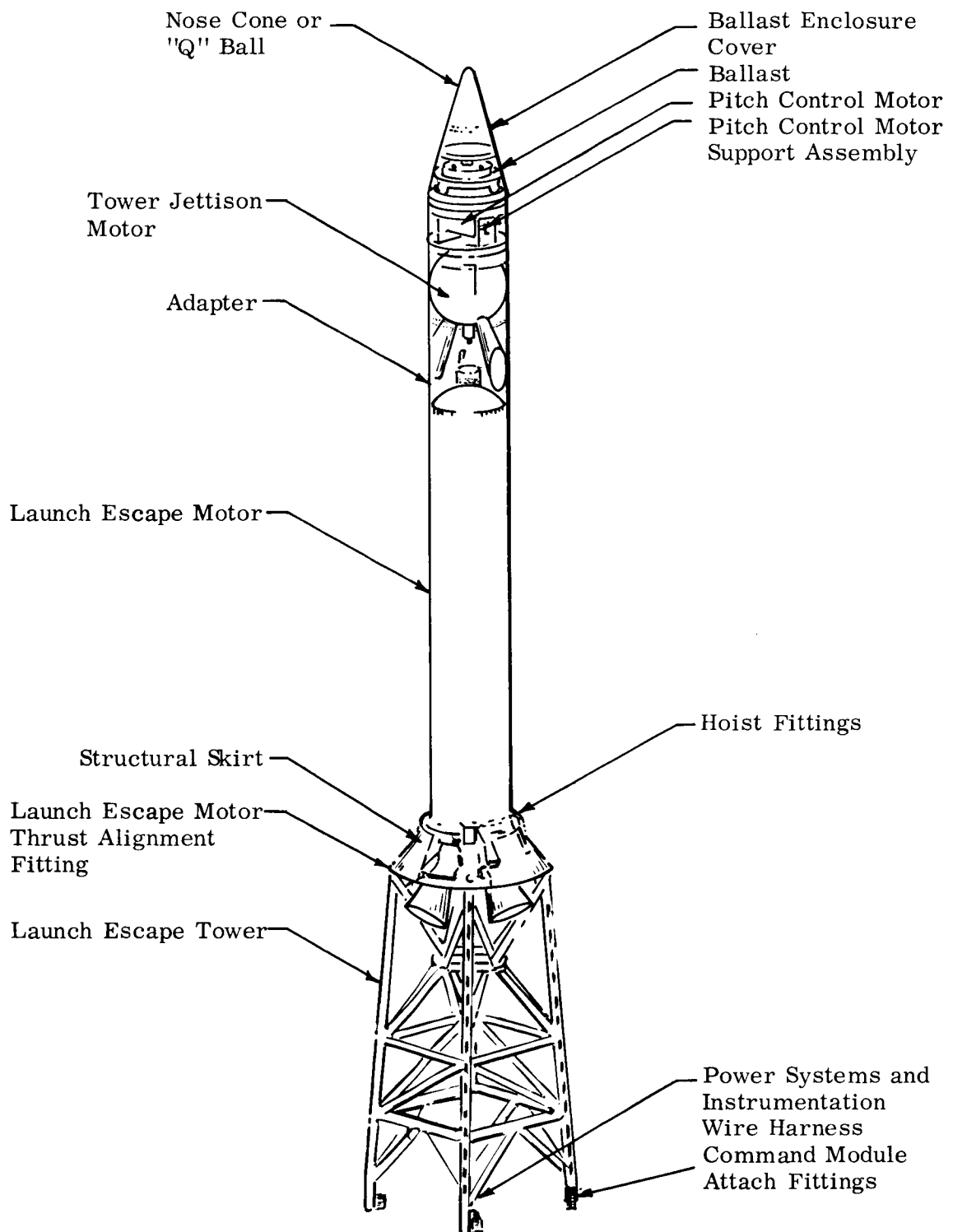


Figure 20-2. Launch Escape System

Launch Escape System Propulsion

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Industry		Notes
		Allocated	Predicted	Achieved	Best	Average	
Engine system	001	0.998	0.993				1
Ignition	051	0.999	0.999				1
Vector Control	021	0.999	0.9992				1
Ordnance	061	0.99999	0.999999				1

Notes:

1. NAA Information.
- 2.
- 3.
- 4.

LAUNCH ESCAPE SYSTEM PROPULSION (CODE: 03 09 01)

FUNCTION

The primary function of the launch escape system is to separate the command module from the launch vehicle in the event of failure or imminent failure. The system will be required to perform the escape function prior to or shortly after liftoff and at maximum dynamic pressure. For normal flights, separation is effected by the main propulsion motor during early operation of the second stage of the launch vehicle.

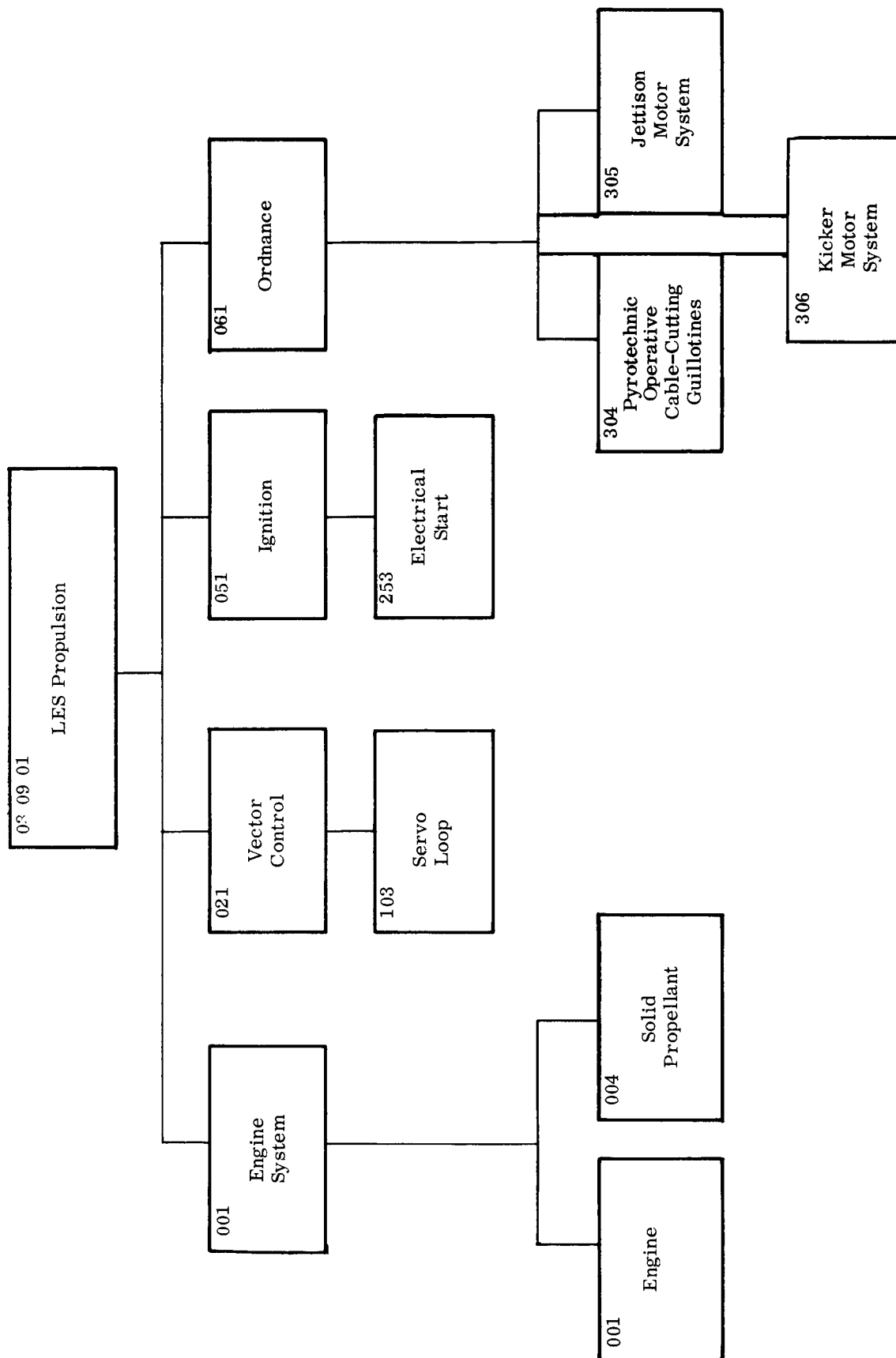
The basic propulsion system is a solid-fuel motor with step, or regressive, burning characteristics. Its nozzles are canted to avoid direct impingement of the exhaust jets on the command module. The launch escape system is jettisoned at approximately maximum altitude after pad escape, or an appropriate time after maximum dynamic pressure escape, and is separated from the command module by a solid-fuel rocket motor.

The thrust-vector control will be an integral part of the launch escape motor. The launch escape system control will provide outputs to activate the service module-command module separation initiator, tower separation mechanism initiator, escape motor ignition, tower jettison motor ignition, thrust-vector control initiator, telemetry signals, and recovery system initiators. Circuitry will be redundant. (See Figure 20-3.)

CONTRACTORS

MAJOR CONTRIBUTORS TO UNRELIABILITY

RELIABILITY TRENDS



RELIABILITY DOCUMENTATION

Functional Subsystem: Launch Escape System Propulsion (Code: 03 09 01)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis (Partial)	May, 1963	
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments	May, 1963	
9. Reliability Model	May, 1963	
10. Quarterly Reliability Reports	May, 1963	
11. Test Results		X

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SECTION 21
GROUND OPERATIONAL SUPPORT SYSTEM

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SECTION 21

GROUND OPERATIONAL SUPPORT SYSTEM
(CODE: 03 10)

DESCRIPTION

Over-all control of all Apollo support elements throughout all phases of a mission will be accomplished from a Mission Control Center (MCC). Mission launch activities up to the time of liftoff will be conducted from a launch control center at Cape Canaveral. In addition to the launch control center, two types of remote stations will be used. The first type of station will provide support for the following communication: voice, telemetry reception and data processing, data transmission from the ground to the spacecraft, tracking to determine spacecraft position and velocity with appropriate data processing and an acquisition system for antenna pointing. The second type of remote station will be equipped for use in tracking the command module during re-entry. These stations will be located both on land and on ships. The remote stations will be connected to the communications and computation centers located in the Mission Control Center by landlines, submarine cables, and/or by radio depending on the location of the remote stations.

Ground Operational Support
System Description

RELIABILITY DOCUMENTATION

Functional Subsystem: Ground Operational Support System (03 10)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Notes:

- 1.
- 2.
- 3.
- 4.

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Ground Operational Support
System Guidance

GROUND OPERATIONAL SUPPORT SYSTEM GUIDANCE (CODE: 03 10 05)

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Ground Operational Support
System Communications

GROUND OPERATIONAL SUPPORT SYSTEM COMMUNICATIONS (CODE: 03 10 06)

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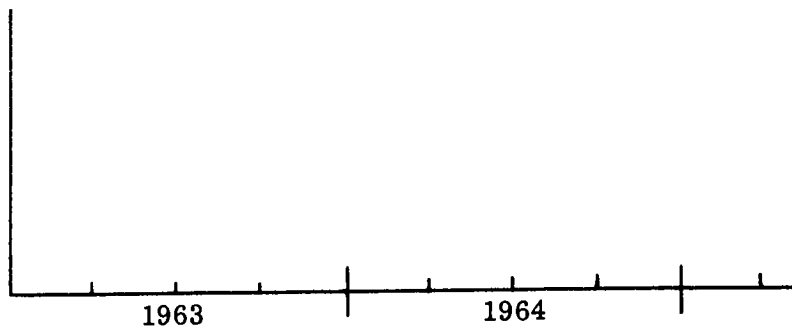
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SECTION 22
GROUND SUPPORT EQUIPMENT

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Ground Support Equipment Description

RELIABILITY: Allocated ● Predicted ○ Achieved x



RELIABILITY

Subsystems	Code	Center Submittal			Percent of Unreliability Contributed	Notes
		Allocated	Predicted	Achieved		
Propulsion	01					
Structure	03					
Electrical Power	02					
Communications	06					
Guidance	05					
Environmental Control	04					

Notes:

- 1.
- 2.
- 3.
- 4.

SECTION 22

GROUND SUPPORT EQUIPMENT
(CODE: 03 11)DESCRIPTION

Spacecraft Ground Support Equipment (GSE) includes all the auxiliary equipment, handling equipment, servicing equipment, training equipment, maintenance equipment, and other GSE required to support all configurations of the Apollo spacecraft. These equipment areas encompass all the devices and equipment required to inspect, test, adjust, calibrate, appraise, gage, measure, repair, overhaul, assemble, disassemble, transport, safeguard, record, store, activate, service, maintain, launch, and otherwise support an end article that is associated with the Apollo spacecraft. (See Figure 22-1.)

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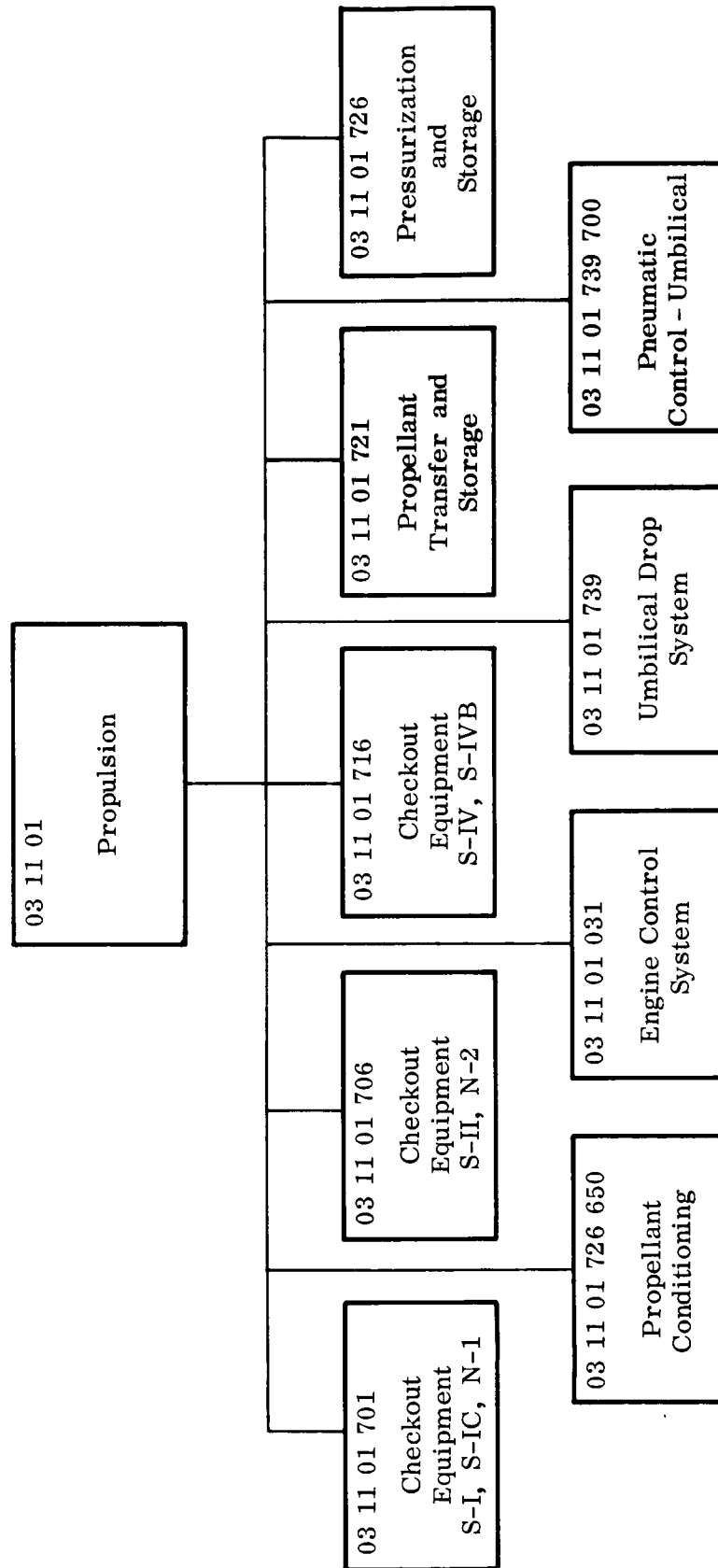


Figure 22-1. Ground Support Equipment Functional Flow Diagram

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Ground Support Equipment
Description

RELIABILITY DOCUMENTATION

Functional Subsystem: Ground Support Equipment (03 11)

	Center Submittals Received	
	Yes	No
1. Design Specifications		X
2. Top Drawings		X
3. Failure Effect Analysis		X
4. Criticality Analysis		X
5. Performance Analysis		X
6. Structural Analysis		X
7. Maintainability Plan		X
8. Reliability Apportionments		X
9. Reliability Model		X
10. Quarterly Reliability Reports		X
11. Test Results		X

Ground Support Equipment
Propulsion

GROUND SUPPORT EQUIPMENT PROPULSION (CODE: 03 11 01)

FUNCTION

Checkout Equipment

The function of the checkout equipment in the propulsion system of the various flights is to provide an interface that is electrically similar to that of the spacecraft in order to provide a complete functional checkout of the spacecraft's propulsion system (see Figure 22-2). The checkout equipment is divided into three general areas; a computer room, a control room, and a terminal facility. The computer room contains the data acquisition and decommutation equipment, a computer complex, data recorders, and ancillary supporting equipment. The control room contains the primary displays and controls. The terminal facility contains a patching network which provides a terminal for all signal inputs to the checkout station.

Propellant Transfer, Pressurization, and Controls

The transfer unit consists of a pump and control system for transferring propellant from ground storage tanks to the spacecraft, and for returning the oxidizer from the spacecraft back to the ground storage tanks. The transfer unit controls and instrumentation are module type and panel mounted.

Umbilical Propulsion System and Pneumatic Controls

The function of the umbilical propulsion system is for use as a coordinated connection pattern for the propulsion service facilities of the spacecraft. The system contains the necessary disconnects in a pattern which mate with the vehicle connection pattern. Fluid disconnects are self sealing.

Contractors

Contributors to Unreliability

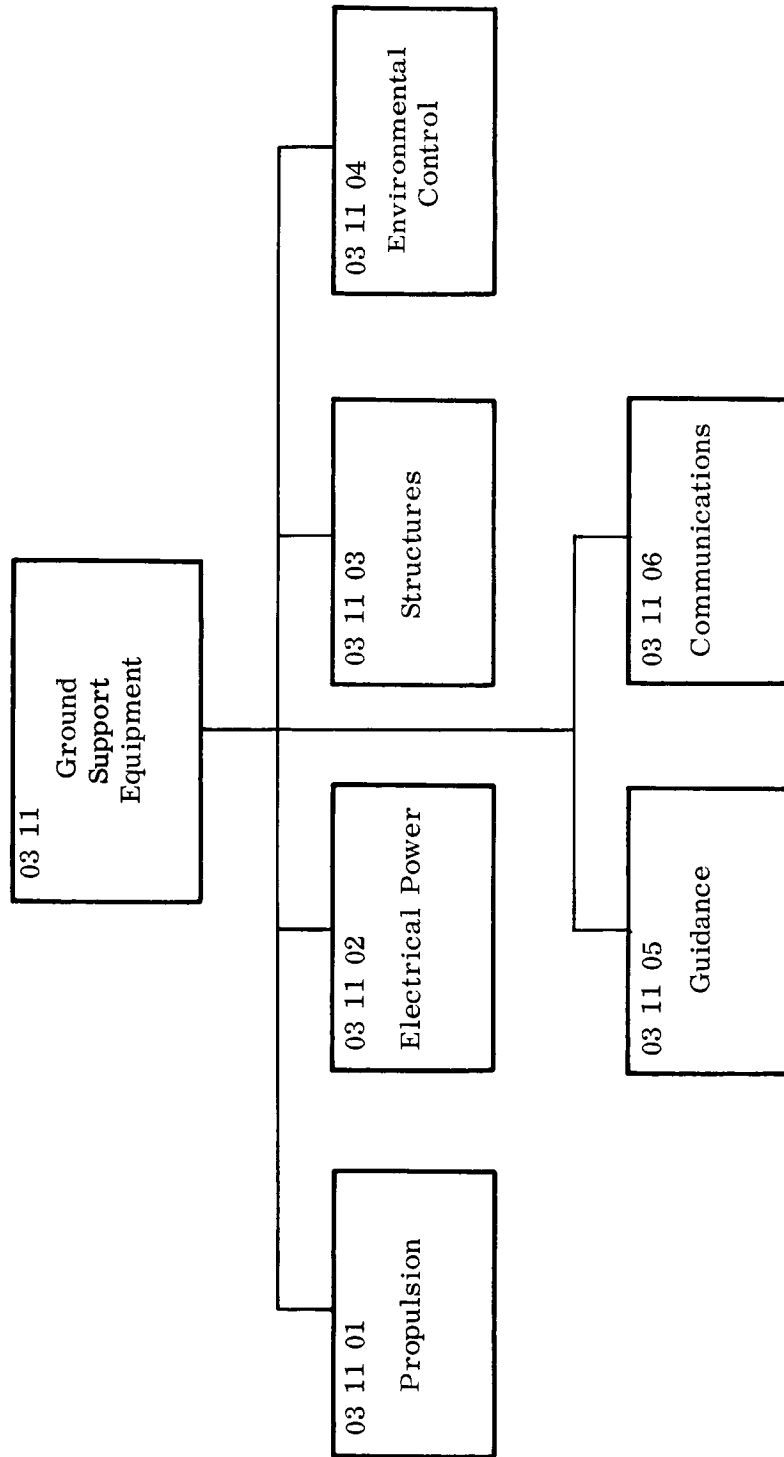


Figure 22-2. Equipment Propulsion System Functional Flow Diagram

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Ground Support Equipment
Electrical Power

GROUND SUPPORT EQUIPMENT ELECTRICAL POWER (CODE 03 11 02)

See Figure 22-3.

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Ground Support Equipment
Electrical Power

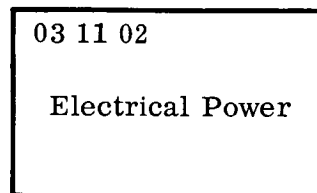


Figure 22-3. Ground Support Equipment Electrical Power Functional Block Diagram

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Ground Support Equipment
Structures

GROUND SUPPORT EQUIPMENT STRUCTURES (CODE: 03 11 03)

See Figure 22-4.

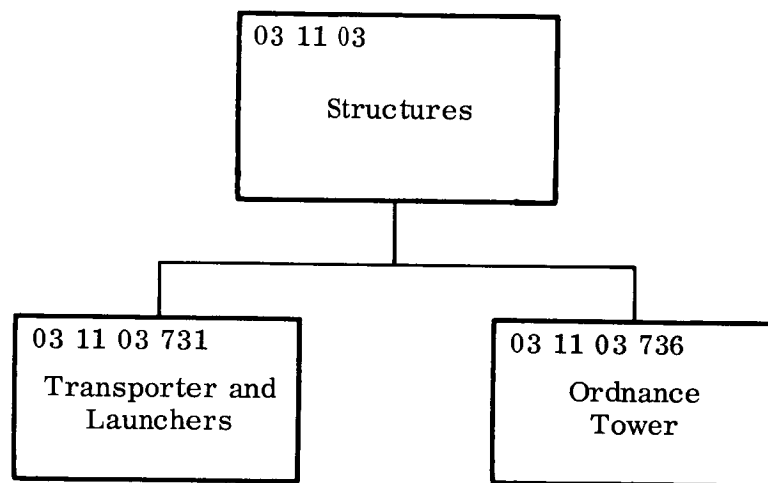


Figure 22-4. Ground Support Equipment Structures Functional Block Diagram

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Ground Support Equipment
Environmental Control

GROUND SUPPORT EQUIPMENT ENVIRONMENTAL CONTROL (CODE: 03 11 04)

See Figure 22-5.

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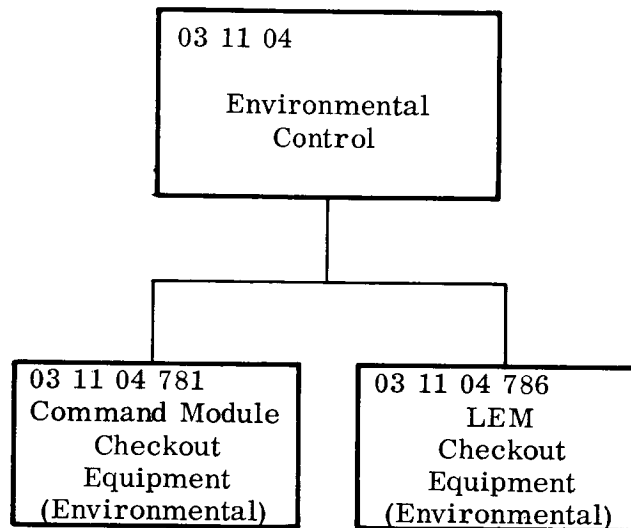


Figure 22-5. Ground Support Equipment Environmental Control
Functional Block Diagram

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Ground Support Equipment
Guidance

GROUND SUPPORT EQUIPMENT GUIDANCE (CODE: 03 11 05)

See Figure 22-6.

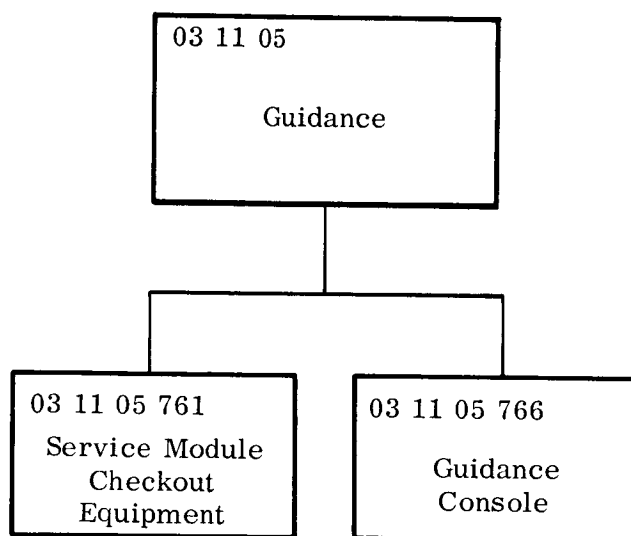


Figure 22-6. Ground Support Equipment Guidance Functional Block Diagram

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Ground Support Equipment
Communications

GROUND SUPPORT EQUIPMENT COMMUNICATIONS (CODE: 03 11 06)

See Figure 22-7.

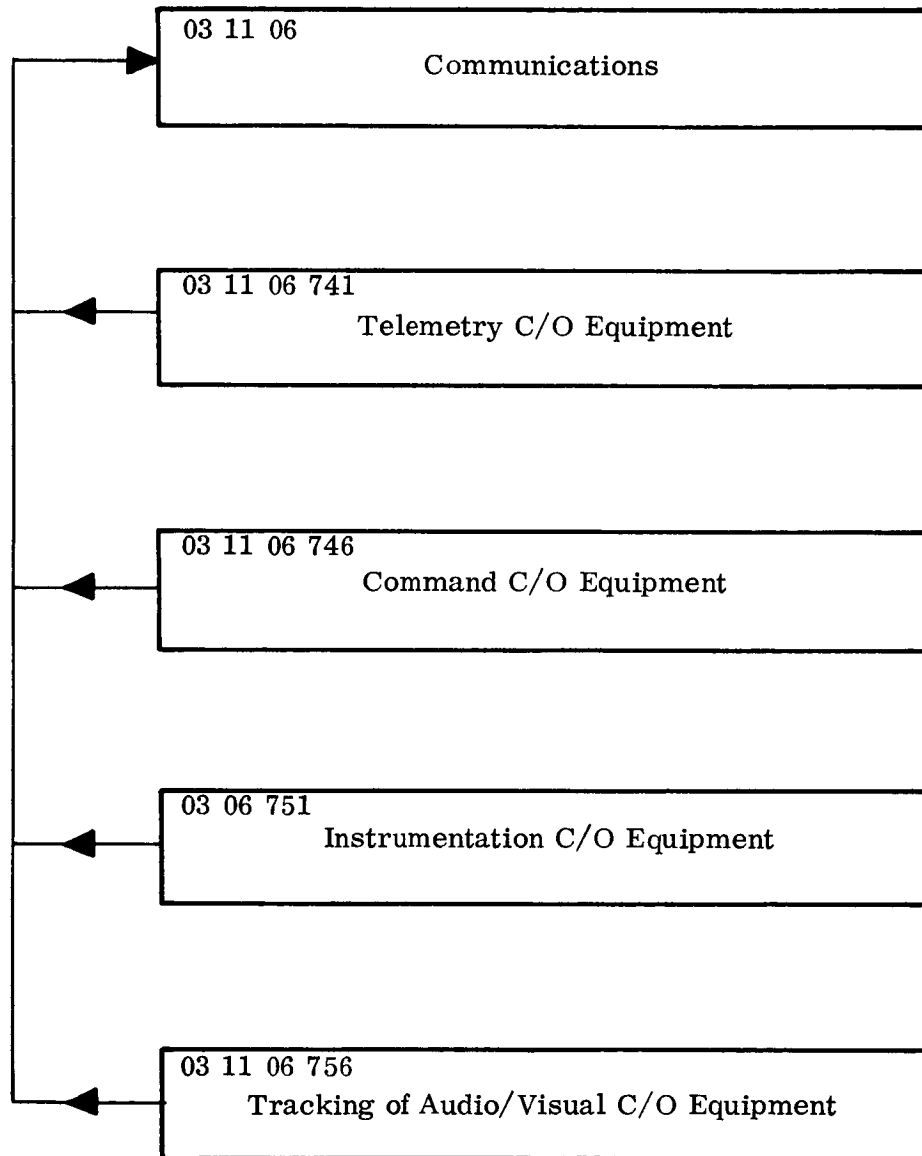


Figure 22-7. Ground Support Equipment Communications Functional Block Diagram